

Isolated Flyback Converter IC with Integrated Switching MOSFET

BD7J200HFN-LB BD7J200EFJ-LB

General Description

This is the product guarantees long time support in Industrial market.

This IC is an optocoupler-less isolated flyback converter. It is not necessary to use any optocouplers and feedback circuits by a third winding of transformers; these have been ever required to obtain a stable output voltage in former applications. Furthermore, adoption of the original adapted type technology that controls on time makes the external phase compensation parts unnecessary, reduces a lot of parts number and minimalizes applications, which realizes the designs of isolated power supply application with high reliability.

Features

- Long Time Support Product for Industrial Applications
- No Need of Any Optocoupler and Third Winding of Transformer
- Set Output Voltage with Two External Resistor and Ratio of Transformer Turns
- Adopt of Original Adapted Type Technology that Controls On Time.
- No Need of External Phase Compensation Parts by High-speed Load Response
- Low Output Ripple by Fixed Switching Frequency (At normal operation)
- High Efficient Light Load Mode (At PFM operation)
- Shutdown and Enable Control
- Built-in 120 V Switching MOSFET
- Soft Start Function
- Load Compensation Function
- Various Protection Function

Input Under Voltage Lockout (VIN UVLO)

Over Current Protection (OCP)

Over Voltage Protection (OVP)

Short Circuit Protection (SCP)

Thermal Shutdown (TSD)

Battery Short Protection (BSP)

Key Specifications

Operation Supply Voltage Range VIN Pin:

VIN Pin: 8 V to 80 V SW Pin: 120 V (Max) Over Current Detection Current: 1.75 A (Typ)

Switching Frequency: 400 kHz (Typ)

■ Reference Voltage Accuracy: ±1.5 %
■ Current at Shutdown: 0 µA (Typ)

Operation Current at Switching:
 2.8 mA (Typ)
 Operation Temperature Pages:
 40 °C to 1135 °C

■ Operation Temperature Range: -40 °C to +125 °C

Packages

HSON8 2.9 mn

W (Typ) x D (Typ) x H (Max) 2.9 mm x 3.0 mm x 0.6 mm

(BD7J200HFN-LB)

HTSOP-J8

4.9 mm x 6.0 mm x 1.0 mm

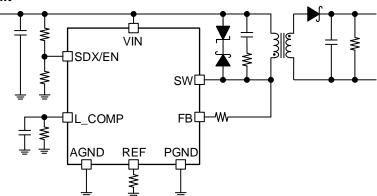
(BD7J200EFJ-LB)



Application

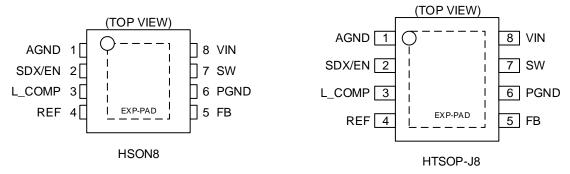
■ Isolated Power Supply for Industrial Equipment

Typical Application Circuit



OProduct structure: Silicon integrated circuit OThis product has no designed protection against radioactive rays.

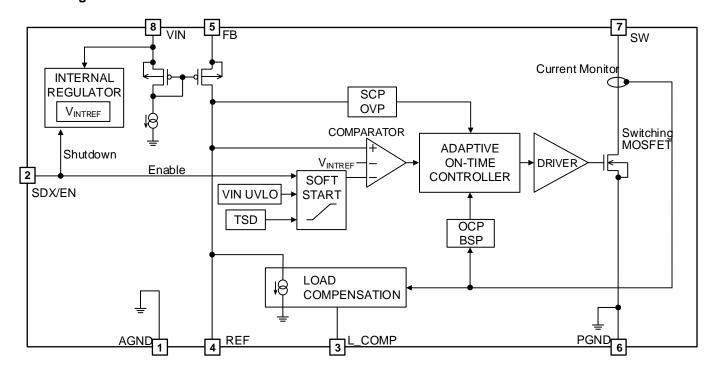
Pin Configurations



Pin Descriptions

Pin No.	Pin Name	Function
1	AGND	Analog system GND pin
2	SDX/EN	Shutdown and enable control pin
3	L_COMP	Setting pin of the load current compensation value
4	REF	Setting pin of the output voltage
5	FB	Setting pin of the output voltage
6	PGND	Power system GND pin
7	SW	Switching output pin
8	VIN	Power supply input pin
-	EXP-PAD	Connect EXP-PAD to both of the AGND and PGND pins

Block Diagram



Description of Blocks

1 INTERNAL REGULATOR

This is the regulator block for internal circuits.

This block also shuts itself down at the shutdown status of the SDX/EN pin voltage ≤ V_{SDX}.

The SDX/EN pin voltage becomes V_{EN1} or more, the IC becomes enable status and the output voltage rises slowly by the soft start function. The SDX/EN pin voltage becomes V_{EN2} or less, the IC becomes disable status and stops the switching operation.

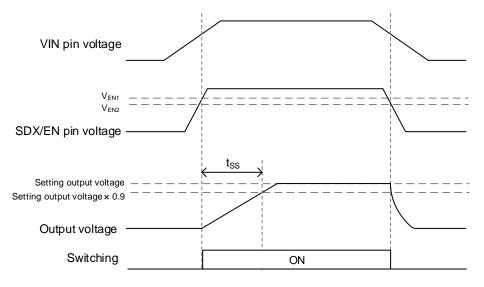


Figure 1. Startup and Stop Timing Chart

In the control method of this IC, it is necessary to operate in the status that the duty is D_{MAX} or less. At the startup and stop, set the VIN pin voltage V_{IN} to meet the next formula.

$$V_{IN} > \frac{N_P}{N_S} \times (V_{OUT} + V_F) \left(\frac{1}{D_{MAX}} - 1\right)$$
 [V]

Where:

 V_{IN} is the VIN pin voltage.

 N_P is the number of winding at the primary transformer.

 N_{S} is the number of winding at the secondary transformer.

 V_{OIIT} is the output voltage.

 $V_{\scriptscriptstyle F}$ is the forward voltage of the secondary output diode.

 D_{MAX} is the maximum duty.

In the case that the SDX/EN pin is shorted to the VIN pin the duty becomes D_{MAX} or more at startup and stop, and there may be occur the output voltage without intending. Refer to <u>Application Examples: 6 Enable Voltage and Disable Voltage</u> for the enable control by the VIN pin.

2 VIN UVLO

This is the input low voltage protection block.

When the VIN pin voltage becomes V_{UVLO1} or less, the IC detects VIN UVLO and stops the switching operation because of the high impedance in the SW pin.

When the VIN pin voltage becomes V_{UVLO2} or more, the IC automatically reset via the soft start.

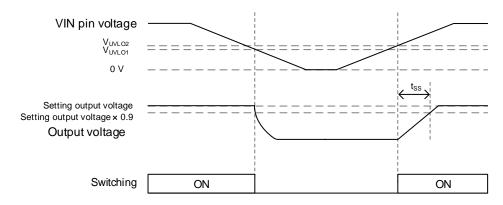


Figure 2. VIN UVLO Timing Chart

3 SOFT START

When the status becomes enable that the SDX/EN pin voltage V_{EN1} or more, the comparison voltage in the comparator block transits slowly 0 V to V_{INTREF} . This operation pretend the IC from rushing current at the rising edge of the output voltage or overshooting. The soft start time is fixed to t_{SS} in the IC.

4 COMPARATOR

In this block, the IC compare the reference voltage to the REF pin voltage that is the feedback voltage of the SW pin voltage. This IC is superior to the response for fluctuation in load because it constitutes the feedback group by the comparator.

5 ADAPTIVE ON TIME CONTROLLER

This block is corresponded to the original adapted type technology that controls on time.

Stable load current: Operates in the PWM control and fix the on time.

Fluctuating load current: Operates in the on time control and realizes a high-speed load response by

fluctuates the switching frequency.

Light load: Decrease the switching frequency and realizes a high efficiency.

When the load current fluctuates, the frequency becomes high. The IC raises the average of primary current by shortening the off time and raises the secondary current.

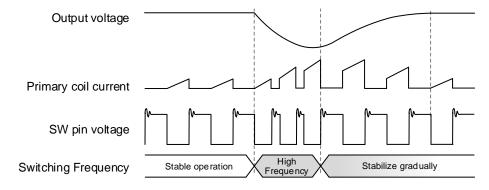


Figure 3. Transient Response Timing Chart

6 DRIVER

This block drives the switching MOSFET.

7 LOAD COMPENSATION

This block compensates the fluctuation of output voltage caused by the fluctuation of V_F characteristic in the secondary output diode corresponded to load current. This block monitors the current flowed to the switching MOSFET and pulls the current corresponded to the quantity of compensation determined by the external resistor and capacitor at the L_COMP pin and time constant from the REF pin. The decline of the REF pin voltage by the drop of feedback current flowing in the external resistor at the REF pin rises the output voltage and it is compensated.

8 OCP, BSP

This is the block of the over current protection and battery short protection.

8.1 OCP (Over Current Protection)

At the switching MOSFET on, the IC detects the OCP when the peak current becomes I_{LIMIT} or more. At this moment, the switching MOSFET is turned off. Because of detecting per switching cycles and restricting on duty, the output voltage drops. In addition, to prevent detection error, the detection of OCP is invalidated for t_{MASK1} after the switching MOSFET is turned on

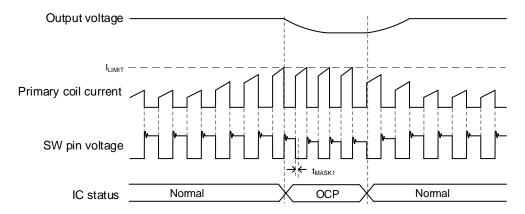


Figure 4. OCP Timing Chart

8.2 BSP (Battery Short Protection)

If the SW pin is connected to high electric potential with low impedance, current flows when the switching MOSFET turned on and it may destroy the IC.

