Click here to ask about the production status of specific part numbers.

### MAX17702

## 4.5V to 60V, Synchronous Step-Down Lead-Acid Battery Charger Controller

#### **General Description**

The Himalaya series of voltage regulator ICs, power modules, and chargers enable cooler, smaller, and simpler power supply solutions. The MAX17702 is a high-efficiency, high-voltage, synchronous, step-down, Himalaya leadacid (Pb-acid) battery charger controller designed to operate over an input-voltage range of 4.5V to 60V. The MAX17702 operates over a wide -40°C to +125°C temperature range and offers a complete charging solution for Pb-acid batteries with a ±4% accurate constant-current regulation. The output voltage is programmable from 1.25V up to (V<sub>DCIN</sub> - 2.1V) with ±1% regulation accuracy.

The device uses an external nMOSFET to provide input supply-side short-circuit protection, preventing battery discharge.

The device charges the battery in constant current (CC), absorption constant voltage (CV) states and enters floating CV state after detecting taper current threshold or absorption CV timer timeout in Absorption CV state. Detection and preconditioning of deeply discharged batteries are enabled by a deep discharge detection comparator.

The MAX17702 is available in a 24-pin 4mm x 4mm TQFN package with an exposed pad.

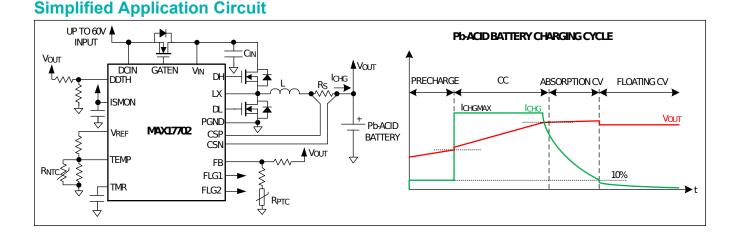
### **Applications**

- Industrial Battery Charging and Energy Storage
- Power Tools
- Battery Backup for Lighting, Security Cameras, and Control Panels
- Portable Industrial Equipment
- Building and Home-Automation Backup Power

#### **Benefits and Features**

- Optimized Feature-Set for Pb-Acid Batteries
  - ±4% Charging Current Regulation Accuracy
  - ±6% Charging Current Monitor Accuracy (ISMON)
  - ±1% Voltage Regulation Accuracy
  - Programmable Constant Current (CC) Mode Charging Current (ILIM)
  - Full-Battery Detection with Taper Current Threshold and Absorption CV Timer (TMR)
  - Wide 4.5V to 60V Input-Voltage Range
  - Adjustable Output-Voltage Range from 1.25V up to (V<sub>DCIN</sub> - 2.1V)
  - 125kHz to 2.2MHz Adjustable Frequency with External Clock Synchronization (RT/SYNC)
- Reliable Operation in Adverse Environmental Conditions
  - Input Short-Circuit Protection (GATEN)
  - Deeply Discharged Battery Detection and Preconditioning (DDTH)
  - Battery Temperature Sensing and Charge when Within Temperature of Range (TEMP)
  - Output Voltage Temperature Compensation
  - Cycle-by-Cycle Overcurrent Limit
  - Programmable EN/UVLO Threshold
  - Status Output Monitoring Using Open-Drain Outputs (FLG1 and FLG2)
  - Overtemperature Protection
  - Wide -40°C to +125°C Ambient Operating Temperature Range/ -40°C to +150°C Junction Temperature Range

Ordering Information appears at end of data sheet.





# 4.5V to 60V, Synchronous Step-Down Lead-Acid Battery Charger Controller

#### **Absolute Maximum Ratings**

V <sub>IN</sub> to SGND/EP0.3V to +65V	BST to PGND0.3V to +70V
DCIN to SGND/EP0.3V to min(+65V, V <sub>IN</sub> + 0.6V)	DL to PGND0.3V to (V <sub>CC</sub> + 0.3V)
GATEN to DCIN	DH to LX0.3V to (BST + 0.3V)
GATEN to SGND/EP max(-0.3V, DCIN - 0.3V) to (DCIN + 6V)	EXTVCC to SGND/EP0.3V to +26V
V <sub>CC</sub> to SGND/EP0.3V to min(+6V, V <sub>IN</sub> + 0.3V)	PGND to SGND/EP0.3V to +0.3V
CSN, CSP to SGND/EP0.3V to (V <sub>IN</sub> + 0.6V)	Continuous Power Dissipation ( $T_A = +70^{\circ}C$ ) (TQFN derate
CSP to CSN0.3V to +0.3V	27.85mW/°C above +70°C)2222mW
V <sub>REF</sub> , TMR, ILIM to SGND/EP0.3V to (V <sub>CC</sub> + 0.3V)	Operating Temperature Range (Note 1)40°C to +125°C
COMP, ISMON, RT/SYNC to SGND/EP0.3V to (V <sub>CC</sub> + 0.3V)	Junction Temperature+150°C
DDTH, FB, TEMP to SGND/EP0.3V to +6V	Storage Temperature Range65°C to +150°C
FLG1, FLG2, EN/UVLO to SGND/EP0.3V to +6V	Lead Temperature (soldering, 10s)+300°C
LX to PGND0.3V to +65V	Soldering Temperature (reflow)+260°C
BST to LX0.3V to +6V	

Note 1: Junction temperature greater than +125°C degrades operating lifetimes.

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

### **Package Information**

#### 24 PIN TQFN

Package Code	T2444+5C
Outline Number	<u>21-100405</u>
Land Pattern Number	<u>90-100139</u>
Thermal Resistance, Four-Layer Board:	
Junction to Ambient ( $\theta_{JA}$ )	36°C/W
Junction to Case ( $\theta_{JC}$ )	3°C/W

For the latest package outline information and land patterns (footprints), go to <u>www.maximintegrated.com/packages</u>. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a four-layer board. For detailed information on package thermal considerations, refer to <u>www.maximintegrated.com/thermal-tutorial</u>.

#### **Electrical Characteristics**

PARAMETER SYMBOL		CONDITIONS	MIN	TYP	MAX	UNITS		
POWER SUPPLY								
DCIN Voltage Range		DCIN connected to V <sub>IN</sub> , External nMOSFET not used	4.5		60	V		
		External nMOSFET used	5.5		60			
V <sub>IN</sub> Voltage Range			4.5		60	V		
Input Quiescent Current	I <sub>QNS</sub>	(V <sub>IN</sub> - V <sub>CSN</sub> ) > 2.1V, V <sub>FB</sub> = 1.5V	1.4	2.1	2.8	mA		
Input Switching Current	I <sub>QS</sub>		1.7	2.5	3.5	mA		
Shutdown Supply Current				7	18	μA		

## 4.5V to 60V, Synchronous Step-Down Lead-Acid Battery Charger Controller

### **Electrical Characteristics (continued)**

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
ENABLE/UVLO (EN/UVL	0)						
EN/UVLO Rising Threshold	V <sub>EN_TH_R</sub>	V <sub>EN/UVLO</sub> rising	1.22	1.25	1.27	V	
EN/UVLO Falling Threshold	V <sub>EN_TH_F</sub>		1.07	1.09	1.11	V	
EN/UVLO Bias Current	I <sub>EN-BIAS</sub>	V <sub>EN/UVLO</sub> = 0.5V	1.4	3.0	6.5	μA	
EN/UVLO True	V <sub>ENT</sub>	V <sub>EN/UVLO</sub> rising	0.4	0.7	1.1	V	
Shutdown Threshold	¥EN1	Hysteresis		60		mV	
V <sub>CC</sub> REGULATORS (INT	LDO AND EXT	-LDO)					
		6V < V <sub>IN</sub> < 60V, I <sub>VCC</sub> = 1mA (V <sub>CC</sub> supplied from INT-LDO)	5.00	5.15	5.30		
V <sub>CC</sub> Output Voltage	V <sub>CC</sub>	$V_{IN}$ = 24V, $I_{VCC}$ = 0mA to 75mA, ( $V_{CC}$ supplied from INT-LDO)	4.95	5.10	5.25	v	
	VCC	$6V < V_{EXTVCC} < 24V$ , $I_{VCC}$ = 1mA ( $V_{CC}$ supplied from EXT-LDO)	5.00	5.15	5.30	V	
		$V_{EXTVCC}$ = 12V, $I_{VCC}$ = 0mA to 75 mA, ( $V_{CC}$ supplied from EXT-LDO)	4.95	5.10	5.25	1	
V <sub>CC</sub> Output-Current Limit	IVCC_LIMIT	$V_{IN}$ = 8.5V, $V_{CC}$ = 4V ( $V_{CC}$ supplied from INT-LDO)	80	110	135		
		V <sub>EXTVCC</sub> = 8.5V, V <sub>CC</sub> = 4V (V <sub>CC</sub> supplied from EXT-LDO)	80	110	135	– mA	
	V <sub>CC-DO</sub>	V <sub>IN</sub> = 4.5V, I <sub>VCC</sub> = 75mA (V <sub>CC</sub> supplied from IN-LDO)		370	750		
V <sub>CC</sub> Dropout Voltage		V <sub>EXTVCC</sub> = 4.9V, I <sub>VCC</sub> = 75mA (V <sub>CC</sub> supplied from EXT-LDO)		185	350	mV	
V <sub>CC</sub> Undervoltage	V <sub>CC-UVR</sub>	V <sub>CC</sub> rising	4.14	4.20	4.26	N	
Threshold	V <sub>CC-UVF</sub>	V <sub>CC</sub> falling	3.74	3.8	3.86	V	
EXTVCC Voltage Range			4.8		24	V	
EXTVCC Switchover		V <sub>EXTVCC</sub> rising	4.63	4.70	4.77	v	
Voltage		Hysteresis		0.24		V	
OSCILLATOR (RT/SYNC	)						
		R <sub>RT/SYNC</sub> = 350 kΩ	118.75	125	131.25		
Switching Frequency	f <sub>SW</sub>	R <sub>RT/SYNC</sub> = unconnected	332.5	350.0	367.5	kHz	
ownoning ricqueriey	1300	$R_{\rm RT/SYNC}$ = 110k $\Omega$	380	400	420		
		R <sub>RT/SYNC</sub> = 19kΩ	2090	2200	2310		
Synchronization Frequency Range	<b>f</b> SYNC		0.9 x f <sub>SW</sub>		1.1 x <sup>f</sup> sw	kHz	
External Clock Amplitude		C <sub>COUPLING</sub> = 10pF	3			V	
SYNC High Pulse Width			100			ns	
SYNC Low Pulse Width			100			ns	

## 4.5V to 60V, Synchronous Step-Down Lead-Acid Battery Charger Controller

### **Electrical Characteristics (continued)**

PARAMETER	SYMBOL	CONE	DITIONS	MIN	TYP	MAX	UNITS	
SYNC Input-Leakage Current	ISYNC_LKG	V <sub>RT/SYNC</sub> = 2.5V, T <sub>A</sub> = +25°C		-100		+100	nA	
GATE DRIVER								
DH to BST On- Resistance		Source 100mA		0.8	1.2	2.1	Ω	
DH to LX On-Resistance		Sink 100mA		0.3	0.6	1.0	Ω	
DL to V <sub>CC</sub> On- Resistance		Source 100mA		0.8	1.2	2.1	Ω	
DL to PGND On- Resistance		Sink 100mA		0.3	0.6	1.0	Ω	
DH Minimum Controlled On-Time	<sup>t</sup> MIN_ON_DH			60	80	100	ns	
DL Minimum Guaranteed On-Time	<sup>t</sup> MIN_ON_DL			60	80	100	ns	
Dead Time	<sup>t</sup> DT_HL	DH falling to DL risir C <sub>DL-PGND</sub> = 6nF	ng, C <sub>DH-LX</sub> = 6nF,		30			
Dead Time	<sup>t</sup> DT_LH	DL falling to DH rising, $C_{DH-LX} = 6nF$ , $C_{DL-PGND} = 6nF$		30			– ns	
	t <sub>HR</sub>	DH rising, C <sub>DH-LX</sub> = 6nF			25		20	
DH Transition Time		DH falling, C <sub>DH-LX</sub> = 6nF		11			ns	
DL Transition Time	t <sub>LR</sub>	DL rising, C <sub>DL-PGND</sub> = 6nF			25			
	t <sub>LF</sub>	DL falling, C <sub>DL-PGN</sub>	<sub>D</sub> = 6nF	11			ns	
REFERENCE VOLTAGE	(V <sub>REF</sub> )							
V <sub>REF</sub> Output Voltage	V <sub>REF</sub>	I <sub>VREF</sub> = 0 to 1mA		2.465	2.500	2.535	V	
Reference Current Limit	IREF_LIM	V <sub>REF</sub> = 2.45V		1.2	1.8	2.7	mA	
CURRENT SENSE (CSP,	CSN, ILIM)							
CSP and CSN Common-Mode Voltage Range				0		(V <sub>IN</sub> - 2)	V	
CSP-to-CSN Input Operating Voltage	V <sub>DIFF_CS</sub>	V <sub>DIFF_CS</sub> = (V <sub>CSP</sub> -	V <sub>CSN</sub> )	-10		100	mV	
		V <sub>ILIM</sub> = 1.5V		48	50	52		
CSP-to-CSN Regulation Voltage Accuracy	V <sub>CSREG</sub>	V <sub>ILIM</sub> = 0.9V		28	30	32	mV	
volage Acculacy		V <sub>ILIM</sub> = V <sub>REF</sub>		48	50	52		
CSP Pin Current		CSP source			200	1400	nA	
		V <sub>EN/UVLO</sub> = 0V, CS	N sink		1.3	2.3		
CSN Pin Current		Charger on, VILIM	I <sub>CHG</sub> > I <sub>TCHG</sub> , CSN source	250	400	550	μA	
		= 0.9V to 1.5V	I <sub>CHG</sub> < I <sub>TCHG</sub> , CSN sink	470	700	1000	1	

