

DFS60B-S1PL10000

DFS60

INCREMENTAL ENCODERS





Ordering information

Туре	Part no.
DFS60B-S1PL10000	1036758

Other models and accessories → www.sick.com/DFS60



Detailed technical data

Performance

Pulses per revolution	10,000 ¹⁾
Measuring step	90°, electric/pulses per revolution
Measuring step deviation at non binary number of lines	± 0.01°
Error limits	± 0.05°

¹⁾ See maximum revolution range.

Interfaces

Communication interface	Incremental
Communication Interface detail	TTL / HTL
Factory setting	Factory setting: output level TTL
Number of signal channels	6-channel
Programmable/configurable	✓
Initialization time	$32 \text{ ms}^{1)}$ 30 ms
Output frequency	≤ 600 kHz
Load current	≤ 30 mA
Power consumption	≤ 0.7 W (without load)

 $^{^{1)}}$ With mechanical zero pulse width.

Electrical data

Connection type	Cable, 8-wire, universal, 3 m ¹⁾
Supply voltage	4.5 32 V
Reference signal, number	1
Reference signal, position	90°, electric, logically gated with A and B
Reverse polarity protection	✓

¹⁾ The universal cable connection is positioned so that it is possible to lay it without bends in a radial or axial direction.

 $^{^{2)}}$ Programming TTL with \geq 5.5 V: short-circuit opposite to another channel or GND permissable for maximum 30 s.

 $^{^{3)}}$ Programming HTL or TTL with < 5.5 V: short-circuit opposite to another channel, US or GND permissable for maximum 30 s.

⁴⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Short-circuit protection of the outputs	√ ^{2) 3)}
MTTFd: mean time to dangerous failure	300 years (EN ISO 13849-1) 4)

 $^{^{1)}}$ The universal cable connection is positioned so that it is possible to lay it without bends in a radial or axial direction.

Mechanical data

Mechanical design	Solid shaft, Servo flange
Shaft diameter	6 mm
Shaft length	10 mm
Weight	+ 0.3 kg
Shaft material	Stainless steel
Flange material	Aluminum
Housing material	Aluminum die cast
Start up torque	0.5 Ncm (+20 °C)
Operating torque	0.3 Ncm (+20 °C)
Permissible shaft loading	80 N (radial) 40 N (axial)
Operating speed	≤ 9,000 min ⁻¹ 1)
Moment of inertia of the rotor	6.2 gcm ²
Bearing lifetime	3.6 x 10^10 revolutions
Angular acceleration	≤ 500,000 rad/s²

 $^{^{1)}}$ Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3
Enclosure rating	IP67, housing side, cable connection (IEC 60529) IP65, shaft side (IEC 60529)
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	-40 °C +100 °C ¹⁾ -30 °C +100 °C ²⁾
Storage temperature range	-40 °C +100 °C, without package
Resistance to shocks	70 g, 6 ms (EN 60068-2-27)
Resistance to vibration	30 g, 10 Hz 2,000 Hz (EN 60068-2-6)

 $^{^{1)}}$ Stationary position of the cable.

Classifications

eCl@ss 5.0	27270501
eCl@ss 5.1.4	27270501
eCl@ss 6.0	27270590
eCl@ss 6.2	27270590
eCl@ss 7.0	27270501

 $^{^{2)}}$ Programming TTL with \geq 5.5 V: short-circuit opposite to another channel or GND permissable for maximum 30 s.

 $^{^{3)}}$ Programming HTL or TTL with < 5.5 V: short-circuit opposite to another channel, US or GND permissable for maximum 30 s.

⁴⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

²⁾ Flexible position of the cable.