To prevent this, the IC has a built-in BSP. When the SW pin voltage becomes $V_{\rm BSP}$ or more at the switching MOSFET on, the IC detects BSP. At this moment, the switching operation is stopped. After $t_{\rm RESTART}$ from the stop, the IC operates the soft start and resets.

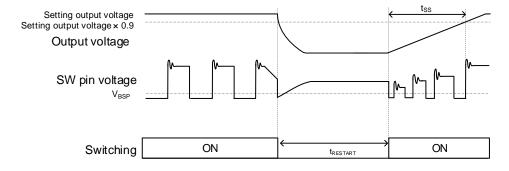


Figure 5. BPS Timing Chart

9 SCP, OVP

This is the block of the short circuit protection and over voltage protection.

9.1 SCP (Short Circuit Protection)

The REF pin obtains the secondary output voltage data from the primary flyback voltage. When the REF pin voltage becomes V_{SCP} or less at the switching MOSFET off, the IC detects SCP. At this moment, the switching operation is stopped. After $t_{RESTART}$ from the stop, the IC operates the soft start and resets.

To prevent detection error, the detection of SCP is invalidated for t_{MASK2} after the switching MOSFET is turned off and for t_{MASK3} at the startup by the soft start.

In the case that the primary flyback voltage is not output correctly, SCP is not detected even if the secondary output voltage drops.

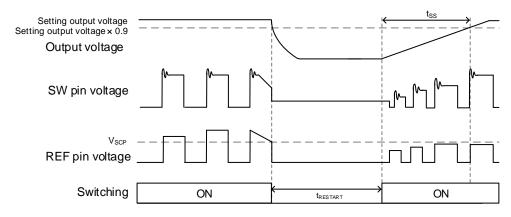


Figure 6. SCP Timing Chart

9.2 OVP (Over Voltage Protection)

The REF pin obtains the secondary output voltage data from the primary flyback voltage. When the REF pin voltage becomes V_{OVP} or more at the switching MOSFET off, the IC detects OVP. At this moment, the switching operation is stopped. After $t_{RESTART}$ from the stop, the IC operates the soft start and resets.

To prevent detection error, the detection of OVP is invalidated for t_{MASK2} after the switching MOSFET is turned off. In the case that the primary flyback voltage is not output correctly, OVP is not detected even if the secondary output voltage rises.

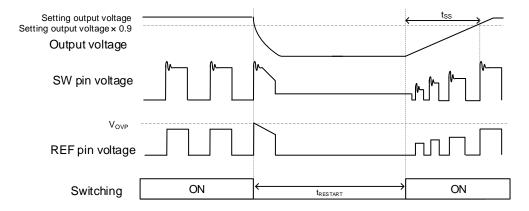


Figure 7. OVP Timing Chart

Absolute Maximum Ratings (Ta = 25 °C)

Parameter	Symbol	Rating	Unit
VIN Pin Voltage	V _{IN_MAX}	100	V
SW Pin Voltage	V_{SW_MAX}	120	V
SDX/EN Pin Voltage	V _{SDX/EN_MAX}	100	V
FB Pin Voltage	V_{FB_MAX}	V _{IN} + 0.3	V
REF Pin Voltage	V _{REF_MAX}	7	V
L_COMP Pin Voltage	$V_{L_COMP_MAX}$	7	V
Maximum Junction Temperature	Tjmax	150	°C
Storage Temperature Range	Tstg	-55 to +150	°C

Caution 1: Operating the IC over the absolute maximum ratings may damage the IC. The damage can either be a short circuit between pins or an open circuit between pins and the internal circuitry. Therefore, it is important to consider circuit protection measures, such as adding a fuse, in case the IC is operated over the absolute maximum ratings.

Caution 2: Should by any chance the maximum junction temperature rating be exceeded the rise in temperature of the chip may result in deterioration of the properties of the chip. In case of exceeding this absolute maximum rating, design a PCB with thermal resistance taken into consideration by increasing board size and copper area so as not to exceed the maximum junction temperature rating.

Thermal Resistance (Note 1)

Doromotor	O. was boat	Thermal Resistance (Typ)		1.1
Parameter	Symbol	1s ^(Note 3)	2s2p ^(Note 4)	– Unit
HSON8				
Junction to Ambient	θ_{JA}	265.1	66.1	°C/W
Junction to Top Characterization Parameter ^(Note 2)	Ψ_{JT}	17	9	°C/W
HTSOP-J8				
Junction to Ambient	θ_{JA}	206.4	45.2	°C/W
Junction to Top Characterization Parameter ^(Note 2)	$\Psi_{ m JT}$	21	13	°C/W

(Note 1) Based on JESD51-2A (Still-Air).

(Note 2) The thermal characterization parameter to report the difference between junction temperature and the temperature at the top center of the outside surface of the component package.
(Note 3) Using a PCB board based on JESD51-3.

(Note 4) Using a PCB board based on JESD51-3.

(Note 1) comig a l'eb beard baced	511 0 L O D O 1 O, 1 .					
Layer Number of Measurement Board	Material	Board Size				
Single	FR-4	114.3 mm x 76.2 mm x	1.57 mmt			
Тор						
Copper Pattern	Thickness					
Footprints and Traces	70 µm					
Layer Number of	Material	Board Size		Thermal \		
Measurement Board	Material			Pitch		Diam
4 Layers	FR-4	114.3 mm x 76.2 mm x 1.6 mmt		1.20 mm	Ф	0.30
Тор		2 Internal Laye	ers	Botto	om	
Copper Pattern	Thickness	Copper Pattern	Thickness	Copper Pattern	า	Th

74.2 mm x 74.2 mm

(Note 5) This thermal via connects with the copper pattern of all layers.

70 µm

Recommended Operating Conditions

Footprints and Traces

Parameter	Symbol	Min	Тур	Max	Unit	Conditions	
Operation Power Supply Voltage Range 1	V _{IN}	8	48	80	V	The VIN pin voltage	
Operation Power Supply Voltage Range 2	V _{SW}	-	-	110	V	The SW pin voltage	
Operation Power Supply Voltage Range 3	V _{L_COMP_MAX2}	-	-	0.5	V	The L_COMP voltage	pin
Operation Temperature	Topr	-40	-	+125	°C		

35 µm

74.2 mm x 74.2 mm

Diameter Φ0.30 mm

Thickness

70 µm

Electrical Characteristics

(Unless otherwise specified V_{IN} = 48 V, $V_{SDX/EN}$ = 2.5 V, Ta = 25 °C)