## 4.5V to 60V, Synchronous Step-Down Lead-Acid Battery Charger Controller

### **Electrical Characteristics (continued)**

PARAMETER	SYMBOL	CONE	DITIONS	MIN	TYP	MAX	UNITS
Current-Loop Error Amplifier Transconductance	9mi	$(V_{CSP} - V_{CSN}) = V_C$	$(V_{CSP} - V_{CSN}) = V_{CSREG} \pm 25mV$		480	685	μS
ILIM Input Leakage Current		V <sub>ILIM</sub> = 1.5V, T <sub>A</sub> = +25°C		-100		100	nA
CSN Undervoltage	Marwara	(V <sub>IN</sub> - V <sub>CSN</sub> ), rising		1.97	2.04	2.10	- v
Lockout Threshold	V <sub>CMUVLO</sub>	(V <sub>IN</sub> - V <sub>CSN</sub> ), falling		1.88	1.95	2.02	v
Overcurrent Threshold	V <sub>CS_PEAK</sub>	V <sub>CS_PEAK</sub> = (V <sub>CSP</sub> 1.5V	- V <sub>CSN</sub> ), V <sub>ILIM</sub> =	70	75	80	mV
		Hysteresis			10		
Zero-Cross Threshold	V <sub>ZX</sub>	(V <sub>CSP</sub> - V <sub>CSN</sub> ) fallin	g		-1.7		mV
PWM-Ramp Amplitude	V <sub>RAMP</sub>	f <sub>SW</sub> = 125kHz to 2.2	MHz	1.37	1.44	1.51	V
VOLTAGE REGULATION	AMPLIFIER (F	B)					1
FB Reference Voltage	V <sub>FB_REG</sub>			1.237	1.250	1.263	V
FB Input-Leakage Current		V <sub>FB</sub> = 1.3V, T <sub>A</sub> = +2	5°C	-100		100	nA
Voltage-Loop-Error Amplifier Gain	G <sub>V</sub>			1.15	1.30	1.42	mV/mV
FB to SGND/EP Short Fault Threshold	V <sub>FBGND</sub>	V <sub>FB</sub> < V <sub>FBGND</sub>		57	65	73	mV
INPUT SHORT-CIRCUIT	PROTECTION (	GATEN)		•			
External nMOSFET Gate Drive Voltage	(V <sub>GATEN</sub> - V <sub>DCIN</sub> )			4.65	5.00	5.50	V
GATEN Drive Current	IGATEN			17	20	23	μA
GATEN Active Pulldown Resistance	R <sub>GATEN_</sub> A	I <sub>GATEN</sub> = 100mA			1.1	2.1	Ω
GATEN Passive Pulldown Resistance	R <sub>GATEN_P</sub>	V <sub>EN/UVLO</sub> = 0V			400	800	Ω
GATEN-DCIN Threshold	V <sub>GATEN_</sub> OK			3.20	3.55	3.90	V
GATEN OK Delay	tGATEN_OK				15		ms
External nMOSFET		(V <sub>DCIN</sub> - V <sub>IN</sub> ) falling		-111	-93	-75	
Reverse Blocking Threshold	V <sub>REV</sub>	Hysteresis			20		mV
External nMOSFET Reverse Blocking Response Time		C <sub>GATEN-DCIN</sub> = 10nF, V <sub>DCIN</sub> < (V <sub>IN</sub> - 93mV) to (V <sub>GATEN</sub> -V <sub>DCIN</sub> ) < 2V			100	180	ns
V <sub>IN</sub> to DCIN Reverse Leakage Current		V <sub>DCIN</sub> = 0V, V <sub>IN</sub> = 60V	V <sub>EN/UVLO</sub> = 0V		170 230	260 350	μA
CHARGER FUNCTIONS		1	1	1			1
Absorption/Floating		V <sub>ILIM</sub> = 1.5V, V <sub>FB</sub> ri	sing	97.15	97.50	97.85	% of
Constant-Voltage (CV) Mode FB Threshold	V <sub>FB_CV</sub>	Hysteresis			0.3		V <sub>FB_REG</sub>

## 4.5V to 60V, Synchronous Step-Down Lead-Acid Battery Charger Controller

### **Electrical Characteristics (continued)**

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS	
Deep-Discharge		V <sub>DDTH</sub> rising		1.245	1.260	1.275		
Comparator Threshold (DDTH)	V <sub>DDREF</sub>	V <sub>DDTH</sub> falling		1.235	1.250	1.265		
Precharge State CSP-			V <sub>ILIM</sub> = 1.5V	2.5	5	7.5		
to-CSN Regulation Voltage Accuracy	VCSPCHG	V <sub>DDTH</sub> = 1.1V	V <sub>ILIM</sub> = 0.9V	0.5	3	5.5	mV	
Taper Current Threshold	ITCHG	Current falling (see	e Note 3)	4.8	10	16.8	% of I <sub>CHGMAX</sub>	
ISMON Output-Voltage		$(V_{CSP} - V_{CSN}) = 5$	0mV	1.41	1.50	1.59	- v	
Accuracy		$(V_{CSP} - V_{CSN}) = 3$	0mV	0.825	0.900	0.975		
ISMON Output Resistance					90		kΩ	
ISMON Output Bandwidth					100		kHz	
CHARGER TIMER (TMR)								
Charger Startup Delay	<b>+</b>	C <sub>TMR</sub> = 220nF			55			
Charger Startup Delay	<sup>t</sup> CH_START	TMR disabled	TMR disabled		54		— ms	
TMR-Oscillator Upper Threshold	V <sub>TMR_H</sub>		1.47	1.50	1.53	V		
TMR-Oscillator Lower Threshold	V <sub>TMR_L</sub>			0.94	0.96	0.98	V	
TMR Source/Sink Current	I <sub>TMR</sub>			8.9	10	10.9	μA	
TMR Disable Threshold	V <sub>TMR_DIS</sub>	V <sub>TMR</sub> > V <sub>TMR_DIS</sub>	(power-up check only)	1.9	2.0	2.1	V	
TMR Short-to-SGND/EP Fault Threshold	V <sub>TMR_GND</sub>	V <sub>TMR</sub> < V <sub>TMR_GN</sub> only)	D (power-up check	80	100	120	mV	
Absorption CV Timer Timeout	t <sub>FCHG</sub>				2097151		TMR CYCLES	
Precharge Timer Timeout	<sup>t</sup> PCHG				262143		TMR CYCLES	
BATTERY TEMPERATUR	RE SENSE (TEN	ÍΡ)					•	
TEMD Lippor Throubald	\/	Battery temperatur	e falling	59.4	60	60.6	% of	
TEMP Upper Threshold	V <sub>TEMPU</sub>	Hysteresis			1		V <sub>REF</sub>	
TEMP Lower Threshold	V	Battery temperatur	e rising	27.3	28	28.5	% of	
	V <sub>TEMPL</sub>	Hysteresis			1.2		V <sub>REF</sub>	
CHARGER STATUS OUT	PUTS (FLG1, F	LG2)						
FLG1/FLG2 Pulldown Voltage		I <sub>FLG1</sub> , I <sub>FLG2</sub> = 10mA				500	mV	
FLG1/FLG2 Leakage Current		V <sub>FLG1</sub> , V <sub>FLG2</sub> = 5	-100		+100	nA		

## 4.5V to 60V, Synchronous Step-Down Lead-Acid Battery Charger Controller

#### **Electrical Characteristics (continued)**

 $(V_{IN} = V_{DCIN} = 24V, C_{VIN} = 4.7\mu$ F,  $C_{DCIN} = 100$ nF,  $C_{VCC} = 4.7\mu$ F,  $C_{VREF} = 100$ nF,  $C_{BST} = 470$ nF,  $V_{BST}$  to  $V_{LX} = 5V$ ,  $V_{EN/UVLO} = V_{LX} = V_{ILIM} = V_{CSN} = V_{CSP} = V_{DDTH} = V_{TMR} = 2.5V$ ,  $V_{TEMP} = V_{FB} = 1.1V$ ,  $V_{EXTVCC} = V_{SGND/EP} = V_{PGND} = 0V$ , RT/SYNC = DH = DL = GATEN = COMP = FLG1 = FLG2 = ISMON = Unconnected,  $T_A = -40^{\circ}$ C to  $+125^{\circ}$ C, unless otherwise noted. Typical values are at  $T_A = +25^{\circ}$ C. All voltages are referenced to SGND/EP, unless otherwise noted.) (Note 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
IC THERMAL PROTECTION						
Thermal Shutdown Threshold		Temperature rising		160		°C
Thermal Shutdown Hysteresis				10		°C

Note 2: Electrical specifications are production tested at T<sub>A</sub> = +25°C. Specifications over the entire operating temperature range are guaranteed by design and characterization.

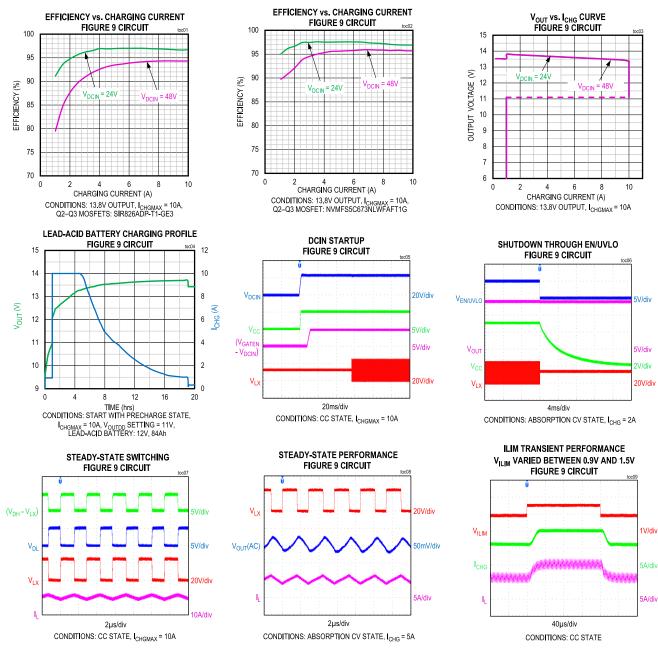
Note 3: CC mode charging current setting is calculated using the following equation

 $I_{\text{CHGMAX}} = \frac{V_{\text{CSREG}}}{R_{\text{S}}}$ , where R<sub>S</sub> is the current-sense resistor.