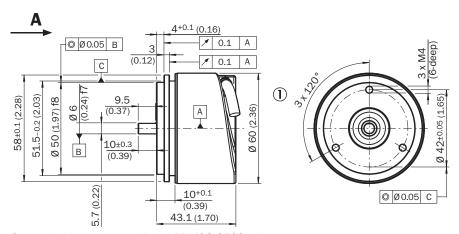
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eCl@ss 8.0	27270501
eCl@ss 8.1	27270501
eCl@ss 9.0	27270501
eCl@ss 10.0	27270501
eCl@ss 11.0	27270501
eCl@ss 12.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing (Dimensions in mm (inch))

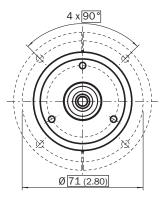
Servo flange, cable



General tolerances according to DIN ISO 2768-mk ① Cable diameter = 5.6 mm +/- 0.2 mm bend radius = 30 mm

Attachment specifications

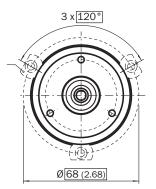
Mounting requirements for half-shell servo clamp



All dimensions in mm (inch)

Part no. 2029165

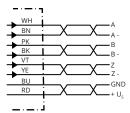
Mounting requirements for small servo clamp



All dimensions in mm (inch)

Part no. 2029166

PIN assignment



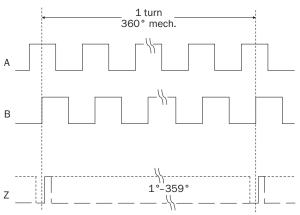
PIN Male connector M12, 8-pin	PIN Male connec- tor M23, 12-pin	Wire colors (ca- ble connection)	TTL/HTL signal	Sin/Cos 1.0 V _{PP}	Explanation
1	6	Brown	_A	COS-	Signal wire
2	5	White	A	COS+	Signal wire
3	1	Black	_B	SIN-	Signal wire
4	8	Pink	В	SIN+	Signal wire
5	4	Yellow	-z	-z	Signal wire
6	3	Purple	Z	Z	Signal wire

PIN Male connector M12, 8-pin	PIN Male connec- tor M23, 12-pin	Wire colors (ca- ble connection)	TTL/HTL signal	Sin/Cos 1.0 V _{PP}	Explanation
7	10	Blue	GND	GND	Ground connection
8	12	Red	+U _S	+U _S	Supply voltage
-	9	-	N.c.	N.c.	Not assigned
-	2	-	N.c.	N.c.	Not assigned
-	11	-	N.c.	N.c.	Not assigned
-	7 1)	Orange	0-SET ¹⁾	N.c.	Set zero pulse
Screen	Screen	Screen	Screen	Screen	Screen connected to housing on encoder side. Connected to ground on control side.
1) For electrical interfaces only: M, U, V, W with 0-SET function on PIN 7 on M23 plug. The 0-SET input is used to set the					

For electrical interfaces only: M, U, V, W with 0-SET function on PIN 7 on M23 plug. The 0-SET input is used to set the zero pulse to the current shaft position. If the 0-SET input is applied to US for longer than 250 ms after it has previously been open or applied to GND for at least 1,000 ms, the current shaft position is assigned zero pulse signal "Z".

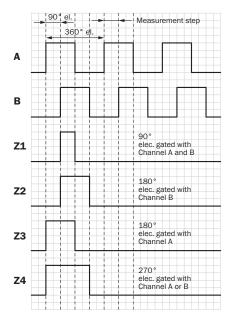
Diagrams

Mechanical zero pulse width 1° to 359° programmable. Width of the zero pulse in relation to a mechanical revolution of the shaft.



Supply voltage	Output
4,5 V 32 V	TTL/HTL programmable

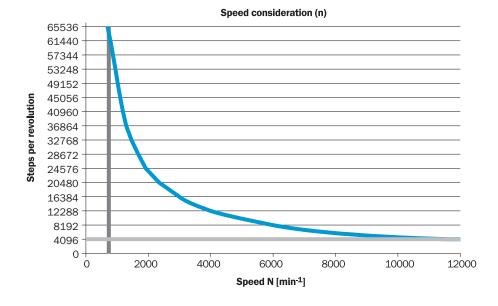
Electrical zero pulse width can be configured to 90°, 180°, or 270°. Width of the zero pulse in relation to a pulse period.



Cw with view on the encoder shaft in direction "A", compare dimensional drawing.