Parameter Symbol Min Typ Max Unit Conditions
Current at Shutdown
Current at Switching Operation Icc - 2.8 6.0 mA VREF = 0.85 V (At PFI operation) UVLO Detection Voltage 1 VuvLo1 4.1 5.0 6.0 V At V _N faling UVLO Detection Voltage 2 VuVLo2 - 5.2 - V At V _N faling UVLO Voltage Hysteresis VuVLO2 - No. 5.2 - V At V _N faling Shutdown And Enable Control Block Shutdown Voltage VSDX - - 0.3 V Enable Voltage 1 VEN. 1.7 2.0 2.3 V At V _{SDX/EN} fising Enable Voltage 2 VEN. 1.7 2.0 2.3 V At V _{SDX/EN} fising Enable Voltage 2 VEN. - 1.8 - V At V _{SDX/EN} falling Enable Voltage 3 VEN. - 1.8 - V At V _{SDX/EN} falling Enable Voltage 4 VEN. - 5.3 - V At V _{SDX/EN} falling SDX/EN Pin Inflow Current Isox Pin Inflow Current RSDX/EN Pin Pull-down Resistance 1 RSDX/EN Pin Pull-down Resi
Current at Switching Operation Icc - 2.8 6.0 mA Operation Ope
UVLO Detection Voltage 2 VUVLO - 5.2 - V At V rising VUVLO Voltage Hysteresis VUVLO VOLTAGE
UVLO Voltage Hysteresis ViDVLO_HYS 0.1 0.2 0.3 V Shutdown and Enable Control Block
Shutdown and Enable Control Block Shutdown Voltage V_SDX - - 0.3 V Enable Voltage 1 V_EN1 1.7 2.0 2.3 V At V_SDX/EN rising Enable Voltage 2 V_EN2 - 1.8 - V At V_SDX/EN falling Enable Voltage Hysteresis V_EN_HYS 0.1 0.2 0.3 V SDX/EN Pin Inflow Current I_SDX/EN 1.6 2.5 3.9 µA SDX/EN Pin Clamp Voltage V_CLPEN - 5.3 - V SDX/EN Pin Pull-down Resistance 1 R_SDX/EN - 815 - kΩ SDX/EN Pin Pull-down Resistance 2 R_SDX/EN - 190 - kΩ SDX/EN Pin Pull-down Resistance 2 R_SDX/EN - 190 - kΩ SDX/EN Pin Pull-down Resistance 2 R_SDX/EN - 190 - kΩ SDX/EN Pin Pull-down Resistance 2 R_SDX/EN - 190 - µA SWITCHING Block SWITCHING BLO
Shutdown Voltage
Enable Voltage 1
Enable Voltage 2
Enable Voltage Hysteresis Ven_Hys 0.1 0.2 0.3 V SDX/EN Pin Inflow Current Isdx 1.6 2.5 3.9 μA SDX/EN Pin Clamp Voltage Vcl_PEN - 5.3 - V SDX/EN Pin Pull-down Resistance 1 Rsdx - 815 - kΩ SDX/EN Pin Pull-down Resistance 2 Rsdx - 190 - kΩ SDX/EN Pin Pull-down Resistance 2 Rsdx - 190 - kΩ SDX/EN Pin Pull-down Resistance 2 Rsdx - 190 - kΩ SDX/EN Pin Pull-down Resistance 2 Rsdx - 190 - kΩ SDX/EN Pin Pull-down Resistance 2 Rsdx - 190 - kΩ SDX/EN Pin Pull-down Resistance 2 Reference Voltage Vintref 0.768 0.780 0.792 V REF Pin Current Iref - 390 - μA SWitching Block SWitching Block SWitching Block SWitching Block SWitching Frequency Iref 1.40 1.75 2.10 A SWitching Frequency Iref 1.40 1.75 2.10 A SWitching Frequency Iref 1.40 1.75 2.10 A SWitching Frequency Iref 1.40 1.25 μs At PWM operation (Duty 40 %) On Time Iref 1.40 1.25 μs At PWM operation (Duty 40 %) Minimum On Time Iref 1.40 335 450 565 ns Maximum Off Time Iref 1.40 1.4
SDX/EN Pin Inflow Current I_SDX/EN 1.6 2.5 3.9 μA SDX/EN Pin Clamp Voltage V_CLPEN - 5.3 - V SDX/EN Pin Pull-down Resistance 1 R_SDX/EN - 815 - KΩ SDX/EN Pin Pull-down Resistance 2 R_SDX/EN2 - 190 - KΩ SDX/EN Pin Pull-down Resistance 2 R_SDX/EN2 - 190 - KΩ SDX/EN Pin Pull-down Resistance 2 R_SDX/EN2 - 190 - KΩ SDX/EN Pin Pull-down Resistance 2 R_SDX/EN2 - 190 - KΩ SDX/EN Pin Pull-down Resistance 2 R_SDX/EN2 - 190 - KΩ SDX/EN Pin Pull-down Resistance 2 R_SDX/EN2 - 190 - Fin Pull-down Resistance 2 R_SDX/EN2 - 190 - Fin Pull-down Resistance 2 R_SDX/EN2 - 190 - Fin Pull-down Resistance 3 R_SDX/EN2 - 190 - Fin Pull-down Resistance 2 R_SD
SDX/EN Pin Clamp Voltage Voltage Voltage SDX/EN Pin Pull-down Resistance 1 Restriction Pull-down Resistance 2 Reference Voltage Block
SDX/EN Pin Pull-down Resistance 1 R_SDX/EN1 - 815 - kΩ
SDX/EN Pin Pull-down Resistance 2 R_SDX/EN2 - 190 - kΩ
Reference Voltage Vintref 0.768 0.780 0.792 V REF Pin Current I_REF - 390 - μA Switching Block
Reference Voltage VINTREF 0.768 0.780 0.792 V
REF Pin Current I_{REF} - 390 - μA Switching Block On Resistance RoN 0.25 0.50 1.00 Ω Between the SW and PGN pins Over Current Detection Current I_{LIMIT} 1.40 1.75 2.10 A Switching Frequency f_{SW} - 400 - kHz At PWM operation (Duty 40 %) On Time t_{ON} 0.75 1.00 1.25 μs At PWM operation (Duty 40 %) Minimum On Time t_{ON_MIN} 260 350 440 ns Minimum Off Time t_{OFF_MIN} 335 450 565 ns Maximum Off Time t_{OFF_MAX} 14 20 26 μs Soft Start Time t_{SS} 1.2 2.5 5.0 ms From rise-up to $V_{REF} \times 90 \%$
Switching Block RoN 0.25 0.50 1.00 Ω Between the SW and PGN pins
On Resistance R_{ON} 0.25 0.50 1.00 Ω Between the SW and PGN pins Over Current Detection Current I_{LIMIT} 1.40 1.75 2.10 A Switching Frequency f_{SW} - 400 - kHz At PWM operation (Duty 40 %) On Time t_{ON} 0.75 1.00 1.25 μ s At PWM operation (Duty 40 %) Minimum On Time t_{ON_MIN} 260 350 440 ns Minimum Off Time t_{OFF_MIN} 335 450 565 ns Maximum Off Time t_{OFF_MAX} 14 20 26 μ s Soft Start Time t_{SS} 1.2 2.5 5.0 ms From rise-up to V_{REF} x 90 %
On Resistance Ron 0.25 0.50 1.00 Ω pins Over Current Detection Current I _{LIMIT} 1.40 1.75 2.10 A Switching Frequency f _{SW} - 400 - kHz At PWM operation (Duty 40 %) On Time t _{ON} 0.75 1.00 1.25 μs At PWM operation (Duty 40 %) Minimum On Time t _{ON_MIN} 260 350 440 ns Minimum Off Time t _{OFF_MIN} 335 450 565 ns Maximum Off Time t _{OFF_MAX} 14 20 26 μs Soft Start Time t _{SS} 1.2 2.5 5.0 ms From rise-up to V _{REF} x 90 %
Switching Frequency $ \begin{array}{c ccccccccccccccccccccccccccccccccccc$
Switching Frequency Tsw - 400 - KHZ 40 %)
Minimum On Time toN Minimum On Time toN_MIN 260 350 440 ns Minimum Off Time toFF_MIN 335 450 565 ns Maximum Off Time toFF_MAX 14 20 26 μs Soft Start Time tss 1.2 2.5 5.0 ms From rise-up to V _{REF} x 90 %
Minimum Off Time t _{OFF_MIN} 335 450 565 ns Maximum Off Time t _{OFF_MAX} 14 20 26 μs Soft Start Time t _{SS} 1.2 2.5 5.0 ms From rise-up to V _{REF} x 90 %
Maximum Off Time $ \begin{array}{c ccccc} & t_{OFF_MAX} & 14 & 20 & 26 & \mu s \\ \hline Soft Start Time & t_{SS} & 1.2 & 2.5 & 5.0 & ms & From rise-up to V_{REF} \times 90 \% \\ \hline \end{array} $
Soft Start Time t _{SS} 1.2 2.5 5.0 ms From rise-up to V _{REF} x 90 %
Maximum Duty D _{MAX} - 50 - %
Minimum Duty
Protection Function Block
Short Protection Detection Voltage V _{SCP} - 0.50 - V
Over Voltage Protection Detection Voltage V _{OVP} - 0.95 - V
Battery Short Protection Detection Voltage V _{BSP} - 2.0 - V
Restart Time t _{RESTART} - 2.0 - ms
Over Current Protection Mask Time t _{MASK1} - 280 - ns
Short and Over Voltage Protection Mask Time t _{MASK2} - 400 - ns
Short Protection Mask Time at Startup t _{MASK3} - 600 - µs
Load Compensation Block
Internal Resistor at L_COMP Pin R _{INTCOMP} - 50 - kΩ
Compressor Magnification K - 0.004 - %