# 4.5V to 60V, Synchronous Step-Down Lead-Acid Battery Charger Controller

### **Typical Operating Characteristics**

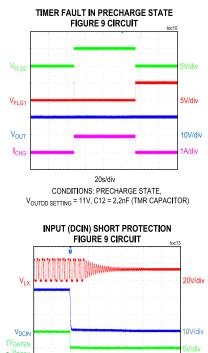
 $(V_{DCIN} = 24V, V_{SGND/EP} = V_{PGND} = 0V, RT/SYNC = unconnected (f_{SW} = 350kHz), T_A = +25^{\circ}C$ , unless otherwise noted. All voltages are referenced to SGND/EP, unless otherwise noted.)



# 4.5V to 60V, Synchronous Step-Down Lead-Acid Battery Charger Controller

### **Typical Operating Characteristics (continued)**

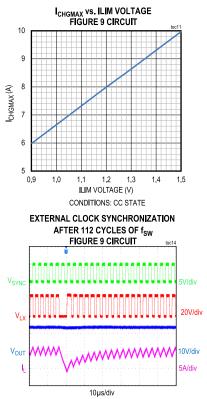
 $(V_{DCIN} = 24V, V_{SGND/EP} = V_{PGND} = 0V, RT/SYNC = unconnected (f_{SW} = 350kHz), T_A = +25^{\circ}C$ , unless otherwise noted. All voltages are referenced to SGND/EP, unless otherwise noted.)





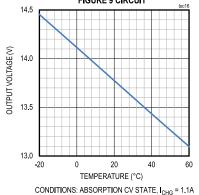
10V/div

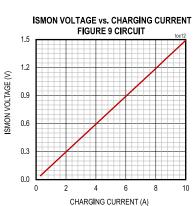
VOUT

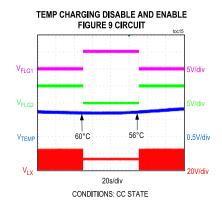


 $\label{eq:conditions:13.8V} \begin{array}{l} \text{TopSulv} \\ \text{CONDITIONS: 13.8V} \text{ OUTPUT, ABSORPTION CV STATE,} \\ \textbf{I}_{CHG} = 5A, \textbf{I}_{CHGMAX} = 10A, \textbf{f}_{SW} = 350 \text{kHz}, \textbf{f}_{SYNC} = 315 \text{kHz} \end{array}$ 





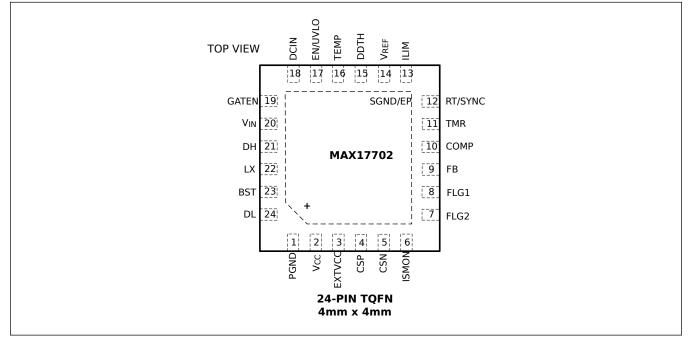




# 4.5V to 60V, Synchronous Step-Down Lead-Acid Battery Charger Controller

### **Pin Configuration**

#### MAX17702



### **Pin Description**

PIN	NAME	FUNCTION
1	PGND	Power Ground. Connect to the return terminal of a $V_{CC}$ bypass capacitor placed close to the IC and the source terminal of the external low-side nMOSFET. Refer to the MAX17702 evaluation kit data sheet for the PCB layout example.
2	V <sub>CC</sub>	Internal LDO Output. Connect a minimum of 4.7 $\mu$ F/0805, low-ESR ceramic capacitor between V <sub>CC</sub> and PGND. V <sub>CC</sub> supports IC internal-control circuitry and gate-drive current for external nMOSFETs.
3	EXTVCC	External Power-Supply Input for EXT-LDO. To power internal circuitry from an external supply, apply a voltage between 4.8V and 24V to the EXTVCC pin. Connect a minimum of $1\mu$ F/0603, low-ESR ceramic capacitor between EXTVCC and SGND/EP. Leave EXTVCC open when not used.
4	CSP	Inverting Input of the Current-Loop Error Amplifier. The CSP and CSN pins measure the voltage across the current sense resistor $R_S$ (see Figure 5).
5	CSN	Non-Inverting Input of the Current-Loop Error Amplifier. Connect CSN to the node connecting the output capacitor and current sense resistor $R_S$ . Use Kelvin connections and route the CSP and CSN traces as a differential pair (see Figure 5).
6	ISMON	Output of Charging Current Monitor. Bypass ISMON with a 1nF low-ESR ceramic capacitor to SGND/EP. The voltage on this pin is 30 times the voltage drop across the current-sense resistor ( $R_S$ ).
7, 8	FLG2, FLG1	Open-Drain Status Output Pins. Connect one $10k\Omega$ pullup resistor each from V <sub>CC</sub> to FLG1 and FLG2. See the <u>Charger Status Outputs (FLG1, FLG2)</u> section for more details.
9	FB	Feedback Input. Connect FB to the center node of a resistor-divider from the positive terminal of the battery to SGND/EP to set the output voltage and temperature compensation. See the <u>Setting</u> <u>Output Voltage and Temperature Compensation (FB)</u> section for more details.

# 4.5V to 60V, Synchronous Step-Down Lead-Acid Battery Charger Controller

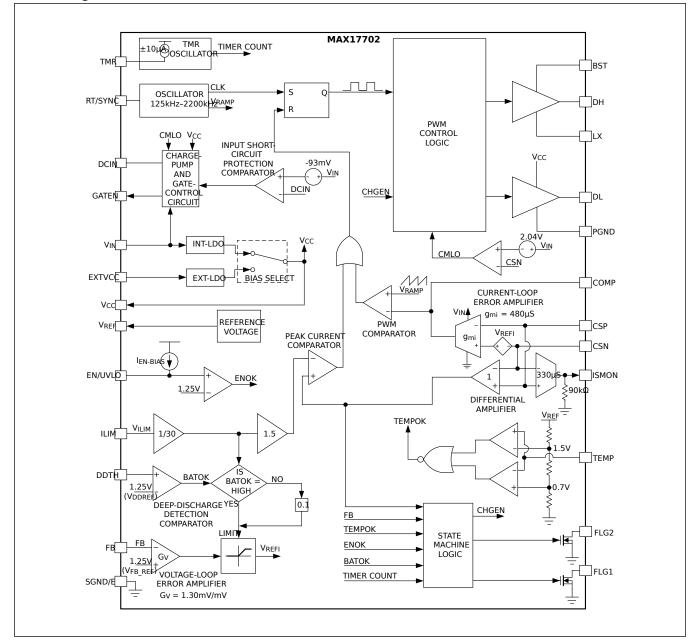
# **Pin Description (continued)**

PIN	NAME	FUNCTION
10	COMP	Current Loop Error Amplifier Output. Connect a compensation network at this pin to stabilize the inner current loop. See the <u>Current Regulation Loop Compensation (COMP)</u> section for more details.
11	TMR	Timer Setting Pin. A capacitor from TMR to SGND/EP sets the charging time in absorption CV, precharge states. Place the timer capacitor close to the TMR pin. Connect TMR to $V_{REF}$ to disable the timer function. See the <u>Charger Timers (TMR)</u> section for more details.
12	RT/SYNC	Switching Frequency Programming/Synchronization Input. Connect a resistor from RT/SYNC to SGND/EP to set the switching frequency between 125kHz to 2.2MHz. Leave RT/SYNC open for the default 350kHz frequency. See the <u>Setting the Switching Frequency and External Clock</u> <u>Synchronization (RT/SYNC)</u> section for more details.
13	ILIM	CC Mode Charging Current Programming Input. Connect ILIM to the center node of a resistor divider between V <sub>REF</sub> and SGND/EP to set the CC mode charging current. Connect to V <sub>REF</sub> for the default CC mode charging current setting. See the <u>CC Mode Charging Current Setting (ILIM)</u> section for more details.
14	V <sub>REF</sub>	2.5V Reference Output. Bypass $V_{REF}$ with a 0.1µF low-ESR ceramic capacitor to SGND/EP. See the <u>Reference Voltage (V_{REF})</u> section for more details.
15	DDTH	Battery Deep-Discharge Detection Input. Connect DDTH to the center node of a resistor divider from the output-voltage node to SGND/EP. If V <sub>DDTH</sub> falls below V <sub>DDREF</sub> , the charger enters the precharge state for battery preconditioning. See the <u>Setting Battery Deep-Discharge Voltage Level</u> (DDTH) and <u>Power-Up/Down Sequence and Charger Operation</u> sections for more details.
16	TEMP	Battery Temperature Input. Connect TEMP to the center node of a resistor divider from V <sub>REF</sub> to SGND/EP. Connect the battery temperature sensing NTC resistor terminals across the bottom resistor of the divider to program the battery charging temperature window. See the <u>Setting Battery</u> <u>Operating Temperature Range (TEMP)</u> section for more details.
17	EN/UVLO	Enable/Undervoltage Lockout Input. Connect to the center node of a resistor divider between DCIN and SGND/EP to set the input voltage at which the device turns on. Connect to SGND/EP to shutdown the device. See the <u>Setting the Input Undervoltage-Lockout Level (EN/UVLO)</u> section for more details.
18	DCIN	Input-Supply-Voltage Sense Pin. Bypass DCIN with a $0.1\mu$ F ceramic capacitor to PGND. Refer to the MAX17702 EV kit data sheet for the recommended PCB layout and routing.
19	GATEN	Gate Drive Output for External nMOSFET. Bypass GATEN with a 2.2nF low-ESR ceramic capacitor to DCIN. GATEN controls the gate of an external nMOSFET connected between DCIN and $V_{IN}$ to prevent battery discharge when DCIN is shorted to PGND. See the <u>Input Short Circuit</u> <u>Protection (GATEN)</u> section for more details.
20	V <sub>IN</sub>	MAX17702 IC-Supply Pin. Bypass V <sub>IN</sub> to PGND with a 0.1 $\mu$ F ceramic capacitor. Refer to the MAX17702 EV kit data sheet for the recommended PCB layout and routing.
21	DH	High-Side nMOSFET Gate Driver Output. Connect to the gate of the high-side nMOSFET.
22	LX	Switching Node Connection Input. Connect to the switching node of the converter.
23	BST	Bootstrap Capacitor Connection Input. Connect a capacitor of $0.1\mu$ F (min) between the BST and LX pins. Connect a Schottky diode from the V <sub>CC</sub> to the BST pin. See the <u>Bootstrap Capacitor</u> <u>Selection</u> and <u>Bootstrap Diode Selection</u> sections for more details.
24	DL	Low-Side nMOSFET Gate Driver Output. Connect to the gate of the low-side nMOSFET.
-	SGND/EP	Signal Ground, Exposed Pad. Refer to the MAX17702 EV kit data sheet for the recommended method of PCB layout, routing, and thermal vias.

# 4.5V to 60V, Synchronous Step-Down Lead-Acid Battery Charger Controller

### **Functional Diagrams**

#### Block Diagram



## 4.5V to 60V, Synchronous Step-Down Lead-Acid Battery Charger Controller

#### **Detailed Description**

The MAX17702 is a 4.5V to 60V wide input, synchronous, step-down Pb-acid battery-charger controller designed to operate over a -40°C to +125°C temperature range. It offers a complete battery charge cycle solution for Pb-acid batteries. Charging begins in one of the three states, namely, precharge, constant current (CC), and absorption constant voltage (CV) state depending on the battery voltage. The charger enters floating CV state after detecting taper current threshold ( $I_{TCHG}$ ) or absorption CV timer timeout in absorption CV state. The charger continues to regulate the output voltage at the floating voltage level of the battery in floating CV state. The PTC resistor ( $R_{PTC}$ ) in the output-voltage feedback resistor-divider circuit provides the temperature compensation for the Pb-acid battery charging voltage. The device provides an input short-circuit protection, and prevents battery discharging for input supply-side short-circuit events by means of an external nMOSFET. The MAX17702 offers up to  $\pm$ 4% accurate constant charging current in CC mode and regulates the no-load output voltage with  $\pm$ 1% accuracy. The MAX17702 supports a wide adjustable output-voltage range of 1.25V to ( $V_{DCIN}$  - 2.1V).