Supply voltage	Output
4,5 V 32 V	TTL/HTL programmable

Maximum revolution range



Recommended accessories

Other models and accessories → www.sick.com/DFS60

	Brief description	Туре	Part no.		
rogramming	g and configuration tools				
	USB programming unit, for programmable SICK encoders AFS60, AFM60, DFS60, VFS60, DFV60 and wire draw encoders with programmable encoders	PGT-08-S	1036616		
▼	Programming unit display for programmable SICK DFS60, DFV60, AFS/AFM60, AHS/AHM36 encoders, and wire draw encoder with DFS60, AFS/AFM60 and AHS/AHM36. Compact dimensions, low weight, and intuitive operation.	PGT-10-Pro	1072254		
ther mount	ing accessories				
	Aluminium measuring wheel with 0-ring (NBR70) for 6 mm solid shaft, circumference 200 mm $$	BEF-MR006020R	2055222		
	Measuring wheel with 0-ring (NBR70) for 6 mm solid shaft, circumference 300 mm $$	BEF-MR006030R	2055634		
	Aluminium measuring wheel with O-ring (NBR70) for 6 mm solid shaft, circumference 500 mm $$	BEF-MR006050R	2055225		
	Aluminum measuring wheel with cross-knurled surface for 6 mm solid shaft, circumference 200 mm	BEF-MR06200AK	4084745		
	Aluminum measuring wheel with smooth polyurethane surface for 6 mm solid shaft, circumference 200 mm	BEF-MR06200AP	4084746		
	Aluminum measuring wheel with ridged polyurethane surface for 6 mm solid shaft, circumference 200 mm	BEF-MR06200APG	4084748		
	Aluminum measuring wheel with studded polyurethane surface for 6 mm solid shaft, circumference 200 mm	BEF-MR06200APN	4084747		
	Mounting bell for encoder with servo flange, 50 mm spigot, mounting kit included	BEF-MG-50	5312987		
	Bearing block for servo and face mount flange encoder. The heavy-duty bearing block is used to absorb very large radial and axial shaft loads. Particularly when using belt pulleys, chain sprockets, friction wheels. Operating speed max. 4,000 rpm^-1, axial shaft load 150 N, radial shaft load 250 N, bearing service life 3.6 x 10^9 revolutions	BEF-FA-LB1210	2044591		
	Mounting kit for servo flange encoder on the bearing block, 1 bar coupling SKPS 1520 06/06 1 hexagon socket wrench SW1.5 DIN 911, 3 mounting eccentric BEMN 1242 49 3 screws M4 x 10 DIN 912,1 hexagon socket wrench SW3 DIN 911, 1 bar coupling SKPS 1520 06/06 1 hexagon socket wrench SW1.5 DIN 911, 3 mounting eccentric BEMN 1242 49 3 screws M4 x 10 DIN 912, 1 hexagon socket wrench SW3 DIN 911	BEF-MK-LB	5320872		
	Servo clamps, large, for servo flange (clamps, eccentric fastener), 3 pcs, without mounting material, without mounting hardware $\frac{1}{2} \left(\frac{1}{2} \right) = \frac{1}{2} \left(\frac{1}{2} \right) \left(\frac{1}{$	BEF-WK-SF	2029166		
lug connect	g connectors and cables				
The second	Head A: female connector, JST, 8-pin, straight Head B: Flying leads Cable: Incremental, SSI, PUR, halogen-free, shielded, 5 m	DOL-0J08-G05MAA3	2046876		
	Head A: female connector, JST, 8-pin, straight Head B: Flying leads Cable: Incremental, SSI, PUR, halogen-free, shielded, 0.5 m	DOL-0J08-G0M5AA3	2046873		
	Head A: female connector, JST, 8-pin, straight Head B: Flying leads Cable: Incremental, SSI, PUR, halogen-free, shielded, 10 m	DOL-0J08-G10MAA3	2046877		