Typical Performance Curves

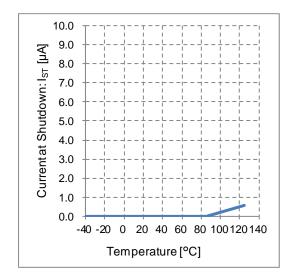


Figure 8. Current at Shutdown vs Temperature

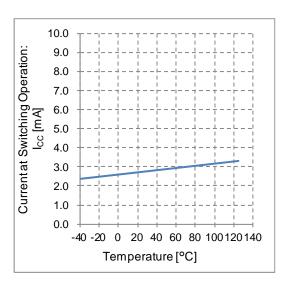


Figure 9. Current at Switching Operation vs Temperature

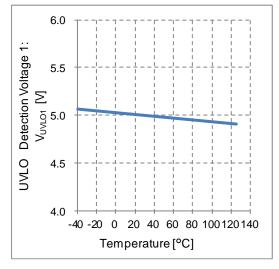


Figure 10. UVLO Detection Voltage 1 vs Temperature

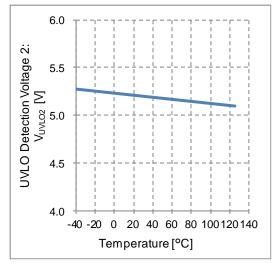


Figure 11. UVLO Detection Voltage 2 vs Temperature

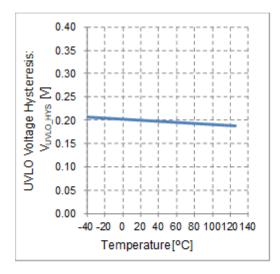


Figure 12. UVLO Voltage Hysteresis vs Temperature

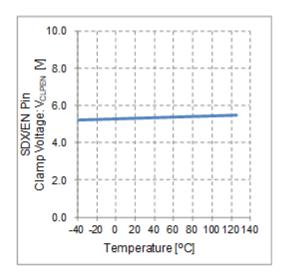


Figure 13. SDX/EN Pin Clamp Voltage vs Temperature

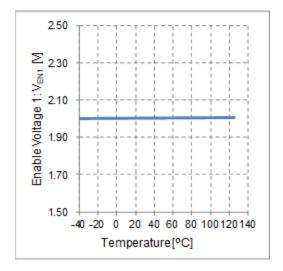


Figure 14. Enable Voltage 1 vs Temperature

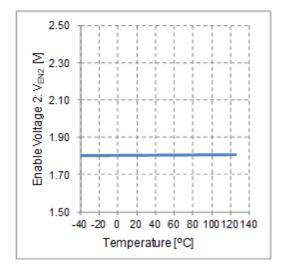


Figure 15. Enable Voltage 2 vs Temperature

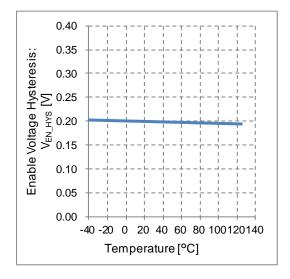


Figure 16. Enable Voltage Hysteresis vs Temperature

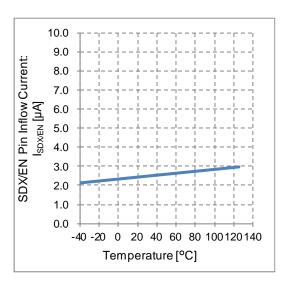


Figure 17. SDX/EN Pin Inflow Current vs Temperature

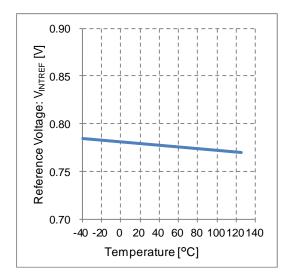


Figure 18. Reference Voltage vs Temperature

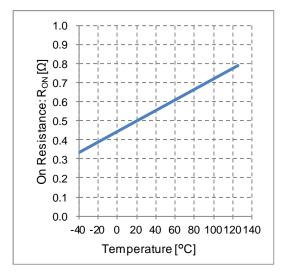


Figure 19. On Resistance vs Temperature

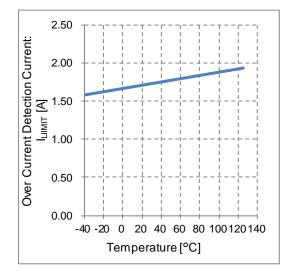


Figure 20. Over Current Detection Current vs Temperature

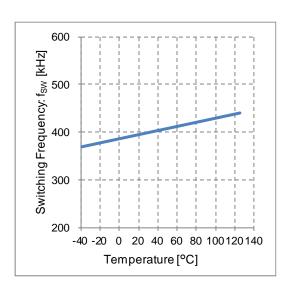


Figure 21. Switching Frequency vs Temperature

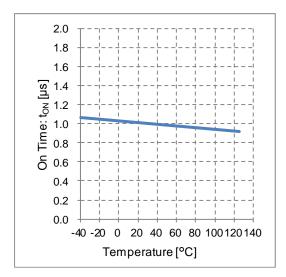


Figure 22. On Time vs Temperature

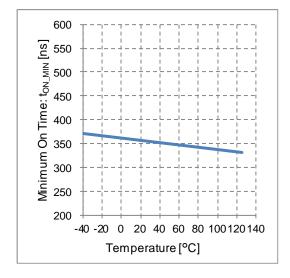


Figure 23. Minimum On Time vs Temperature

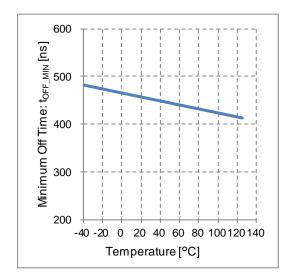


Figure 24. Minimum Off Time vs Temperature

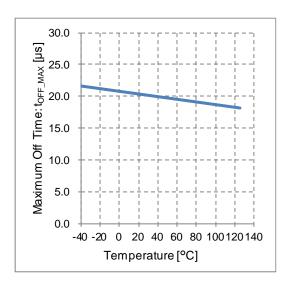


Figure 25. Maximum Off Time vs Temperature

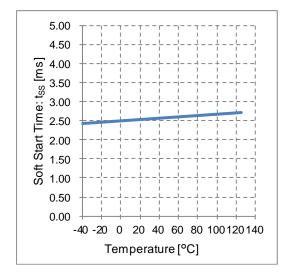


Figure 26. Soft Start Time vs Temperature

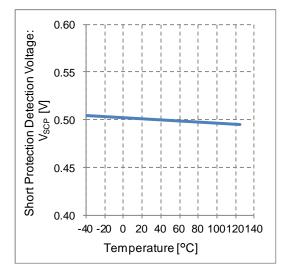


Figure 27. Short Protection Detection Voltage vs Temperature

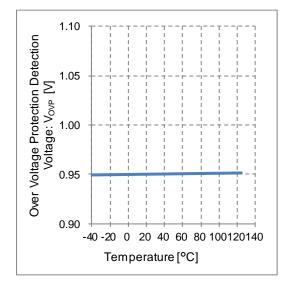


Figure 28. Over Voltage Protection Detection Voltage vs Temperature

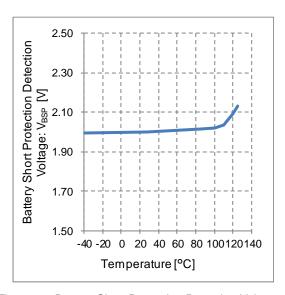


Figure 29. Battery Short Protection Detection Voltage vs Temperature

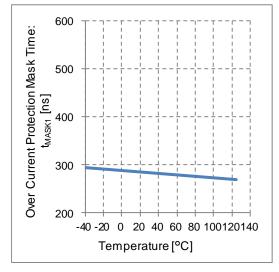


Figure 30. Over Current Protection Mask Time vs Temperature

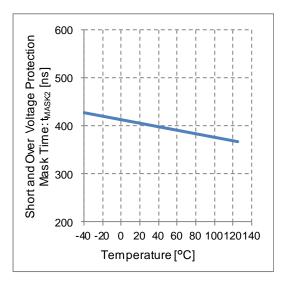


Figure 31. Short and Over Voltage Protection Mask Time vs Temperature

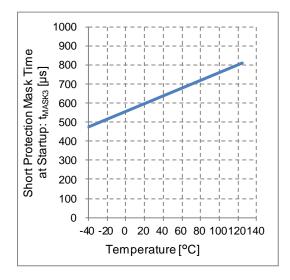


Figure 32. Short Protection Mask Time at Startup vs Temperature

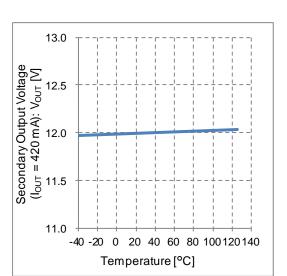


Figure 34. Secondary Output Voltage vs Temperature (I_{OUT} = 420 mA)

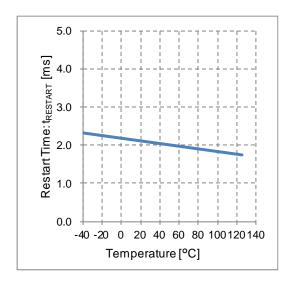


Figure 33. Restart Time vs Temperature

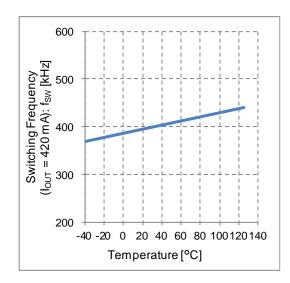


Figure 35. Switching Frequency vs Temperature (I_{OUT} = 420 mA)

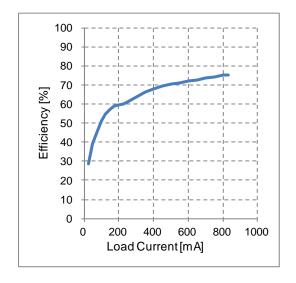


Figure 36. Efficiency vs Load Current

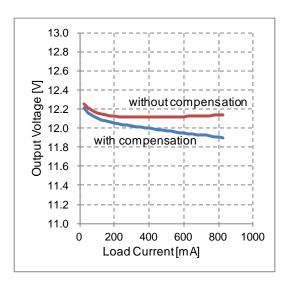


Figure 37. Output Voltage vs Load Current

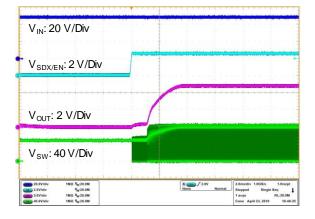


Figure 38. Startup Waveform (The SDX/EN Pin Control)

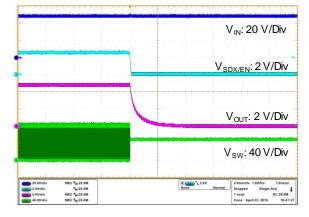


Figure 39. Shutdown Waveform (The SDX/EN Pin Control)

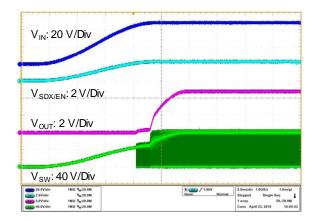


Figure 40. Startup Waveform (The VIN Pin Control)

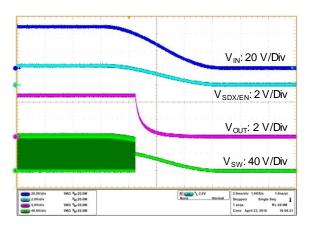


Figure 41. Shutdown Waveform (The VIN Pin Control)

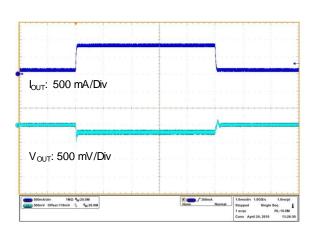


Figure 42. Load Transient Response (I_{OUT} = 0.1 A to 0.83 A)

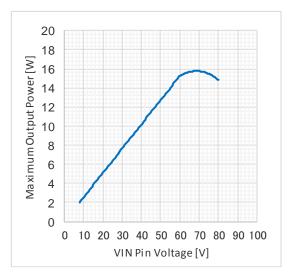


Figure 43. Maximum Output Power vs VIN Pin Voltage

Application Examples

1 Output Voltage

When the internal switching MOSFET is off, the SW pin voltage becomes higher than the VIN pin voltage. The secondary output voltage is calculated by the primary flyback voltage, which is described by the difference between this SW pin voltage and VIN pin voltage. The SW pin voltage at turn off is calculated by the formula below.

$$V_{SW} = V_{IN} + \frac{N_P}{N_S} \times (V_{OUT} + V_F + I_S \times ESR)$$
 [V]

Where:

 V_{SW} is the SW pin voltage.

 V_{IN} is the VIN pin voltage.

 N_P is the number of winding at the primary transformer.

 N_S is the number of winding at the secondary transformer.

 V_{OUT} is the output voltage.

 V_F is the forward voltage of the secondary output diode.

 I_S is the secondary transformer current.

ESR is the secondary total impedance (secondary transformer winding resistance and board).

The external resistor R_{FB} between the FB and SW pins converts the primary flyback voltage into the FB pin inflow current I_{RFB} . The FB pin inflow current I_{RFB} is calculated by the formula below because the FB pin voltage is nearly equal to the VIN pin voltage by the IC's internal circuit.

$$I_{RFB} = \frac{V_{SW} - V_{FB}}{R_{FB}}$$

$$= \frac{V_{IN} + \frac{N_P}{N_S} \times (V_{OUT} + V_F + I_S \times ESR) - V_{FB}}{R_{FB}}$$

$$= \frac{\frac{N_P}{N_S} \times (V_{OUT} + V_F + I_S \times ESR)}{R_{FB}}$$
[A]

Where:

 I_{RFB} is the FB pin inflow current.