The MAX17702 features a constant frequency, average current-mode control architecture shown in <u>Figure 1</u>. An internal current loop consists of a transconductance amplifier ( $g_{mi}$ ) that senses the inductor current flowing through current-sense resistor ( $R_S$ ) as a voltage drop across the CSP and CSN pins. The current-sense voltage is compared with a current-loop reference voltage ( $V_{REFI}$ ), which is set by the outer voltage-loop-error amplifier ( $G_V$ ) and limited by the voltage programmed at the ILIM pin ( $V_{ILIM}$ ). The voltage at the COMP pin is compared with a 1.44V (typ) ramp using a PWM comparator to set the duty cycle of the converter. The required compensation to stabilize the current loop is applied at the COMP pin using  $R_Z$ ,  $C_Z$ , and  $C_P$ . Under steady-state conditions, the inner current loop forces the voltage drop across  $R_S$  equal to  $V_{REFI}$ .

The output voltage is monitored by the voltage error amplifier  $G_V$  with a resistor divider (R<sub>FB1</sub>, R<sub>FB2</sub>, R<sub>PTC</sub>, and R<sub>ABS</sub>) connected across the positive and negative battery terminals with the center node connected to the FB pin. The voltage at the FB pin is compared with the FB reference voltage (V<sub>FB REG</sub>). The voltage-loop-error amplifier sets the current

loop reference voltage (V<sub>REFI</sub>). V<sub>REFI</sub> is limited to  $\frac{V_{\text{ILIM}}}{30}$  till  $V_{\text{FB}} \leq \left[V_{\text{FB}_{\text{REG}}} - \frac{V_{\text{ILIM}}}{30 \times G_V}\right]$ . This results in a constant current

through R<sub>S</sub>. When the output voltage rises such that,  $V_{FB} > \left[V_{FB\_REG} - \frac{V_{ILIM}}{30 \times G_V}\right]$ ,  $V_{REFI}$ , and hence, the charging current

 $(I_{CHG})$  proportionately reduces. The charging current for a given output voltage  $(V_{OUT\_SS})$  in absorption CV state is given by the following equation:

$$I_{\text{CHG}} = \left( V_{\text{FB}_{\text{REG}}} - V_{\text{OUT}_{\text{SS}}} \times \left( \frac{\left( R_{\text{FB2}} + R_{\text{PTC}} \right) \times R_{\text{ABS}}}{\left( \left( R_{\text{FB1}} + R_{\text{FB2}} + R_{\text{PTC}} \right) \times R_{\text{ABS}} + \left( R_{\text{FB2}} + R_{\text{PTC}} \right) \times R_{\text{FB1}}} \right) \right) \times \frac{G_V}{R_S}$$

where,

 $V_{FB REG}$  = FB reference voltage

V<sub>OUT SS</sub> = Output voltage in absorption CV state

I<sub>CHG</sub> = Charging current of the charger for a given output voltage

RFB1, RFB2, RPTC, and RABS = Output voltage feedback voltage-divider resistors

 $G_V$  = Voltage loop error amplifier gain (1.30mV/mV)

Deeply discharged batteries can be detected by using the deep-discharge detection comparator with a resistor divider ( $R_{DDT}$  or  $R_{DDB}$ ) connected across the positive and negative battery terminals with the center node connected to the DDTH pin. When  $V_{DDTH} < 1.25V$  ( $V_{DDREF}$ ), the battery is considered to be deeply discharged and the charger enters

precharge state to revive the deeply discharged battery. In precharge state,  $V_{REFI}$  is limited to  $\frac{V_{ILIM}}{300}$  to limit the charging current to 10% of the CC mode charging current. The charger timer (TMR) sets the maximum allowed charging time in precharge and absorption CV states to improve system safety.

An NTC-sense resistor can be used with MAX17702 to sense battery temperature (TEMP) and charge only within the allowed battery temperature range. The switching frequency of the device can be programmed from 125kHz to

# 4.5V to 60V, Synchronous Step-Down Lead-Acid Battery Charger Controller

2.2MHz using a resistor at the RT/SYNC pin. RT/SYNC also provides an external clock synchronization feature. Input undervoltage lockout is implemented using the EN/UVLO pin. Two open-drain status outputs (FLG1 and FLG2) indicate the battery charger status. And, the charging current can be monitored using the ISMON pin.

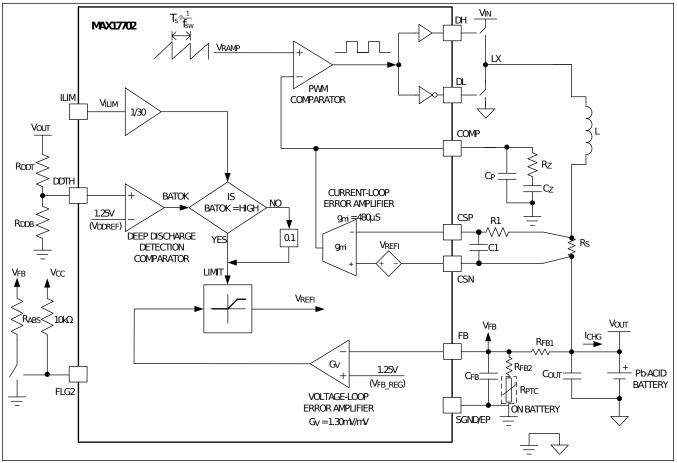


Figure 1. Average Current-Mode Control Loop

#### Power-Up/-Down Sequence and Charger Operation

<u>Figure 2</u> shows the MAX17702 power-up/-down sequence when DCIN voltage is applied/removed, and a Pb-acid battery charge cycle. <u>Figure 3</u> shows the MAX17702 charger-state diagram of the IC. MAX17702 offers precharge, constant-current (CC), absorption constant-voltage (CV), and floating constant-voltage states for charging the Pb-acid battery.

When the DCIN voltage reaches a level such that  $V_{EN/UVLO}$  is around 0.7V ( $V_{ENT}$ ) the INT-LDO regulator is enabled and  $V_{CC}$  rises. When  $V_{CC}$  rises above 4.2V ( $V_{CC-UVR}$ ) and  $V_{EN/UVLO}$  rises above 1.25V ( $V_{EN_TH_R}$ ), the MAX17702 enters powerup-check state from the charger-off state, initiates EN/UVLO debounce and checks for hardware faults. If there are no hardware faults detected at power-up (see the <u>Charger Status Outputs (FLG1 and FLG2</u>) section), the MAX17702 enables internal blocks during the charger startup delay time ( $t_{CH_START}$ ).

During charger power-up, the open-drain status output FLG2 is set to high-impedance. After the  $t_{CH\_START}$  delay, the charger initiates converter switching and enters precharge state from powerup check state if  $V_{DDTH} < 1.25V$  ( $V_{DDREF}$ ). The charger enters CC state from the power-up check state if  $V_{DDTH} \ge 1.25V$  ( $V_{DDREF}$ ).

In the precharge state, the charging current reference  $\left(\frac{V_{CSPCHG}}{R_S}\right)$  is set to 10% of the CC mode charging current

## 4.5V to 60V, Synchronous Step-Down Lead-Acid Battery Charger Controller

 $(I_{CHGMAX})$  to precondition the battery and revive it from deep-discharge state. The charger timer counts the charging time in the precharge state and if the output voltage rises above the deep-discharge threshold ( $V_{DDTH} > 1.26V$  ( $V_{DDREF}$ )) within the precharge timer timeout ( $t_{PCHG}$ ), the charger exits the precharge state, resets the charger-timer counter, and enters CC state. If the charger timer expires in precharge state ( $t_{TC} > t_{PCHG}$ ), the charger enters a latched-fault state.

If the timer function is disabled, the charger continues to charge in the precharge state until the output voltage rises above the deep discharge rising threshold ( $V_{DDTH} > 1.26V (V_{DDREF})$ ) beyond which the charger enters CC state.

In the CC state, the charger timer does not count, and the charging current ( $I_{CHG}$ ) is regulated at the CC mode charging current ( $I_{CHGMAX}$ ) proportional to  $V_{ILIM}$  until the output voltage reaches the CV mode threshold ( $V_{FB} > 1.219V$  ( $V_{FB}$  <sub>CV</sub>)). When  $V_{FB} > 1.219V$  ( $V_{FB}$  <sub>CV</sub>), the charger exits CC state and enters absorption CV state.

In the absorption CV state, the charging current is a function of the output voltage. The charger timer starts to count the charging time in the absorption CV state. If the charging current ( $I_{CHG}$ ) tapers naturally down to the taper current threshold ( $I_{TCHG}$ ) or the charger timer count exceeds the absorption CV timer timeout ( $t_{TC} > t_{FCHG}$ ), the timer resets and the charger exits the absorption CV state and enters the floating CV state by pulling down the open-drain status output (FLG2) to low. When FLG2 is pulled down, the output regulating voltage reduces from the absorption-voltage level to the floating-voltage level of the battery, as programmed by an external resistor R<sub>ABS</sub>.

If the timer function is disabled, the charger continues to charge the battery in the absorption CV state until  $I_{CHG} < I_{TCHG}$  is detected. The charger enters the floating CV state upon detecting  $I_{CHG} < I_{TCHG}$  in the absorption CV state.

In the floating CV state, the charging current is again a function of output voltage. In the floating CV state, the output voltage continues to regulate at the floating voltage level of the battery to maintain the full-charge state.

If the battery operating temperature is detected out of the set range (TEMP fault condition) in either the precharge or absorption CV state, the charger enters the respective suspend state (precharge suspend and absorption CV suspend) and pauses the timer. Upon entering back to an allowed operating temperature range (exit TEMP fault condition), the timer resumes and the charging resumes back to the previous state. If the TEMP fault is detected in either CC state or floating CV state, the charger enters the respective suspend state (CC suspend and floating CV suspend). If the exit TEMP fault condition is detected, charging resumes back to the previous state. If the timer function is disabled, the charger enters or exits the charge suspend state based on the battery operating temperature range.

When  $V_{EN/UVLO}$  falls below 1.09V ( $V_{EN\_TH\_F}$ ), the MAX17702 initiates a shutdown sequence with a debounce time of 2ms (typ). If the input voltage decreases such that ( $V_{IN} - V_{CSN}$ ) falls below the current-loop-error amplifier undervoltage-lockout falling threshold ( $V_{CMUVLO} = 1.95V$ ), the MAX17702 initiates a shutdown sequence immediately. The converter stops switching, and GATEN is pulled down with 1.1 $\Omega$  ( $R_{GATEN\_A}$ ) to DCIN to turn off the external nMOSFET. The COMP is pulled low after a debounce time of 100µs (typ).

If  $V_{EN/UVLO}$  falls below 0.64V ( $V_{ENT}$ ), the MAX17702 initiates a shutdown sequence with a debounce time of 10µs (typ). During this shutdown sequence, the MAX17702 pulls down the GATEN with 1.1 $\Omega$  ( $R_{GATEN_A}$ ) to DCIN to turn off the external nMOSFET. See the <u>Setting the Input Undervoltage-Lockout Level (EN/UVLO)</u> section for more details.