 $V_{FB}\,$ is the FB pin voltage.

 R_{FB} is the external resistor between the FB and SW pins.

Furthermore, the REF pin voltage is calculated by the formula below because the FB pin inflow current flows into the external resistor R_{REF} between the REF and AGND pins.

$$V_{REF} = \frac{R_{REF}}{R_{FB}} \times \frac{N_P}{N_S} \times (V_{OUT} + V_F + I_S \times ESR) \quad [V]$$

Where

 V_{REF} is the REF pin voltage.

 R_{REF} is the external resistor between the REF and AGND pins.

The resistor R_{REF} is necessary to be set as the current flowing in the REF pin becomes I_{REF} when the REF pin voltage is equal to V_{INTREF} . This IC's internal circuit is designed as $R_{REF} = 2 \text{ k}\Omega$ according to the formula below.

$$R_{REF} = \frac{V_{INTREF}}{I_{REF}} \qquad [\Omega]$$

Where:

 V_{INTREF} is the REF pin voltage.

1 Output Voltage - continued

The REF pin voltage is input to the comparator with the reference voltage in the IC. By the internal circuit, the REF pin voltage becomes equal to the reference voltage. Therefore, the output voltage and the REF pin voltage is calculated by the formula below.

$$V_{OUT} = \frac{R_{FB}}{R_{REF}} \times \frac{N_S}{N_P} \times V_{REF} - V_F - I_S \times ESR \qquad [V]$$

The output voltage is set by the number of winding ratio of the primary and secondary transformer and the resistance ratio of R_{FB} and R_{REF} . In addition, V_F and ESR is factor of the error in the output voltage. According to the relational expression in above, the external resistor between the FB and SW pins R_{FB} is calculated by the formula below.

$$R_{FB} = \frac{R_{REF}}{V_{REF}} \times \frac{N_P}{N_S} \times (V_{OUT} + V_F + I_S \times ESR) \quad [\Omega]$$

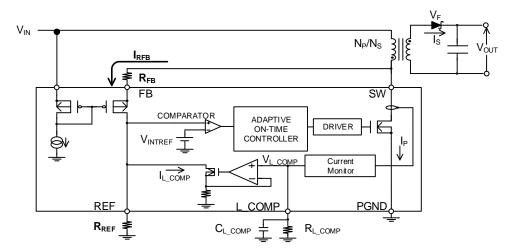


Figure 44. Control Block Diagram

2 Transformer

2.1 Number of Winding Ratio

The number of winding ration is the parameter with which the output voltage, maximum output electric power, duty and the SW pin voltage is set.

The duty of flyback converter is calculated by the formula below.

$$Duty = \frac{\frac{N_P}{N_S} \times (V_{OUT} + V_F)}{V_{IN} + \frac{N_P}{N_S} \times (V_{OUT} + V_F)}$$
 [%]

Where.

 N_P is the number of winding at the primary transformer.

 $N_{S}\,$ is the number of winding at the secondary transformer.

 V_{OUT} is the output voltage.

 V_F is the forward voltage of the secondary output diode.

 V_{IN} is the VIN pin voltage.

The feedback voltage is monitored at the SW pin. In addition, it is necessary to set the duty to D_{MAX} or less for the stable control. By the restriction of the minimum on time, the minimum duty is determined to D_{MIN} and the number of winding ratio has to meet the requirements below.

$$\frac{D_{MIN}}{1 - D_{MIN}} \times \frac{V_{IN}}{V_{OUT} + V_F} < \frac{N_P}{N_S} < \frac{V_{IN}}{V_{OUT} + V_F}$$

Where.

 D_{MIN} is the minimum duty.

2 Transformer – continued

2.2 Primary Inductance

The right half plane zero point occurs in the feedback group of flyback converter. The phase delays 90 ° by this, it is necessary to set the right half plane zero frequency f_{RHP_ZERO} to the switching frequency f_{SW} or less. The right half plane zero frequency f_{RHP_ZERO} is calculated by the formula below.

$$f_{RHP_ZERO} = \frac{\left(\frac{N_P}{N_S}\right)^2 \times \left\{\frac{V_{IN}}{V_{IN} + \frac{N_P}{N_S} \times (V_{OUT} + V_F)}\right\}^2 \times R_{OUT}}{2\pi \times \frac{\frac{N_P}{N_S} \times (V_{OUT} + V_F)}{V_{IN} + \frac{N_P}{N_S} \times (V_{OUT} + V_F)} \times L_P}$$
[Hz]

Where:

 $f_{RHP\ ZERO}$ is the right half plane zero frequency.

 N_P is the number of winding at the primary transformer.

 N_S is the number of winding at the secondary transformer.

 V_{IN} is the VIN pin voltage.

 V_{OUT} is the output voltage.

 $V_F\,$ is the forward voltage of the secondary output diode.

 $R_{OUT}\,$ is the load resistance.

 L_n is the primary inductance.

For the insurance of stability, the right half plane zero frequency f_{RHP_ZERO} has to be set to more than one quarter of the switching frequency f_{SW} . From this, the condition below is required.

$$f_{RHP_ZERO} > \frac{1}{4} \times f_{SW}$$

$$L_p < \frac{2 \times Duty \times {V_{IN}}^2}{(V_{OUT} + V_F) \times I_{OUT_MAX} \times \pi \times f_{SW}}$$
 [H]

Where:

 f_{SW} is the switching frequency.

 $I_{OUT\ MAX}$ is the maximum value of the output current.

2.2 Primary Inductance - continued

The minimum value of primary inductance can be found by the relation of in/output electric power. If the L_P becomes lower, the peak current of primary transformer becomes higher. Because the necessary output voltage cannot be obtained if the peak current value becomes the over current detection current or more, the lower limit of necessary primary inductance value corresponding to maximum load is calculated by the conditional expression below.

$$L_{p} > \frac{1}{2} \times \frac{{V_{IN}}^{2} \times t_{S} \times Duty^{2} \times \eta}{I_{LIMIT_MIN} \times Duty \times V_{IN} \times \eta - V_{OUT_MAX} \times I_{OUT_MAX}}$$
 [H]

Where:

 $t_{\rm S}$ is the cycle of switching.

 η is the efficiency.

 $I_{LIMIT\ MIN}$ is the minimum value of over current detection current.

 $V_{OUT\ MAX}$ is the maximum value of output voltage.

According to the above, the primary inductance is necessary to meet the requirements below.

$$\frac{1}{2} \times \frac{{V_{IN}}^2 \times t_S \times Duty^2 \times \eta}{I_{LIMIT_MIN} \times Duty \times V_{IN} \times \eta - V_{OUT_MAX} \times I_{OUT_MAX}}$$

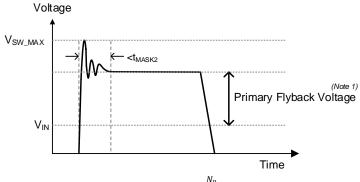
$$< L_p < \frac{2 \times Duty \times {V_{IN}}^2}{(V_{OUT} + V_F) \times I_{OUT_MAX} \times \pi \times f_{SW}}$$
 [H]

2 Transformer - continued

2.3 Leak Inductance

The leak inductance of transformer causes the ringing at the SW pin at the moment the internal switching MOSFET is turned off. Insert the snubber circuit not to exceed the absolute maximum rating of the SW pin voltage. It is necessary to settle down within t_{MASK2} for the prevention of the error in the secondary output voltage.

In addition, it is important to consider that it is not exceeded the rating voltage of secondary output diode at the moment the internal switching MOSFET is turned on.



(Note 1) Primary Flyback Voltage = $\frac{N_P}{N_S} \times (V_{OUT} + V_F + I_S \times ESR)$

Figure 45. Leak Inductance

2.4 Winding Resistance

The primary winding resistance lowers the efficiency of electricity and the secondary winding resistance lowers the output voltage as well as it. According to them, it is recommended to use the small winding resistance transformer.

2.5 Saturated Current

Because the core of transformer saturates if the primary transformer current exceeds the rating saturated current, the energy does not transmit to the secondary side. The primary transformer current increases rapidly because the inductance value drops if the core saturates. Set the primary transformer current to less than the rating saturated current.

3 Output Capacitor

It is necessary to select the proper secondary output capacitor for the stable operation. Refer to the indication of the capacitor and select the appropriate capacitor.

$$C_{OUT} = 1.6 \times 10^{-9} \times \frac{1}{L_P} \times \left(\frac{N_P}{N_S} \times Duty\right)^2$$
 [F]

Where:

 C_{OUT} is the value of output capacitor.

 L_P is the primary inductance.

 N_P is the number of winding at the primary transformer.

 N_{S} is the number of winding at the secondary transformer.

In addition, it is necessary to rise up within t_{SS} for the secondary output voltage. Therefore, also consider the condition below to select the output capacitor. The startup error may occur because the over current protection operates by the plunging current at startup if the capacitor value is extremely large.

$$C_{OUT} \leq \frac{1}{2} \times \frac{t_{SS} \times \left\{ \left(I_{LIMIT_MIN} \times \frac{N_P}{N_S} \right) \times (1 - Duty) - I_{OUT_MAX} \right\}}{V_{OUT}} \quad [F]$$

Where:

 t_{SS} is the soft start time.

 $I_{LIMIT\ MIN}$ is the minimum value of over current detection current.

 $I_{OUT\ MAX}$ is the maximum value of output current.

 V_{OUT} is the output voltage.

4 Input Capacitor

Use the ceramic capacitor for the input capacitor and locate the input capacitor as near as possible to the VIN pin. The pattern of board and location of capacitor may occur the errors.

It is necessary to set the value of input capacitor so that the ripple voltage of the VIN pin becomes 4 % or less of the VIN pin voltage. Also, consider in the load fluctuation and startup.

5 Secondary Output Diode

It is recommended to use the schottky barrier diode whose forward voltage of the secondary output diode V_F is small because the V_F becomes the factor of error in the output voltage. Select the secondary output diode so that the forward current does not exceed the rating. The reverse voltage occurring at the secondary output diode V_R is calculated by the next formula when the internal switching MOSFET is on.

$$V_R = V_{IN} \times \frac{N_S}{N_P} + V_{OUT}$$
 [V]

Where:

 V_R is the reverse voltage at the secondary output diode.

 V_{IN} is the VIN pin voltage.

 N_P is the number of winding at the primary transformer.

 $N_{\rm S}$ is the number of winding at the secondary transformer.

 V_{OIIT} is the output voltage.

Furthermore, the ringing piles up the reverse voltage at the secondary output diode V_R at the moment the internal switching MOSFET is turned on. Set the peak voltage of V_R to less than the rating of secondary output diode.

6 Enable Voltage and Disable Voltage

This IC becomes shutdown status when the SDX/EN pin voltage becomes V_{SDX} or less. At the rise-up of the SDX/EN pin voltage, the IC becomes enable status when the voltage becomes V_{EN1} or more and starts the operation. At the fall, the IC becomes disable status when the voltage becomes V_{EN2} or less.

Shown as Figure 45, the SDX/EN pin realizes the enable control with the VIN pin by connecting the circuit divided by the resistor R₁ and R₂ between the VIN and AGND pins to the SDX/EN pin.

Remind that the internal clamp element turned on and the inflow current occurs if the SDX/EN pin voltage becomes V_{CLPEN} or more.

6.1 Enable Voltage

The enable voltage at the rise-up of the VIN pin voltage V_{IN_ENABLE} is calculated by the formula below.

$$V_{IN_ENABLE} = V_{EN1} \times \frac{R_1 \times (R_2 + R_{SDX/EN1}) + R_2 \times R_{SDX/EN1}}{R_2 \times R_{SDX/EN1}}$$
[V]

Where:

 V_{IN_ENABLE} is the enable voltage at the rise-up of the VIN pin voltage.

 V_{EN1} is the enable voltage 1.

6.2 Disable Voltage

The disable voltage at the fall of the VIN pin voltage V_{IN_DISABLE} is calculated by the formula below.

$$V_{IN_DISABLE} = V_{EN2} \times \frac{R_1 \times (R_2 + R_{SDX/EN1} + R_{SDX/EN2}) + R_2 \times (R_{SDX/EN1} + R_{SDX/EN2})}{R_2 \times (R_{SDX/EN1} + R_{SDX/EN2})}$$
[V]

 $V_{IN\ DISABLE}$ is the disable voltage at the fall of the VIN pin voltage.

 V_{EN2} is the enable voltage 2.

It is necessary to set the duty to D_{MAX} or less and operate in this IC's control method. So set the disable voltage at the fall of the VIN pin voltage $V_{IN_DISABLE}$ to meet the condition below.

$$V_{IN_DISABLE} > \frac{N_P}{N_S} \times (V_{OUT} + V_F)$$
 [V]

Where:

 N_P is the number of winding at the primary transformer.

 N_{S} is the number of winding at the secondary transformer.

 V_{OUT} is the output voltage.

 V_F is the forward voltage at the secondary output diode.

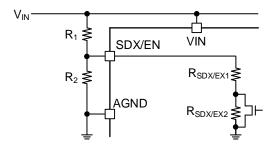


Figure 46. Position of Resistors Connected to the SDX/EN Pin

Minimum Load Current

This IC stables the secondary output voltage isolated with the transformer by the primary flyback voltage at the internal switching MOSFET turned off. Therefore, it operates with the minimum on time t_{ON_MIN} and maximum off time t_{OFF_MAX} even if the status is light load. By this operation, the output voltage may rise in the case of the low load current because a little energy is supplied to the secondary output. To prevent the rise of output voltage, secure the minimum load current with adding such as the dummy resistor R_{DUMMY} .

The necessary minimum load current I_{OUT MIN} is calculated by the formula below.

$$I_{OUT_MIN} = \frac{1}{2} \times \frac{\left(V_{IN} \times t_{ON_MIN}\right)^2}{L_P \times V_{OUT} \times \left(t_{ON_MIN} + t_{OFF_MAX}\right)}$$
[A]

Where:

 $I_{OUT\ MIN}$ is the minimum output current.

 V_{IN} is the VIN pin voltage.

 $t_{\mathit{ON_MIN}}$ is the minimum on time.

 L_P is the primary inductance.

 V_{OUT} is the output voltage.

 $t_{\mathit{OFF}\ \mathit{MAX}}$ is the maximum off time.

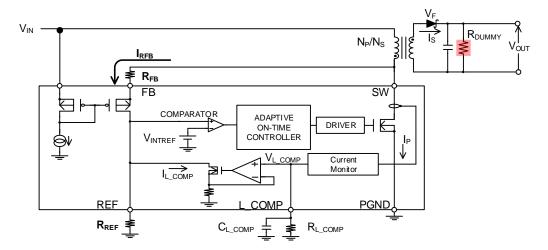


Figure 47. Position of R_{DUMMY}

8 Infection Point of Switching Frequency

This IC realizes the efficiency by fluctuating the switching frequency corresponding to the load current at light load. The load current l_{OUT} f_{SW}, from which the switching frequency f_{SW} starts to drop, is calculated by the formula below.

$$I_{OUT_}f_{SW} = \frac{1}{2} \times \frac{f_{SW} \times (V_{IN} \times t_{ON_MIN})^2}{L_P \times V_{OUT}}$$
[A]

Where:

 $I_{OUT} \; f_{SW} \;$ is the load current, from which the switching frequency starts to drop.

 f_{SW} is the switching frequency.

 V_{IN} is the VIN pin voltage.

 $t_{\it ON~MIN}$ is the minimum on time.

 L_P is the primary inductance.

 V_{OUT} is the output voltage.

In addition, the switching frequency becomes the minimum switching frequency f_{SW_MIN} at the switching operation with the minimum on time t_{ON_MIN} and maximum off time t_{OFF_MAX} and it is calculated by the formula below.

$$f_{SW_MIN} = \frac{1}{t_{ON\ MIN} + t_{OFF\ MAX}}$$
 [Hz]

Where:

 $f_{SW\ MIN}$ is the minimum switching frequency.

 $t_{\mathit{OFF}\ \mathit{MAX}}$ is the maximum off time.

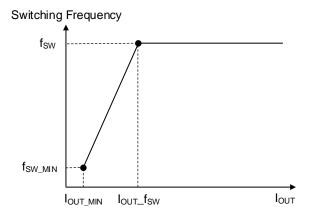


Figure 48. Switching Frequency vs I_{OUT}

9 Load Compensation Function

The load regulation is worsen by V_F and ESR. In the application gotten worse by these factors, it is enable to make the fluctuation of the output voltage caused by the load current alteration small by using the load compensation function.

In addition to above, short the L_COMP pin to the GND to invalidate this function.

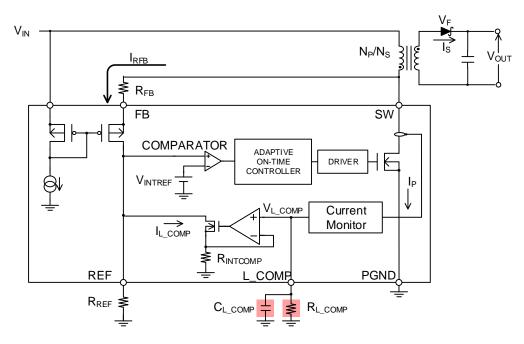


Figure 49. Block Diagram of Load Compensation

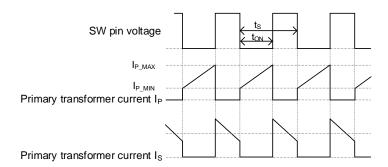


Figure 50. Switching Operation or Continuous Mode

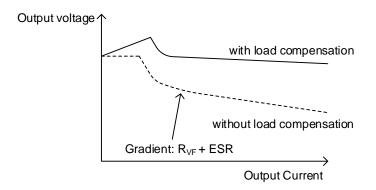


Figure 51. Image of Load Compensation

9 Load Compensation Function - continued

9.1 Setting of Amount of Load Compensation

This function compensates the drop of output voltage V_{OUT} corresponding to the average current of primary transformer current I_P.

The amount of load compensation is adjusted by the external capacitor C_{L_COMP} and external resistor R_{L_COMP} at the L_COMP pin because the primary transformer current I_P and secondary transformer current I_S have the relation of the formula below. The reference value of C_{L_COMP} is 0.1 μ F.

$$I_P = \frac{N_P}{N_S} \times I_S \tag{A}$$

Where:

 I_P is the primary transformer current.

 N_P is the number of winding at the primary transformer.

 N_S is the number of winding at the secondary transformer.

 I_S is the secondary transformer current.

9.1.1 Setting of External Resistor at the L_COMP Pin RL_COMP

It is necessary to calculate the L_COMP pin current I_{L_COMP} following the formula below for the setting of the external resistor at the L_COMP pin R_{L_COMP} .

$$I_{L_COMP} = \frac{V_{L_COMP}}{R_{INTCOMP}}$$
 [A]

Where:

 $I_{L\ COMP}$ is the L_COMP pin current.

 $V_{L,COMP}$ is the L_COMP pin voltage.

 $R_{INTCOMP}$ is the internal resistor at the L_COMP pin

 V_{L_COMP} mentioned in the formula above is the value converted the current which calculated by K x I_P flowing from Current Monitor Block to the L_COMP pin by the external resistor at the L_COMP pin R_{L_COMP}. It becomes I_{L_COMP} in the inside and compensates the REF pin current.

It is necessary to meet $V_{L_COMP} \le 0.5 \text{ V}$ because the operational voltage's upper limit of V_{L_COMP} is restricted by the internal circuit.

In addition, Connect the external capacitor at the L_COMP pin C_{L_COMP} because the rapid fluctuation of I_{L_COMP} may make the V_{L_COMP} unstable.