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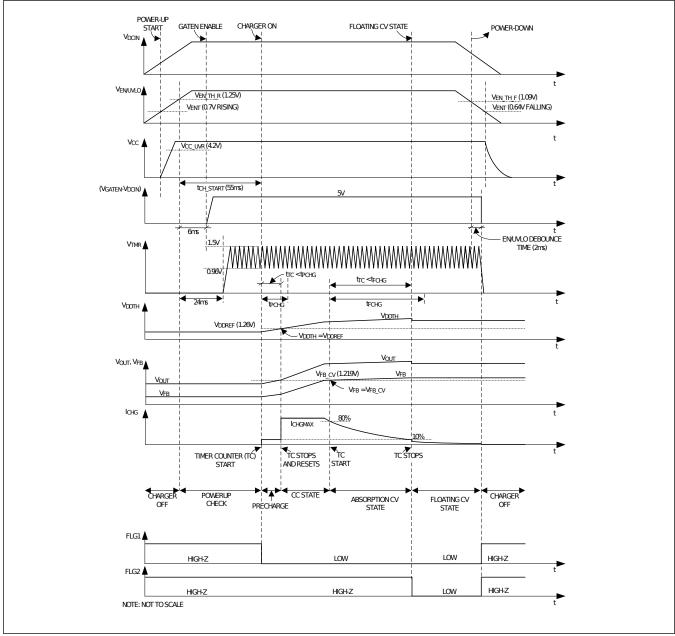


Figure 2. Charger Power-Up/-Down Sequence and Pb-Acid Battery Charge Cycle

## 4.5V to 60V, Synchronous Step-Down Lead-Acid Battery Charger Controller

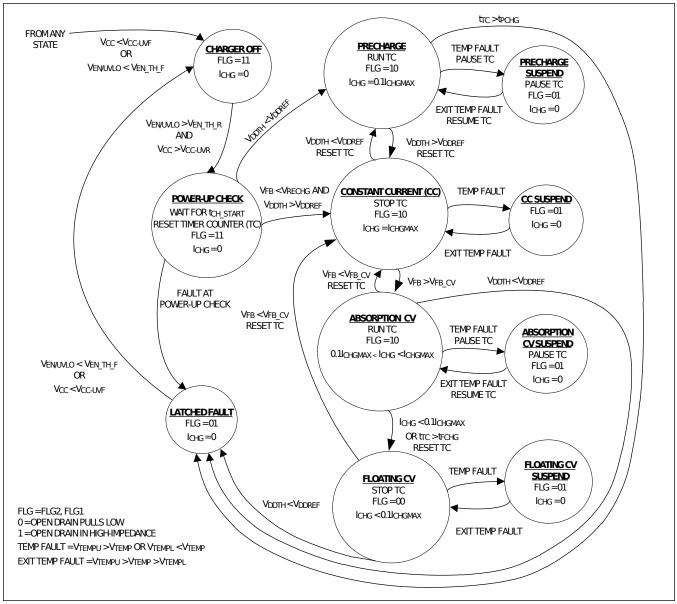


Figure 3. Charger-State Diagram

#### Input Short-Circuit Protection (GATEN)

The MAX17702 provides a gate drive output (GATEN) that drives a logic-level gate-threshold external nMOSFET, which turns off and prevents battery discharging for input supply short-circuit events. The GATEN is pulled up with 20 $\mu$ A (I<sub>GATEN</sub>) when V<sub>IN</sub> is 2.04V (V<sub>CMUVLO</sub>) above V<sub>CSN</sub>. If V<sub>GATEN</sub> does not reach 3.55V (V<sub>GATEN\_OK</sub>) within 15ms (t<sub>GATEN\_OK</sub>), MAX17702 enters the latched-fault state.

<u>Figure 4</u> depicts the MAX17702 behavior when DCIN is shorted to PGND. When  $V_{DCIN}$  is 93mV ( $V_{REV}$ ) below  $V_{IN}$ , GATEN is pulled down with 1.1 $\Omega$  ( $R_{GATEN}$  A) and the external nMOSFET is turned off within 100ns (typ). When  $V_{EN/}$  UVLO goes below 0.64V ( $V_{ENT}$ ), the MAX17702 shuts down with 10 $\mu$ s (typ) debounce time. When DCIN-to-PGND short is removed, a power-up sequence is initiated (see the <u>Power-Up/Down Sequence and Charger Operation</u> section). When

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the input short-circuit protection is not used, connect a 2.2nF capacitor between GATEN and DCIN, and short DCIN to  $V_{\text{IN}}$ .

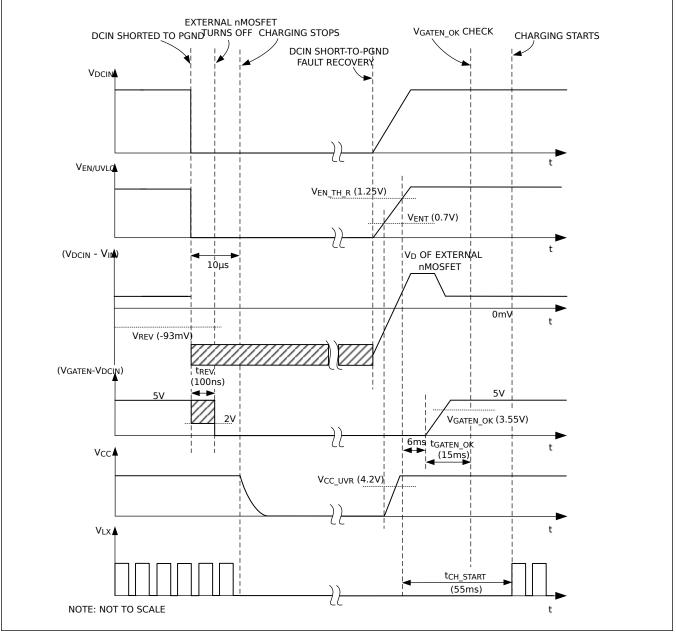


Figure 4. Input Short-Circuit Protection and Recovery Timing Diagram

#### **Charger Timers (TMR)**

The MAX17702 offers a programmable timer feature to provide battery charge-cycle control. Connect a capacitor from TMR to SGND/EP to use the timer feature. Connect TMR to  $V_{REF}$  to disable the timer feature. The timer counts the charging time in the precharge and absorption CV states.

## 4.5V to 60V, Synchronous Step-Down Lead-Acid Battery Charger Controller

In the precharge state, if  $V_{DDTH}$  does not reach 1.26V ( $V_{DDREF}$ ) within precharge timer count ( $t_{PCHG}$ ), the charger enters the latched-fault state.

In absorption CV state, the charger pulls down FLG2 to low and enters the floating CV state, when the absorption CV timer count ( $t_{FCHG}$ ) elapses.

Table 1 shows the relative timer counts in different states.

#### **Table 1. Charger Timers**

STATE	TIMER COUNT	
Precharge	t <sub>PCHG</sub> = t <sub>FCHG</sub> /8	
CC	Timer does not count	
Absorption CV	<sup>t</sup> ғснg	
Floating CV	Timer does not count	

The MAX17702 supports 2.2nF to  $10\mu$ F capacitance on the TMR pin, translating to an absorption CV timeout period range of 7.2 minutes to 547 hours.

Use the following equation to calculate the C<sub>TMR</sub> for the required absorption CV timer timeout (T<sub>CVTMR</sub>):

$$C_{\text{TMR}} \ge 1.15 \times \left(\frac{T_{\text{CVTMR}}}{2 \times t_{\text{FCHG}}}\right) \times \left(\frac{I_{\text{TMR}}}{V_{\text{TMR}_{\text{H}}} - V_{\text{TMR}_{\text{L}}}}\right)$$

where

T<sub>CVTMR</sub> = Desired safety timer setting in the absorption CV state in seconds

C<sub>TMR</sub> = TMR capacitor in Farad

t<sub>FCHG</sub> = Number of TMR cycles in the absorption CV state (2097151)

 $V_{\text{TMR} \text{ H}}$  = TMR oscillator upper threshold (1.5V)

 $V_{\text{TMR L}}$  = TMR oscillator lower threshold (0.96V)

I<sub>TMR</sub> = TMR pin source/sink current (10µA)

#### Charger Status Outputs (FLG1, FLG2)

The MAX17702 features two open-drain status output pins (FLG1 and FLG2) to indicate the status of the charger. <u>Table</u> 2 shows the status flag summary.

#### Table 2. Status Output Indications

CHARGER STATUS FLG (FLG2, FLG1)	FLG2	FLG1	CHARGER STATE
11	Open drain in Hi- Impedance (1)	Open drain in Hi- Impedance (1)	Charger Off
10	Open drain in Hi- Impedance (1)	Open drain pulls low (0)	Charging in progress (precharge, CC, absorption CV states)
00	Open drain pulls low (0)	Open drain pulls low (0)	Float charging (floating CV state)
01	Open drain pulls low (0)	Open drain in Hi- Impedance (1)	Latched fault or charge suspend due to high- or low-battery temperature detection*

\*Latched-fault state includes latched hardware faults and faulty battery states. Charge suspended due to high or low battery temperature is not a latched fault. <u>Table 3</u> provides various fault detection features available and their behaviors in MAX17702.

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### **Table 3. Protection Under System Faults**

FAULT CONDITION	FAULT MONITOR STATE	FAULT BEHAVIOR	
RT/SYNC to SGND/EP short			
GATEN to DCIN short		Latched Fault. Need to recycle power to restart the device	
TMR unconnected	Power-Up Check		
TMR to SGND/EP short			
V <sub>REF</sub> to SGND/EP short			
V <sub>REF</sub> < 1.95V or V <sub>REF</sub> > 3.05V	Continuous, During Normal		
(V <sub>GATEN</sub> - V <sub>DCIN</sub> ) < V <sub>GATEN_OK</sub>			
V <sub>FB</sub> < 65mV (FB to SGND/EP short or R <sub>FB1</sub> open fault)	Operation		
Faulty battery (timer count in Precharge state t <sub>TC</sub> > t <sub>PCHG</sub> )	Precharge State		
V <sub>DDTH</sub> < 1.25V (V <sub>DDREF</sub> )	Absorption CV and Floating CV States		
High- or low-battery temperature detection (V <sub>TEMP</sub> < 0.7V (V <sub>TEMPL</sub> ) or V <sub>TEMP</sub> > 1.5V (V <sub>TEMPU</sub> ))	Precharge, CC, Absorption CV, Floating CV States	Suspend Charge, Pause Timer. Upon entering back to an allowed operating temperature range, the timer resumes (except in CC and Floating CV states), charging resumes back to the previous state.	

#### Linear Regulator (V<sub>CC</sub> and EXTVCC)

The MAX17702 integrates two internal low-dropout (LDO) linear regulators INT-LDO and EXT-LDO that power V<sub>CC</sub>. V<sub>CC</sub> powers gate drivers and internal control circuitry. INT-LDO is powered from V<sub>IN</sub> and turns on when V<sub>EN/UVLO</sub> > V<sub>ENT</sub> (0.7V). EXT-LDO is powered from EXTVCC. At any time, only one of these two linear regulators operates, depending on the EXTVCC voltage. If V<sub>EXTVCC</sub> > 4.7V (typ) then V<sub>CC</sub> is powered from EXT-LDO. If V<sub>EXTVCC</sub> < 4.46V (typ), then V<sub>CC</sub> is powered from INT-LDO. Powering V<sub>CC</sub> from EXTVCC reduces on-chip power dissipation and increases efficiency at higher input voltages. EXTVCC should be connected to V<sub>OUT</sub> for applications with V<sub>OUT</sub> ≥ 4.8V. The maximum voltage limit on EXTVCC is 24V. Bypass EXTVCC with a 1µF ceramic capacitor to SGND/EP. Leave EXTVCC open when not used. Bypass V<sub>CC</sub> to PGND with at least a 4.7µF/0805, low-ESR ceramic capacitor.

#### Reference Voltage (V<sub>REF</sub>)

The MAX17702 provides a ±1.4% accurate 2.5V reference voltage on the V<sub>REF</sub> pin. V<sub>REF</sub> can be used to program V<sub>ILIM</sub> to set the CC mode charging current (I<sub>CHGMAX</sub>). V<sub>REF</sub> can also be used to program TMR and TEMP for disabling the charger timer and the setting battery operating temperature range, respectively. Connect a minimum 0.1µF low-ESR ceramic capacitor between V<sub>REF</sub> and SGND/EP. See the <u>CC Mode Charging Current Setting (ILIM)</u>, Charger Timers (TMR), and <u>Setting Battery Operating Temperature Range (TEMP)</u> sections for more details.

#### Setting the Switching Frequency and External Clock Synchronization (RT/SYNC)

The switching frequency of the device can be programmed from 125kHz to 2.2MHz by using a resistor ( $R_{RT/SYNC}$ ) connected from the RT/SYNC pin to SGND/EP.  $R_{RT/SYNC}$  can be calculated using the following equation:

$$R_{\text{RT/SYNC}} = \frac{44830}{f_{\text{SW}}} - 1.205$$

Where  $R_{RT/SYNC}$  is in k $\Omega$  and  $f_{SW}$  is in kHz. Leave the RT/SYNC pin unconnected to operate the device at 350kHz (default) switching frequency.