Than the above, V_{L_COMP} should meet the conditions below.

$$\begin{split} V_{L_COMP} &= K \times R_{L_COMP} \times I_{P_AVE} \le 0.5 \\ &= K \times R_{L_COMP} \times \frac{I_{P_MIN} + I_{P_MAX}}{2} \times \frac{t_{ON}}{t_{S}} \le 0.5 \end{split} \quad \text{[V]}$$

Where:

 ${\it K}\,$ is the compressor magnification in Current Monitor Block.

 $R_{L,COMP}$ is the external resistor at the L_COMP pin.

 I_{P_AVE} is the average value of primary transformer current I_P.

 $I_{P\ MIN}$ is the minimum value of primary transformer current I_P.

 $I_{P\ MAX}$ is the maximum value of primary transformer current I_P.

 $t_{\rm S}$ is the switching cycle.

 t_{ON} is the on time.

9.1.1 Setting of External Resistor at the L_COMP Pin RL_COMP - continued

By the load compensation function, the feedback current decreases I_{L_COMP} from its original current value flowing at R_{REF} . As the result, the High level of V_{SW} rises for compensating this drop and it compensates the dropped output voltage V_{OUT} .

The output voltage at operating the load compensation function is calculated by the formula below.

$$V_{OUT} = \frac{N_S}{N_P} \times \left(\frac{V_{REF}}{R_{RFF}} + I_{L_COMP}\right) \times R_{FB} - V_F - I_{S_AVE} \times ESR$$
 [V]

Where:

 V_{OUT} is the output voltage.

 N_S is the number of winding at the secondary transformer.

 N_P is the number of winding at the primary transformer.

 V_{REF} is the REF pin voltage.

 R_{REF} is the external resistor between the REF and AGND pins.

 $I_{L\ COMP}$ is the L_COMP pin current.

 R_{FB} is the external resistor between the FB and SW pins.

 V_F is the forward voltage at the secondary output diode.

 $I_{S\ AVE}$ is the average value of the secondary transformer current Is.

Reference: The output voltage V_{OUT} at normal operation

$$V_{OUT} = \frac{N_S}{N_P} \times \frac{R_{FB}}{R_{REF}} \times V_{REF} - V_F - I_{S_AVE} \times ESR$$
 [V]

According to the formula above, it is necessary to establish the next formula to remove the forward voltage at the secondary output diode V_F and ESR by the L_COMP pin current I_{L_COMP} .

$$I_{L_COMP} \times \frac{N_S}{N_P} \times R_{FB} = V_F + I_{S_AVE} \times ESR$$
 [A]

Next, calculate the R_{L_COMP} by making the linear approximation R_{VF} of the fluctuation of the forward voltage at the secondary output diode corresponding to the secondary transformer current I_S .

$$\frac{K \times R_{L_COMP} \times I_{P_AVE}}{R_{INTCOMP}} \times \frac{N_S}{N_P} \times R_{FB} = I_{S_AVE} \times R_{VF} + I_{S_AVE} \times ESR$$

$$\frac{K \times R_{L_COMP}}{R_{INTCOMP}} \times \left(\frac{N_S}{N_P}\right)^2 \times R_{FB} = (R_{VF} + ESR) \times \frac{1 - Duty}{Duty}$$

Than the above,

$$R_{L_COMP} = R_{INTCOMP} \times \frac{R_{VF} + ESR}{K \times R_{ER}} \times \left(\frac{N_S}{N_D}\right)^2 \times \frac{1 - Duty}{Duty}$$
 [Q]

Where:

K is the compressor magnification in Current Monitor Block.

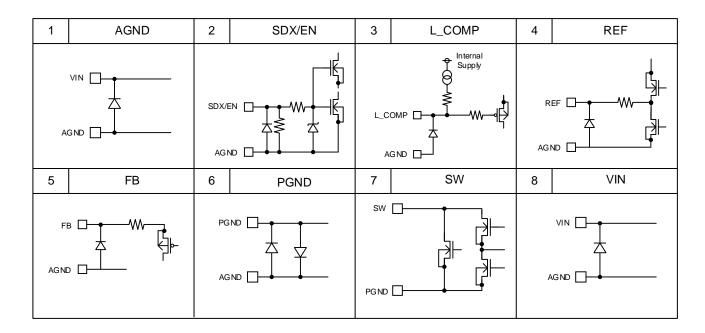
 $R_{L,COMP}$ is the external resistor at the L_COMP pin.

 $I_{P\ AVE}$ is the average value of primary transformer current I_P.

 $R_{INTCOMP}$ is the internal resistor at the L_COMP pin

The values of R_{VF} , ESR, and R_{FB} depend on the operating environment such as use parts and mounting boards. When set the R_{L_COMP} actually, adjust them monitoring the output voltage V_{OUT} in the range of using load current certainly.

I/O Equivalence Circuit



Operational Notes

1. Reverse Connection of Power Supply

Connecting the power supply in reverse polarity can damage the IC. Take precautions against reverse polarity when connecting the power supply, such as mounting an external diode between the power supply and the IC's power supply pins.

2. Power Supply Lines

Design the PCB layout pattern to provide low impedance supply lines. Furthermore, connect a capacitor to ground at all power supply pins. Consider the effect of temperature and aging on the capacitance value when using electrolytic capacitors.

3. Ground Voltage

Ensure that no pins are at a voltage below that of the ground pin at any time, even during transient condition.

4. Ground Wiring Pattern

When using both small-signal and large-current ground traces, the two ground traces should be routed separately but connected to a single ground at the reference point of the application board to avoid fluctuations in the small-signal ground caused by large currents. Also ensure that the ground traces of external components do not cause variations on the ground voltage. The ground lines must be as short and thick as possible to reduce line impedance.

5. Recommended Operating Conditions

The function and operation of the IC are guaranteed within the range specified by the recommended operating conditions. The characteristic values are guaranteed only under the conditions of each item specified by the electrical characteristics.

6. Inrush Current

When power is first supplied to the IC, it is possible that the internal logic may be unstable and inrush current may flow instantaneously due to the internal powering sequence and delays, especially if the IC has more than one power supply. Therefore, give special consideration to power coupling capacitance, power wiring, width of ground wiring, and routing of connections.

7. Testing on Application Boards

When testing the IC on an application board, connecting a capacitor directly to a low-impedance output pin may subject the IC to stress. Always discharge capacitors completely after each process or step. The IC's power supply should always be turned off completely before connecting or removing it from the test setup during the inspection process. To prevent damage from static discharge, ground the IC during assembly and use similar precautions during transport and storage.

8. Inter-pin Short and Mounting Errors

Ensure that the direction and position are correct when mounting the IC on the PCB. Incorrect mounting may result in damaging the IC. Avoid nearby pins being shorted to each other especially to ground, power supply and output pin. Inter-pin shorts could be due to many reasons such as metal particles, water droplets (in very humid environment) and unintentional solder bridge deposited in between pins during assembly to name a few.

9. Unused Input Pins

Input pins of an IC are often connected to the gate of a MOS transistor. The gate has extremely high impedance and extremely low capacitance. If left unconnected, the electric field from the outside can easily charge it. The small charge acquired in this way is enough to produce a significant effect on the conduction through the transistor and cause unexpected operation of the IC. So unless otherwise specified, unused input pins should be connected to the power supply or ground line.

Operational Notes - continued

10. Regarding the Input Pin of the IC

This monolithic IC contains P+ isolation and P substrate layers between adjacent elements in order to keep them isolated. P-N junctions are formed at the intersection of the P layers with the N layers of other elements, creating a parasitic diode or transistor. For example (refer to figure below):

When GND > Pin A and GND > Pin B, the P-N junction operates as a parasitic diode. When GND > Pin B, the P-N junction operates as a parasitic transistor.

Parasitic diodes inevitably occur in the structure of the IC. The operation of parasitic diodes can result in mutual interference among circuits, operational faults, or physical damage. Therefore, conditions that cause these diodes to operate, such as applying a voltage lower than the GND voltage to an input pin (and thus to the P substrate) should be avoided.

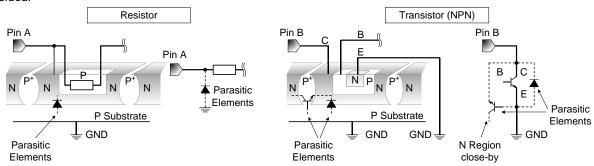


Figure 52. Example of Monolithic IC Structure

11. Ceramic Capacitor

When using a ceramic capacitor, determine a capacitance value considering the change of capacitance with temperature and the decrease in nominal capacitance due to DC bias and others.

12. Thermal Shutdown Circuit (TSD)

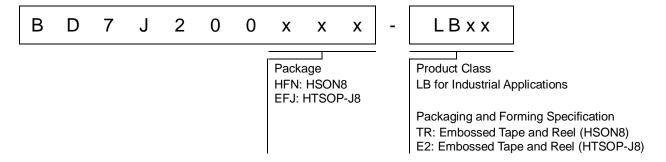
This IC has a built-in thermal shutdown circuit that prevents heat damage to the IC. Normal operation should always be within the IC's maximum junction temperature rating. If however the rating is exceeded for a continued period, the junction temperature (Tj) will rise which will activate the TSD circuit that will turn OFF power output pins. When the Tj falls below the TSD threshold, the circuits are automatically restored to normal operation.

Note that the TSD circuit operates in a situation that exceeds the absolute maximum ratings and therefore, under no circumstances, should the TSD circuit be used in a set design or for any purpose other than protecting the IC from heat damage.

13. Over Current Protection Circuit (OCP)

This IC incorporates an integrated overcurrent protection circuit that is activated when the load is shorted. This protection circuit is effective in preventing damage due to sudden and unexpected incidents. However, the IC should not be used in applications characterized by continuous operation or transitioning of the protection circuit.

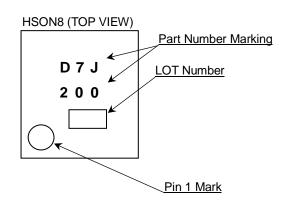
Ordering Information

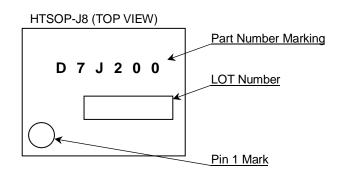


Lineup

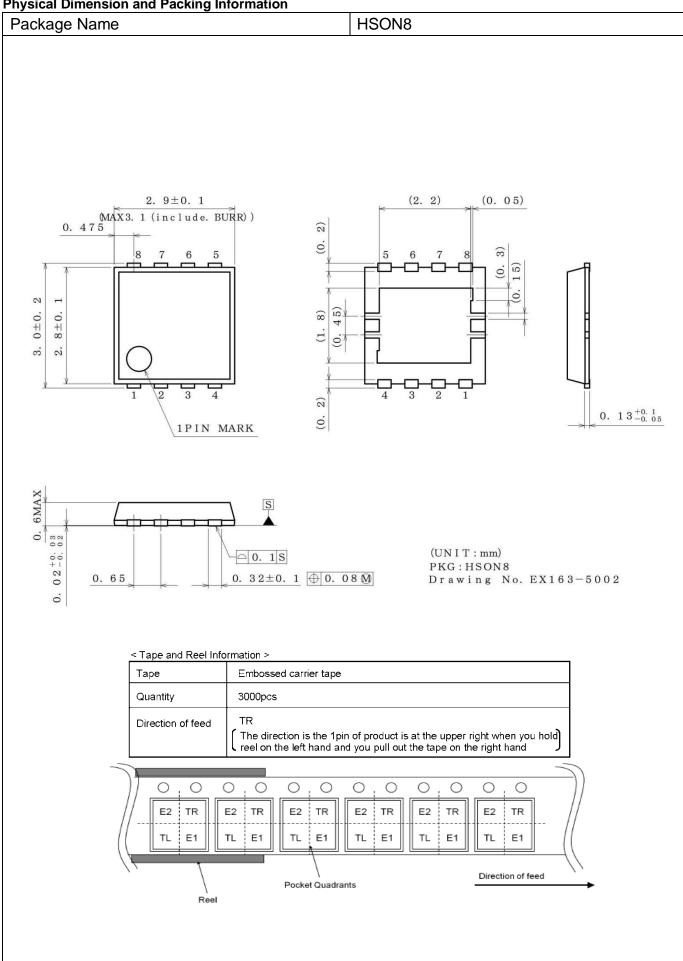
Product Name	Part Number Marking	Orderable Part Number	Package
BD7J200HFN-LB	D7J200	BD7J200HFN-LBTR	HSON8
BD7J200EFJ-LB	D7J200	BD7J200EFJ-LBE2	HTSOP-J8

Marking Diagrams

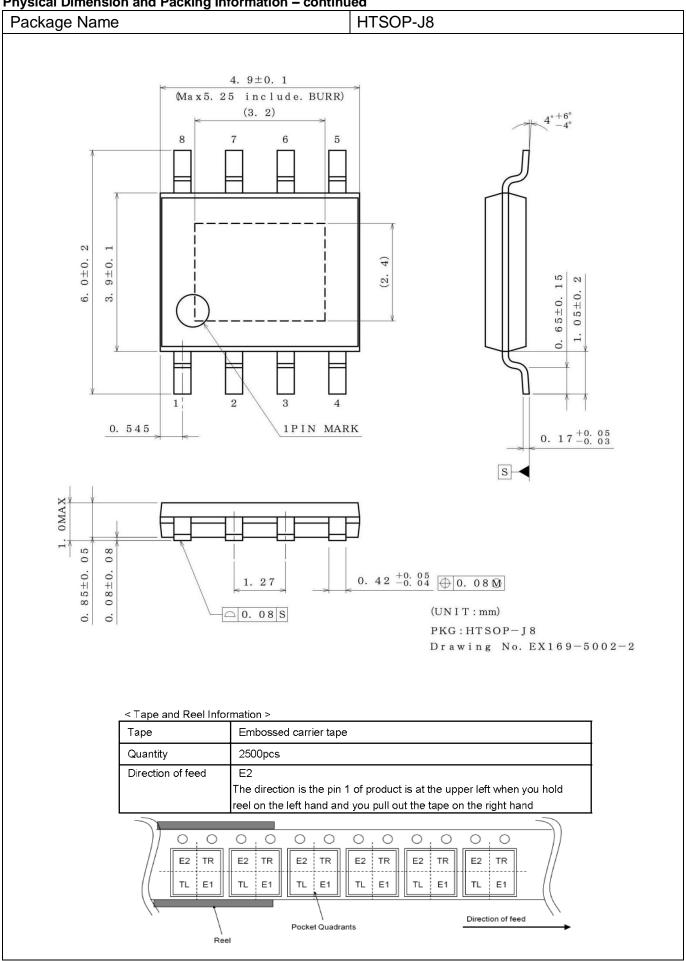




Physical Dimension and Packing Information



Physical Dimension and Packing Information - continued



Revision History

Date	Revision	Changes
20.Aug.2019	001	New Release

Notice

Precaution on using ROHM Products

1. If you intend to use our Products in devices requiring extremely high reliability (such as medical equipment (Note 1), aircraft/spacecraft, nuclear power controllers, etc.) and whose malfunction or failure may cause loss of human life, bodily injury or serious damage to property ("Specific Applications"), please consult with the ROHM sales representative in advance. Unless otherwise agreed in writing by ROHM in advance, ROHM shall not be in any way responsible or liable for any damages, expenses or losses incurred by you or third parties arising from the use of any ROHM's Products for Specific Applications.

(Note1) Medical Equipment Classification of the Specific Applications

ſ	JÁPAN	USA	EU	CHINA
Ī	CLASSⅢ	CL ACCIII	CLASS II b	СГУССШ
ſ	CLASSIV	CLASSⅢ	CLASSⅢ	CLASSⅢ

- 2. ROHM designs and manufactures its Products subject to strict quality control system. However, semiconductor products can fail or malfunction at a certain rate. Please be sure to implement, at your own responsibilities, adequate safety measures including but not limited to fail-safe design against the physical injury, damage to any property, which a failure or malfunction of our Products may cause. The following are examples of safety measures:
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 - [b] Use of our Products outdoors or in places where the Products are exposed to direct sunlight or dust
 - [c] Use of our Products in places where the Products are exposed to sea wind or corrosive gases, including Cl₂, H₂S, NH₃, SO₂, and NO₂
 - [d] Use of our Products in places where the Products are exposed to static electricity or electromagnetic waves
 - [e] Use of our Products in proximity to heat-producing components, plastic cords, or other flammable items
 - [f] Sealing or coating our Products with resin or other coating materials
 - [g] Use of our Products without cleaning residue of flux (Exclude cases where no-clean type fluxes is used. However, recommend sufficiently about the residue.); or Washing our Products by using water or water-soluble cleaning agents for cleaning residue after soldering
 - [h] Use of the Products in places subject to dew condensation
- 4. The Products are not subject to radiation-proof design.
- 5. Please verify and confirm characteristics of the final or mounted products in using the Products.
- 6. In particular, if a transient load (a large amount of load applied in a short period of time, such as pulse, is applied, confirmation of performance characteristics after on-board mounting is strongly recommended. Avoid applying power exceeding normal rated power; exceeding the power rating under steady-state loading condition may negatively affect product performance and reliability.
- 7. De-rate Power Dissipation depending on ambient temperature. When used in sealed area, confirm that it is the use in the range that does not exceed the maximum junction temperature.
- 8. Confirm that operation temperature is within the specified range described in the product specification.
- ROHM shall not be in any way responsible or liable for failure induced under deviant condition from what is defined in this document.

Precaution for Mounting / Circuit board design

- 1. When a highly active halogenous (chlorine, bromine, etc.) flux is used, the residue of flux may negatively affect product performance and reliability.
- 2. In principle, the reflow soldering method must be used on a surface-mount products, the flow soldering method must be used on a through hole mount products. If the flow soldering method is preferred on a surface-mount products, please consult with the ROHM representative in advance.

For details, please refer to ROHM Mounting specification

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- 1. If change is made to the constant of an external circuit, please allow a sufficient margin considering variations of the characteristics of the Products and external components, including transient characteristics, as well as static characteristics.
- 2. You agree that application notes, reference designs, and associated data and information contained in this document are presented only as guidance for Products use. Therefore, in case you use such information, you are solely responsible for it and you must exercise your own independent verification and judgment in the use of such information contained in this document. ROHM shall not be in any way responsible or liable for any damages, expenses or losses incurred by you or third parties arising from the use of such information.

Precaution for Electrostatic

This Product is electrostatic sensitive product, which may be damaged due to electrostatic discharge. Please take proper caution in your manufacturing process and storage so that voltage exceeding the Products maximum rating will not be applied to Products. Please take special care under dry condition (e.g. Grounding of human body / equipment / solder iron, isolation from charged objects, setting of lonizer, friction prevention and temperature / humidity control).

Precaution for Storage / Transportation

- 1. Product performance and soldered connections may deteriorate if the Products are stored in the places where:
 - [a] the Products are exposed to sea winds or corrosive gases, including Cl₂, H₂S, NH₃, SO₂, and NO₂
 - [b] the temperature or humidity exceeds those recommended by ROHM
 - [c] the Products are exposed to direct sunshine or condensation
 - [d] the Products are exposed to high Electrostatic
- Even under ROHM recommended storage condition, solderability of products out of recommended storage time period
 may be degraded. It is strongly recommended to confirm solderability before using Products of which storage time is
 exceeding the recommended storage time period.
- 3. Store / transport cartons in the correct direction, which is indicated on a carton with a symbol. Otherwise bent leads may occur due to excessive stress applied when dropping of a carton.
- 4. Use Products within the specified time after opening a humidity barrier bag. Baking is required before using Products of which storage time is exceeding the recommended storage time period.

Precaution for Product Label

A two-dimensional barcode printed on ROHM Products label is for ROHM's internal use only.

Precaution for Disposition

When disposing Products please dispose them properly using an authorized industry waste company.

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