The MAX17702 can be synchronized to an external clock coupled to the RT/SYNC pin through a 10pF ceramic capacitor. The external clock is detected after checking the rising edge for 112 cycles of the internal clock (set by RT/SYNC). If

## 4.5V to 60V, Synchronous Step-Down Lead-Acid Battery Charger Controller

the external clock frequency is within the allowed SYNC frequency range ( $\pm 10\%$  of nominal internal clock frequency), the device stops switching for 2 switching time periods and then restarts with an external clock. When the external clock is removed, the device stops switching for 10 switching time periods and then restarts with the internal clock.

The minimum external-clock pulse-width should be greater than 100ns. The off-time duration of the external clock should be at least 100ns.

#### Peak Current-Limit

The MAX17702 provides a cycle-by-cycle overcurrent protection by limiting the peak current-sense voltage ( $V_{CSP} - V_{CSN}$ ) across the current sense pins. When an overcurrent event (( $V_{CSP} - V_{CSN}$ ) >  $V_{CS}$ \_PEAK) is detected, the overcurrent comparator in the MAX17702 terminates the DH pulse and limits the peak current. The overcurrent fault is not latched.

#### **Charging Current Monitoring (ISMON)**

The output charge current can be monitored by observing the voltage at the ISMON pin. Connect a 1nF ceramic capacitor on ISMON to filter out the switching frequency component in the ISMON voltage. The charging current is given by the following equation:

$$I_{\rm CHG} = \frac{V_{\rm ISMON}}{30 \times R_{\rm S}}$$

where,

 $I_{CHG}$  = Charging current  $V_{ISMON}$  = Voltage on the ISMON pin  $R_S$  = Current-sense resistance

#### **Thermal-Shutdown Protection**

Thermal-shutdown protection limits the junction temperature of the device. When the junction temperature of the device exceeds +160°C, an on-chip thermal sensor shuts down the device, allowing the device to cool. The device turns on after the junction temperature reduces by 10°C. Carefully evaluate the total power dissipation (see the <u>Device Power</u> <u>Dissipation</u> section) to avoid unwanted triggering of the thermal shutdown during normal operation.

### **Applications Information**

#### Inductor Selection

Three key inductor parameters must be specified for operation with the device: inductance value (L), DC resistance (R<sub>DCR</sub>), and inductor saturation current (I<sub>SAT</sub>).

The required inductance is calculated based on the inductor current ripple ratio (LIR), i.e., the ratio of inductor peak-topeak ripple current ( $\Delta I_I$ ) to CC mode charging current ( $I_{CHGMAX}$ ). A good compromise between size and loss is an LIR of 0.3.

The inductance value (L) is given by the higher value of the two calculated inductances:

$$L1 = \frac{V_{OUT} \times (1-D)}{LIR \times I_{CHGMAX} \times f_{SW}}$$
$$L2 = \frac{V_{OUT}}{600000 \times I_{CHGMAX}}$$

where,

V<sub>OUT</sub> = Desired voltage across battery in absorption CV state

I<sub>CHGMAX</sub> = CC mode charging current

D = Duty cycle of the converter,  $V_{OUT}/V_{IN}$ 

VIN = Nominal input voltage

f<sub>SW</sub> = Switching frequency

Select an inductor that is nearest to the calculated value. The inductor (RMS) current rating should be more than the CC mode charging current. Select a low-loss inductor with acceptable dimensions and the lowest possible DC resistance. The saturation current rating (ISAT) of the inductor must be high enough to ensure that saturation can occur only above the overcurrent threshold corresponding to VCS PEAK.

#### **Output Capacitor Selection**

Batteries have significant internal charging resistance and connection resistances (R<sub>BAT</sub>). The switching ripple component of charger output current flows into R<sub>BAT</sub> and results in a large output-voltage ripple.

To reduce the voltage ripple across the battery, additional X7R ceramic capacitors and/or low-ESR POSCAP capacitors can be used at the output of the charger. X7R ceramic output capacitors are preferred due to their stability over temperature. For higher values of output capacitance, low-ESR POSCAP capacitors can be used in parallel with ceramic capacitors.

Calculate the required output capacitance (C<sub>OUT</sub>) based on the following equation:

$$C_{OUT} = \frac{25 \times I_{CHGMAX}}{f_{SW} \times V_{OUT}}$$

SW

where,

I<sub>CHGMAX</sub> = CC mode charging current setting

f<sub>SW</sub> = Switching frequency

V<sub>OUT</sub> = Desired voltage across battery in absorption CV state

Derating of ceramic capacitors with DC-bias voltage must be considered while selecting the capacitors, using the manufacturer data sheet. The selected output capacitor (COUT SEL) and its equivalent series resistance (ESRCOUT) affect the output voltage ripple ( $\Delta V_{OUT}$ ). Estimate the resultant output-voltage ripple ( $\Delta V_{OUT}$ ) using the following equation:

$$\Delta V_{OUT} \approx \Delta I_L \times \left( \mathsf{ESR}_{\mathsf{COUT}} + \frac{1}{8 \times f_{\mathsf{SW}} \times C_{\mathsf{OUT}}} \right)$$

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where  $\Delta I_L$  is the inductor peak-to-peak ripple current.

#### **Input Capacitor Selection**

The input filter capacitor reduces peak currents drawn from the power source and reduces noise and voltage ripple on the input caused by the switching converter. Calculate the required input capacitance at  $V_{IN}$  ( $C_{VIN}$ ) using the following equation:

 $C_{VIN} = \frac{I_{CHGMAX} \times D \times (1 - D)}{\eta \times f_{SW} \times \Delta V_{IN}}$ 

where,

 $D = \frac{V_{OUT}}{V_{IN}} = Duty ratio of the converter$ 

f<sub>SW</sub> = Switching frequency

 $\Delta V_{IN}$  = Allowable input-voltage ripple

 $\eta$  = Efficiency of the converter

I<sub>CHGMAX</sub> = CC mode charging current

Choose  $\Delta V_{IN} \le 0.5V$  to minimize voltage ripple across the external nMOSFET and to provide robust operation during input short-circuit events.

The input capacitor RMS current (I<sub>RMS</sub>) is calculated using the following equation:

$$I_{RMS} = I_{CHGMAX} \times \frac{\sqrt{V_{OUT} \times (V_{IN} - V_{OUT})}}{V_{IN}}$$

Choose low-ESR ceramic input capacitors that exhibit less than a 10°C temperature rise at I<sub>RMS</sub> for optimal long-term reliability. X7R capacitors are recommended in industrial applications for their temperature stability. Derating of ceramic capacitors with DC-bias voltage must be considered while selecting the capacitors using the manufacturer data sheet.

Choose an electrolytic capacitor at DCIN to prevent the DCIN voltage from being less than -0.3V during input short events. An electrolytic capacitor also provides the damping for potential oscillations caused by inductance of the longer input power path and input ceramic capacitor ( $C_{VIN}$ ). Additionally, if required, add a Schottky diode at DCIN in parallel with the electrolytic capacitor.

#### **Operating Input-Voltage Range**

The following equations are used to calculate the operating input voltage range for a given output voltage and CC mode charging current setting. The minimum operating input voltage on the DCIN pin is given by the higher value from the two calculated voltages:

$$V_{\text{DCIN(MIN1)}} = \frac{V_{\text{OUT}} + I_{\text{CHGMAX}} \times \left( R_{\text{DS}}_{\text{ON(LS)}} + R_{\text{DCR(MAX)}} \right)}{\left( 1 - \left( 1.05 \times f_{\text{SW}} \times \left( t_{\text{DT}}_{\text{HL}} + t_{\text{MIN}}_{\text{ON}}_{\text{DL}} \right) \right) \right)} + \left( I_{\text{CHGMAX}} \times \left( R_{\text{DS}}_{\text{ON(HS)}} - R_{\text{DS}}_{\text{ON(LS)}} \right) \right)$$

 $V_{\text{DCIN(MIN2)}} = V_{\text{OUT}} + 2.1V$ 

where:

 $V_{DCIN(MIN1)}$ ,  $V_{DCIN(MIN2)}$  = Minimum operating input voltages; the higher of the two values is the minimum operating input voltage,  $V_{DCIN(MIN)}$ 

 $V_{OUT}$  = Desired maximum regulation voltage across battery in absorption CV state at minimum battery operating temperature (T<sub>COLD</sub>)

I<sub>CHGMAX</sub> = CC mode charging current setting

 $f_{SW}$  = Switching frequency in Hz

 $R_{DCR(MAX)}$  = Worst-case DC resistance of the inductor in  $\Omega$ 

## 4.5V to 60V, Synchronous Step-Down Lead-Acid Battery Charger Controller

 $R_{DS\_ON(HS)}$  and  $R_{DS\_ON(LS)}$  = Worst-case on-state resistances of high-side and low-side internal MOSFETs in  $\Omega$ , respectively

 $t_{DT}$  HL = Dead time (30ns)

t<sub>MIN ON DL(MAX)</sub> = Worst-case DL minimum guaranteed on-time (100ns)

The maximum operating input voltage on the DCIN pin is calculated as follows:

$$V_{\text{DCIN(MAX)}} = \frac{V_{\text{OUT}}}{\left(1.05 \times f_{\text{SW}} \times f_{\text{MIN}} \text{ON}_{\text{DH}(\text{MAX})}\right)}$$

where t<sub>MIN ON DH(MAX)</sub> = Worst-case DH minimum guaranteed on-time (100ns)

#### CC Mode Charging Current Setting (ILIM)

The CC mode charge current setting involves setting up a voltage on the ILIM pin (V<sub>ILIM</sub>) and choice of current sense resistor R<sub>S</sub>. Selection of R<sub>S</sub> involves a trade-off between power loss and charging current accuracy. The best MAX17702 charging current accuracy is obtained with a voltage drop (V<sub>CSP</sub> - V<sub>CSN</sub>) of 50mV across R<sub>S</sub>. (V<sub>CSP</sub> - V<sub>CSN</sub>) can be reduced at the expense of charging current accuracy to reduce power loss. The recommended range for voltage across R<sub>S</sub> is 30mV (±6.7% charging current accuracy) to 50mV (±4% charging current accuracy). R<sub>S</sub> can be calculated using the following equation:

$$R_{S} \leq \frac{\left(V_{CSP} - V_{CSN}\right)}{V_{CHGMAX}}$$

Once  $R_S$  is selected,  $V_{ILIM}$  can be calculated using the following equation:

$$V_{\rm ILIM} = 30 \times R_S \times I_{\rm CHGMAX}$$

A resistor divider from  $V_{REF}$  to SGND/EP can be used to program  $V_{ILIM}$  as shown in <u>Figure 5</u>. The resistor divider values are calculated as follows:

 $R_{\text{LIM1}} = 20 \times (V_{\text{REF}} - V_{\text{ILIM}}) k\Omega$ 

 $R_{\text{LIM2}} = 20 \times V_{\text{ILIM}} k\Omega$ 

The permitted voltage range for the V<sub>ILIM</sub> setting is 0.9V to 1.5V. The MAX17702 can be set to the default I<sub>CHGMAX</sub> setting corresponding to (V<sub>CSP</sub> - V<sub>CSN</sub>) = 50mV across R<sub>S</sub> by connecting ILIM to V<sub>REF</sub>.

Connect an R-C filter in the current-sense signal path as shown in <u>Figure 5</u> to attenuate switching noise while preserving accuracy and bandwidth. Select an R-C filter corner frequency at 5 times the switching frequency. The recommended filter resistance (R1) is  $40\Omega$  for minimal impact on the current-sense accuracy. Place the filter close to the CSP and CSN pins of the device. Calculate the value of filter capacitor C1 using the following equation:

 $C1 = \frac{1}{2\pi x R1 x 5 x f_{\rm SW}}$ 

where f<sub>SW</sub> = Switching frequency

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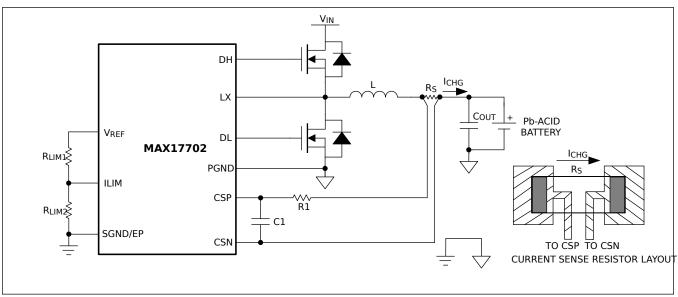


Figure 5. Current Sense Circuit

#### Setting the Input Undervoltage-Lockout Level (EN/UVLO)

The MAX17702 offers an adjustable input undervoltage-lockout level using the EN/UVLO pin. Pulling the EN/UVLO pin below 1.09V (typ) stops charger operation. Pulling EN/UVLO below 0.64V (typ) causes the MAX17702 to shut down. In this state, the device draws  $I_{IN}$  SH (7µA) quiescent current. Figure 6 shows the recommended EN/UVLO configuration based on the required input voltage range. Connect EN/UVLO to the center node of a resistor divider from the DCIN to SGND/EP to set the input voltage at which the device turns on. Choose R1 as follows:

 $R1 \leq (10000 \times V_{\text{DCIN(MIN)}})$ 

where  $V_{DCIN(MIN)}$  is the voltage at which the device is required to turn on.

Calculate the value of R2 using the following equation:

$$R2 = \frac{V_{\text{EN}_{\text{TH}_{\text{R}}} \times R1}}{(V_{\text{DCIN(MIN)}} - V_{\text{EN}_{\text{TH}_{\text{R}}} + (l_{\text{EN}_{\text{-}} \text{BIAS}} \times R1))}}$$

where:

I<sub>EN-BIAS</sub> = Internal bias pullup current on the EN/ULVO pin

 $V_{EN}$  TH R = EN/UVLO rising threshold voltage (1.25V)

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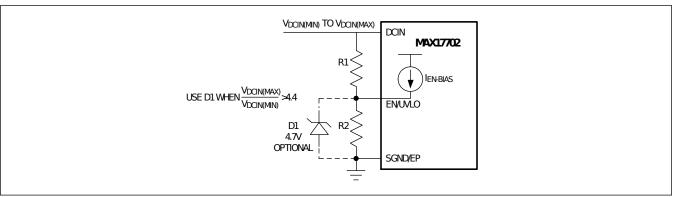


Figure 6. Setting the Input Undervoltage-Lockout

#### **Current-Regulation Loop Compensation (COMP)**

The MAX17702 features a COMP pin to tune the current loop to control performance of the average current-mode controller. Refer to <u>Figure 1</u> for a depiction of the compensation network on the COMP pin using R<sub>Z</sub>, C<sub>Z</sub>, and C<sub>P</sub>. The choice of the compensation component values depends on the chosen inductor (L) and its DC resistance (R<sub>DCR</sub>), switching frequency (f<sub>SW</sub>), current sense resistor (R<sub>S</sub>), maximum operating input voltage (V<sub>DCIN(MAX)</sub>), the desired regulation voltage across battery in absorption CV state (V<sub>OUT</sub>), battery charging resistance (R<sub>BAT</sub>), and the on-resistances of the step-down converter nMOSFETs (R<sub>DS\_ON(HS)</sub> and R<sub>DS\_ON(LS)</sub>).

Calculate the compensation resistor  $R_Z$  using the following equation:

$$R_{Z} = \frac{3000 \times L \times f_{SW}}{V_{DCIN(MAX)} \times R_{S}}$$

Calculate the compensation capacitor  $C_Z$  using the following equation:

$$C_{Z} = \frac{0.8 \times L}{R_{Z} \times R_{E}}$$

where

$$R_{E} = \left[ R_{\text{DCR}} + R_{S} + R_{\text{DS}}_{\text{ON(HS)}} \times D_{\text{MIN}} + R_{\text{DS}}_{\text{ON(LS)}} \times (1 - D_{\text{MIN}}) + R_{\text{BAT}} \right]$$
$$D_{\text{MIN}} = \frac{V_{\text{OUT}}}{V_{\text{DCIN(MAX)}}}$$

Calculate the high-frequency pole capacitor C<sub>P</sub> using the following equation:

$$C_{P} = \frac{0.35}{R_{Z} \times f_{SW}}$$

#### Setting Output Voltage and Temperature Compensation (FB)

The MAX17702 features a FB pin to regulate the voltage across the battery to a desired level. Temperature compensation of the battery charging voltage can be achieved by including a linear positive temperature coefficient (PTC) resistor in the output-voltage feedback circuit. Connect a feedback resistor-divider circuit ( $R_{FB1}$ ,  $R_{FB2}$ ,  $R_{PTC}$ , and  $R_{ABS}$ ) with a compensating capacitor ( $C_{FB}$ ) as depicted in Figure 7.

The choice of feedback circuit components depends on the desired regulation voltages across the battery in absorption CV and floating CV states, and temperature compensation. Select the linear PTC resistor ( $R_{PTC}$ ) between 1.5k $\Omega$  and 5k $\Omega$ . Calculate  $R_{ABS}$ ,  $R_{FB2}$ , and  $R_{FB1}$  using the following equations:

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$$R_{ABS} = \frac{\Delta R_{PTC} x (V_{FLOAT_H} - V_{FB_REG}) x (V_{FLOAT_L} - V_{FB_REG})}{V_{ABS_H} x (V_{FLOAT_L} - V_{FB_REG}) - V_{ABS_L} x (V_{FLOAT_H} - V_{FB_REG}) + V_{FB_REG} x (V_{FLOAT_H} - V_{FLOAT_L})}$$

$$R_{FB2} = \frac{(V_{ABS} - V_{FLOAT})}{(V_{FLOAT} - V_{FB_REG})} x R_{ABS} - R_{PTC}$$

$$R_{FB1} = \frac{(V_{ABS} - V_{FLOAT})}{V_{FB_REG}} x R_{ABS}$$

where:

V<sub>FB REG</sub> = FB reference voltage (1.25V)

 $\Delta R_{PTC}$  = Resistance variation for the selected linear PTC resistor over operating temperature limits of the Pb-acid battery V<sub>FLOAT</sub>, V<sub>FLOAT</sub>, And V<sub>FLOAT</sub> = Desired regulated output voltages in floating CV state at room temperature (25°C), maximum battery charging temperature limit (T<sub>HOT</sub>), and minimum battery charging temperature limit (T<sub>COLD</sub>) based on the desired temperature compensation (battery voltage variation/°C increment), respectively

 $V_{ABS}$ ,  $V_{ABS}_H$ , and  $V_{ABS}_L$ = Desired regulated output voltages in absorption CV state at room temperature (T<sub>HOT</sub> and T<sub>COLD</sub>) based on the desired temperature compensation, respectively

The compensation capacitor (C<sub>FB</sub>) stabilizes the voltage regulation loop. Calculate C<sub>FB</sub> using the following equation:

$$C_{\text{FB}} = \frac{5}{R_{\text{PAR}} \times f_{\text{SW}}} \times \frac{V_{\text{DCIN}(\text{MAX})}}{V_{\text{DCIN}(\text{MIN})}}$$

where:

V<sub>DCIN(MIN)</sub> = Minimum input-operating voltage

V<sub>DCIN(MAX)</sub> = Maximum input-operating voltage

f<sub>SW</sub> = Switching frequency

 $R_{PAR} = \frac{\left(R_{FB2} + R_{PTC}\right) \times R_{ABS} \times R_{FB1}}{\left(R_{FB2} + R_{PTC}\right) \times \left(R_{FB1} + R_{ABS}\right) + R_{ABS} \times R_{FB1}}$ 

Small signal nMOSFET (Q4) in series with R<sub>ABS</sub> is used to change the output voltage regulation point from the absorption level to the floating level of the battery. Select the MOSFET with R<sub>DS-ON</sub> in range of 1 $\Omega$  to 10 $\Omega$  and with a gate threshold voltage less than 3V.

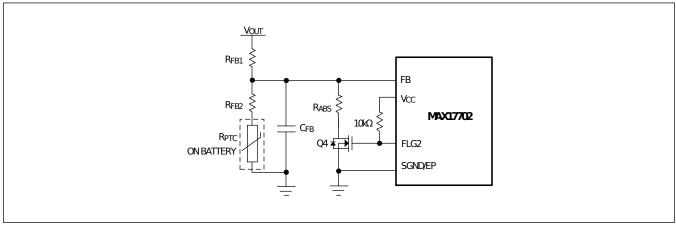


Figure 7. Setting the Output Regulated Voltage in Absorption and Floating CV states with Temperature Compensation

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#### Setting Battery Deep-Discharge Voltage Level (DDTH)

The MAX17702 offers a battery deep-discharge state detection mechanism through the DDTH pin. During power-up the device enters a precharge state when the voltage at the DDTH pin ( $V_{DDTH}$ ) is less than 1.25V ( $V_{DDREF}$ ). The device transitions into a CC state when  $V_{DDTH}$  exceeds  $V_{DDREF}$ . The deep-discharge voltage sense level of a battery can be set by connecting DDTH to the center node of a resistor-divider from output to SGND/EP as shown in Figure 1. Connect DDTH to  $V_{REF}$  when not used.

Select  $R_{DDT}$  in the range of  $50k\Omega$  to  $100k\Omega$ .

Calculate resistor R<sub>DDB</sub> from the following equation:

$$R_{\text{DDB}} = \frac{R_{\text{DDT}}}{\left(\frac{V_{\text{OUTDD}}}{V_{\text{DDREF}}} - 1\right)}$$

where,

V<sub>OUTDD</sub> = Deep-discharge level of the battery

V<sub>DDREF</sub> = Deep-discharge detection comparator threshold (1.25V)

#### Setting Battery Operating Temperature Range (TEMP)

The MAX17702 features a TEMP pin for battery temperature sensing and allows charging only when the temperature is within the programmed operating temperature range ( $T_{COLD} < T < T_{HOT}$ ) using a negative temperature coefficient (NTC) resistor. Connect an NTC resistor in a resistor divider circuit from V<sub>REF</sub> to SGND/EP as shown in Figure 8. A 47k $\Omega$  NTC resistor with B-constant (25°C to 85°C) = 4108 is recommended. Calculate R<sub>TEMP1</sub>, R<sub>TEMP2</sub> and R<sub>TEMP3</sub> using the following equations:

$$R_{\text{TEMP1}} = 127 \text{k}\Omega; \qquad \text{For } (T_{\text{HOT}} - T_{\text{COLD}}) > 45^{\circ}C$$

$$= \frac{2.86 \times R_{\text{NTCCOLD}} \times R_{\text{NTCHOT}}}{(R_{\text{NTCCOLD}} - 3.86 \times R_{\text{NTCHOT}})}; \text{ For } (T_{\text{HOT}} - T_{\text{COLD}}) \le 45^{\circ}C$$

$$R_{\text{TEMP2}} = 0.35 \times R_{\text{EFF}}COLD - 1.35 \times R_{\text{EFF}}HOT}; \text{ For } (T_{\text{HOT}} - T_{\text{COLD}}) > 45^{\circ}C$$

$$= 0; \qquad \text{For } (T_{\text{HOT}} - T_{\text{COLD}}) \le 45^{\circ}C$$

$$R_{\text{TEMP3}} = \frac{2}{3}(R_{\text{TEMP2}} + R_{\text{EFF}}COLD)$$

 $R_{EFF\_COLD} = \frac{R_{NTCCOLD} \times R_{TEMP1}}{(R_{NTCCOLD} + R_{TEMP1})}$  $R_{EFF\_HOT} = \frac{R_{NTCHOT} \times R_{TEMP1}}{(R_{NTCHOT} + R_{TEMP1})}$ 

where,

T<sub>HOT</sub> = Maximum battery charging temperature limit in °C

T<sub>COLD</sub> = Minimum battery charging temperature limit in °C

R<sub>NTCCOLD</sub> = Resistance value of the selected NTC resistor at T<sub>COLD</sub>

and  $R_{NTCHOT}$  = Resistance value of the selected NTC resistor at  $T_{HOT}$ .

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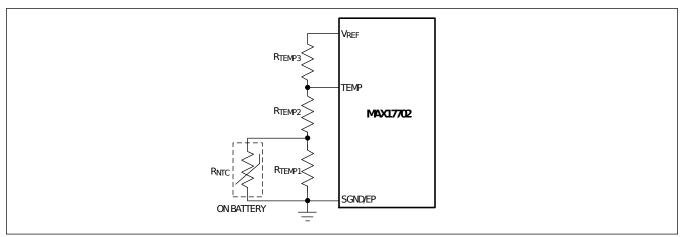


Figure 8. Setting the Battery Operating Temperature Range

#### **Bootstrap Capacitor Selection**

The bootstrap capacitance ( $C_{BST}$ ) value is determined by the selection of the high-side nMOSFET(s). Choose  $C_{BST}$  using the following equation:

$$C_{BST} \ge \frac{\Delta Q_G}{\Delta V_{BST}}$$

where:

 $\Delta Q_G$  = Total gate charge of the high-side nMOSFET(s)

 $\Delta V_{BST}$  = Voltage variation allowed on the high-side nMOSFET(s) driver after turn-on

Choose  $\Delta V_{BST} \le 100$ mV to select C<sub>BST</sub>. The bootstrap capacitor should be a low-ESR ceramic capacitor. A minimum value of  $0.1\mu$ F is recommended.

#### **Bootstrap Diode Selection**

Select a Schottky diode with the following ratings:

- Reverse voltage rating  $\geq$  (Maximum input operating voltage + 10V)
- Average forward current rating ≥ 1A

Choose a diode with low forward voltage drop and low reverse leakage current across the operating temperature range.

#### Input Short-Circuit Protection External nMOSFET Selection

The MAX17702 is designed to control an external logic-level nMOSFET that turns off in less than 100ns and isolates the V<sub>IN</sub> node from input short-circuit events. This feature prevents discharge of the battery into the input during input short-circuit events. The external nMOSFET used for this feature only turns on once during power-up and turns off during shutdown and, therefore, does not need to be optimized for switching performance. Select an external nMOSFET with low R<sub>DS-ON</sub> for low forward-path conduction losses. The MAX17702 supports external nMOSFETs with gate charge up to 250nC at V<sub>GS</sub> = 3.9V. Using an external nMOSFET with larger gate charge values results in a gate charging time larger than t<sub>GATEN OK</sub> (15ms typ) and causes the MAX17702 to enter the latched-fault condition.

#### Step-Down Converter nMOSFET Selection

The MAX17702 drives two external logic-level nMOSFETs to implement the step-down converter high-side and low-side switches. These nMOSFETs must be logic-level compatible with guaranteed on-resistance specifications provided at  $V_{GS}$  = 4.5V. The key selection parameters to choose these MOSFETs include:

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- On-resistance (R<sub>DS-ON</sub>)
- Maximum drain-to-source voltage (V<sub>DS(MAX)</sub>)
- Miller Plateau voltage on the nMOSFET Gaté (V<sub>MIL</sub>)
- Total gate charge (Q<sub>G</sub>)
- Output capacitance (C<sub>OSS</sub>)
- Power-dissipation rating and package thermal resistance
- Maximum operating junction temperature

For the step-down converter, nMOSFETs should be chosen in such a way that the switching losses and conduction losses are balanced and optimized. The duty cycles for the high-side and low-side external nMOSFETs can be calculated as follows:

$$D = \frac{V_{OUT}}{V_{IN}}$$

High-side nMOSFET duty cycle: D

Low-side nMOSFET duty cycle: 1 - D

High-side nMOSFET losses can be estimated using the following formula:

PHS-MOSFET = PHS-MOSFET\_CONDUCTION + PHS-MOSFET\_SWITCHING

$$P_{HS} - MOSFET_CONDUCTION = I_{CHG}^2 \times R_{DS} - ON(HS) \times D$$

$$P_{\text{HS}-\text{MOSFET}_\text{SWITCHING}} = f_{\text{SW}} \times \left( \left[ \frac{V_{\text{IN}} \times I_{\text{CHG}}}{2} \times \frac{Q_{\text{SW}} \times R_{\text{DR}}}{V_{\text{CC}} - V_{\text{MIL}}} \right] + \left[ V_{\text{IN}} \times Q_{\text{rr}} \right] + \left[ \frac{1}{2} \times C_{\text{OSSHS}} \times V_{\text{IN}}^2 \right] + \left[ \frac{1}{2} \times C_{\text{OSSLS}} \times V_{\text{IN}}^2 \right] \right)$$

where,

f<sub>SW</sub> = Switching frequency

I<sub>CHG</sub> = Charging current

Q<sub>SW</sub> = Switching charge of the high-side nMOSFET from the nMOSFET data sheet,

R<sub>DR</sub> = Sum of the DH pin driver pullup resistance and the high-side nMOSFET internal gate resistance,

 $V_{MIL} = V_{GS}$  of the high-side nMOSFET that corresponds to  $I_D = I_{CHGMAX}$  on the  $V_{GS}$  vs  $I_D$  curve in the nMOSFET data sheet

Q<sub>rr</sub> = Reverse-recovery charge of low-side nMOSFET(s) body diode

 $C_{OSSHS}$  = Effective output capacitance of the high-side nMOSFET(s)

C<sub>OSSLS</sub> = Effective output capacitance of the low-side nMOSFET(s)

Low-side nMOSFET losses can be estimated using the following formula:

$$P_{LS-MOSFET} = I_{CHG}^{2} \times R_{DS-ON(LS)} \times (1 - D) + 2 \times V_{D} \times I_{CHG} \times t_{DT} \times f_{SW}$$

where:

V<sub>D</sub> = Forward-drop of the low-side nMOSFET(s) body diode

t<sub>DT</sub> = Dead time (30ns)

Take R<sub>DS-ON</sub> variation with respect to temperature into account while calculating the power losses and ensure that the losses of each nMOSFET do not exceed their power rating and operate within a safe junction temperature rating. When parallel nMOSFETs are used, it is recommended to use appropriate independent series gate resistors for each nMOSFET to account for gate charge variation from one nMOSFET to another.

#### **System Considerations**

The MAX17702 is designed to charge Pb-acid batteries. When load current is drawn during the battery charging process, the charging current available for battery charging reduces. This influences the charging time in precharge, CC, and absorption CV states. The timer setting must be adjusted accordingly for intended charging process. If the load current drawn is more than the taper current threshold ( $I_{TCHG}$ ), the charger continues to operate in the absorption CV state until the timer is elapsed. The charger enters floating CV state, after the timer elapses in absorption CV state. If the timer is disabled and the load current is more than  $I_{TCHG}$ , the charger continues to operate in absorption CV state.

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For safe operation, follow the procedure below while making connections:

- 1. Connect the battery terminals to the output of the charger circuit. Note that the output capacitors of the charger can draw current from the battery during a hot plug-in / connection process.
- 2. Connect the input power source to the battery charger circuit only after securely connecting the battery at the output.
- 3. Do not operate the charger without battery.

#### **Device Power Dissipation**

The MAX17702 must dissipate losses due to quiescent-current consumption and the internal gate driver.

If  $V_{CC}$  is powered from  $V_{IN}$ , use the following equation to calculate the approximate IC losses:

$$\mathsf{P}_{\mathsf{MAX17702}} = V_{\mathsf{IN}} \times \left[ \left[ \mathsf{Q}_{G} \times \mathsf{f}_{\mathsf{SW}} \right] + \mathsf{I}_{\mathsf{QNS}} \right]$$

When  $V_{OUT}$  is used to power  $V_{CC}$  by connecting the EXTVCC pin to an output voltage greater than 4.8V, use the following equation to calculate the approximate IC losses:

 $P_{MAX17702}=V_{EXTVCC} \times \left[\left[Q_{G} \times f_{SW}\right] + I_{QNS}\right]$ 

where,

 $Q_G$  = Total gate charge of high-side and low-side nMOSFETs,

I<sub>QNS</sub> = Input Quiescent current (2.1mA)

Calculate the junction temperature using the following equation and ensure that it does not exceed +125°C.

$$T_J = T_{A(MAX)} + (\theta_{JA} \times P_{MAX17702})$$

where,

 $T_J$  = Junction temperature

 $P_{MAX17702}$  = Power loss in the device

 $\theta_{JA}$  = Junction-to-ambient thermal resistance

T<sub>A(MAX)</sub> = Maximum ambient temperature

#### PCB Layout Guidelines

Careful PCB layout is critical to achieve low losses, and low EMI emissions. Use the following guidelines for PCB layout:

- Place ceramic input filter capacitors as close as possible across the drain of the high-side nMOSFET and source of the low-side nMOSFET.
- Route the V<sub>IN</sub> and DCIN traces from input short-circuit protection nMOSFET source and drain terminals as a
  differential pair and connect to V<sub>IN</sub> and DCIN pins of the device. Place V<sub>IN</sub> and DCIN bypass capacitors close to V<sub>IN</sub>
  and DCIN pins respectively.
- Place V<sub>CC</sub> and EXTVCC bypass capacitors and the BST capacitor near the respective pins.
- Place GATEN-to-DCIN bypass capacitor close to the GATEN, DCIN pins of the device.
- Place bootstrap capacitor close to BST, LX pins of the device.
- Route the bootstrap diode connections from V<sub>CC</sub> capacitor and to bootstrap capacitor as short as possible to minimize the loop inductance.
- Route switching traces (BST, LX, DH, and DL) away from sensitive signal traces (RT/SYNC, COMP, CSP, CSN and FB).
- The gate current traces must be short in length. Use multiple vias to route these signals if routed from one layer of the PCB to another layer.
- Route current-sense traces as a differential pair to minimize the loop inductance and avoid differential noise.
- Place the current-sense filter resistor and capacitor near both the CSP and CSN pins.
- Place feedback and compensation components close to the device and connect to the SGND/EP copper area.
- Place all power components on the top side of the board and run the power-stage currents using traces or copper fills on the top side only, without adding vias, wherever possible.
- Keep the power traces and load connections short. Use multilayer, thick copper PCBs (2oz or higher) to enhance

## 4.5V to 60V, Synchronous Step-Down Lead-Acid Battery Charger Controller

efficiency and minimize trace inductance and resistance.

- Allocate a large PGND copper area for the output node, and connect the return terminals of the input filter capacitors, output capacitors, and the source terminals of the low-side nMOSFET(s) to that area.
- Refer to the MAX17702 EV kit data sheet for recommended PCB layout and routing.

# 4.5V to 60V, Synchronous Step-Down Lead-Acid Battery Charger Controller

### **Typical Application Circuits**

#### **10A Pb-Acid Battery Charger**

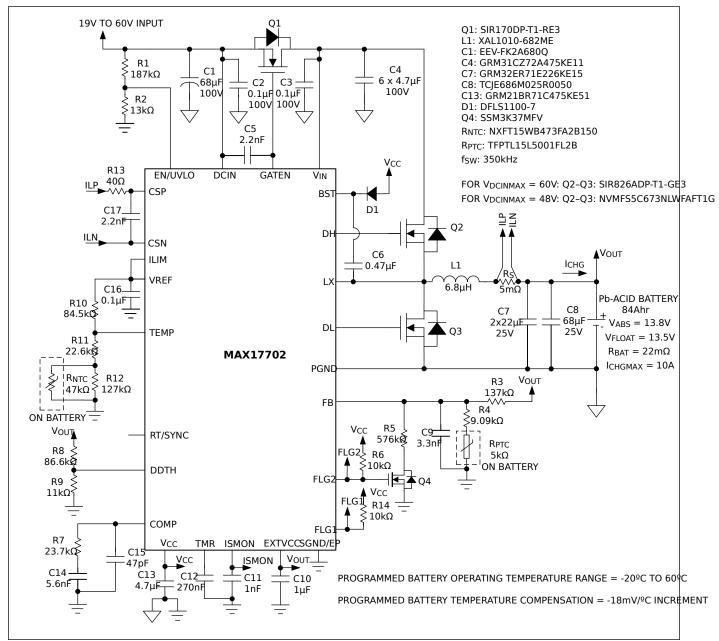


Figure 9. 13.8V/10A Pb-Acid Battery Charger

# 4.5V to 60V, Synchronous Step-Down Lead-Acid Battery Charger Controller

## **Ordering Information**

PART NUMBER	TEMPERATURE RANGE	PIN-PACKAGE	
MAX17702ATG+	-40°C to +125°C	24 TQFN-EP	
MAX17702ATG+T	-40°C to +125°C	24 TQFN-EP	

+ Denotes a lead(Pb)-free/RoHS-compliant package.

T = Tape-and-reel.

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#### **Revision History**

REVISION	REVISION	DESCRIPTION	PAGES
NUMBER	DATE		CHANGED
0	4/21	Release for Market Intro	—

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