	Brief description	Туре	Part no.
	Head A: female connector, JST, 8-pin, straight Head B: Flying leads Cable: SSI, Incremental, PUR, halogen-free, shielded, 1.5 m	DOL-0J08-G1M5AA6	2048590
	Head A: female connector, JST, 8-pin, straight Head B: Flying leads Cable: SSI, Incremental, PUR, halogen-free, shielded, 3 m	DOL-0J08-G3M0AA6	2048591
	Head A: female connector, terminal box, 8-pin, straight Head B: male connector, D-Sub, 9-pin, straight Cable: SSI + incremental, PVC, shielded, 0.5 m Programming adapter cable for programming tool PGT-10-Pro and PGT-08-S	DSL-0D08-G0M5AC3	2061739
	Head A: female connector, JST, 8-pin, straight Head B: male connector, M23, 12-pin, straight Cable: Incremental, PUR, halogen-free, shielded, 1 m	STL-2312-G01MAA3	2061622
	Head A: female connector, JST, 8-pin, straight Head B: male connector, M23, 12-pin, straight Cable: Incremental, PUR, halogen-free, shielded, 2 m	STL-2312-G02MAA3	2061504
	Head A: female connector, JST, 8-pin, straight Head B: male connector, M23, 12-pin, straight Cable: Incremental, PUR, halogen-free, shielded, 0.35 m	STL-2312-GM35AA3	2061621
	Head A: male connector, M12, 8-pin, straight, A-coded Cable: Incremental, shielded	STE-1208-GA01	6044892
	Head A: male connector, M23, 12-pin, straight Cable: HIPERFACE [®] , SSI, Incremental, shielded	STE-2312-G01	2077273
		STE-2312-GX	6028548
Shaft adaptat	ion		
	Bellows coupling, shaft diameter 6 mm / 6 mm, maximum shaft offset: radial \pm 0.25 mm, axial \pm 0.4 mm, angular +/- 4°; max. speed 10,000 rpm, -30 °C to +120 °C, max. torque 120 Ncm; material: stainless steel bellows, aluminum hub	KUP-0606-B	5312981
	Cross-slotted coupling, shaft diameter 6 mm / 6 mm, maximum shaft offset: radial \pm 0.3 mm, axial \pm 0.2 mm, angle \pm 3°; max. speed 10,000 rpm, -10° to $+80^\circ$ C, max. torque 80 Ncm; material: fiber-glass reinforced polyamide, aluminum hub	KUP-0606-S	2056406
	Bar coupling, shaft diameter 6 mm /8 mm, maximum shaft offset radial \pm 0.3 mm, axial \pm 0.2 mm, angle \pm 3°, max. speed 10,000 rpm, torsion spring rigidity 38 Nm/wheel; material: fiber-glass reinforced polyamide, aluminum hub	KUP-0608-S	5314179
	Bellows coupling, shaft diameter 6 mm / 10 mm, maximum shaft offset: radial \pm 0.25 mm, axial \pm 0.4 mm, angular +/- 4°; max. speed 10,000 rpm, -30 °C to +120 °C, max. torque 120 Ncm; material: stainless steel bellows, aluminum hub	KUP-0610-B	5312982
10	Double loop coupling, shaft diameter 6 mm $^{\prime}$ 10 mm, max. shaft offset: radially +/- 2,5 mm, axially +/-3 mm, angle +/- 10 degrees;max. speed 3.000 rpm, -30 to +80 degrees Celsius, torsional spring stiffness of 25 Nm/rad	KUP-0610-D	5326697
	Spring washer coupling, shaft diameter 6 mm / 10 mm, Maximum shaft offset: radial +/- 0.3 mm, axial +/- 0.4 mm, angular +/- 2.5°; max. speed 12,000 rpm, -10° to +80 °C, max. torque 60 Ncm; material: aluminum flange, glass fiber-reinforced polyamide membrane and hardened steel coupling pin	KUP-0610-F	5312985
Vo	Claw coupling, shaft diameter 6 mm / 10 mm, damping element 80 shore blue, maximum shaft offset: radial \pm 0.22 mm, axial \pm 1 mm angular \pm 1.3°, max. speed 19,000 rpm, angle of twist max. 10°, –30 °C to +80 °C, max. torque 800 Ncm, tightening torque of screws: ISO 4029 150 Ncm, material: aluminum flange, damping element: polyurethane	KUP-0610-J	2127056

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	Brief description	Туре	Part no.
0	Bar coupling, shaft diameter 6 mm / 10 mm, max. shaft offset: radial \pm 0,3 mm, axial \pm 0,3 mm, angular \pm 3°; max. speed 10.000 rpm, -10° to $+80^\circ$ C, max. torque: 80 Ncm, material: fiber-glass reinforced polyamide, aluminum hub	KUP-0610-S	2056407

SICK AT A GLANCE

SICK is one of the leading manufacturers of intelligent sensors and sensor solutions for industrial applications. A unique range of products and services creates the perfect basis for controlling processes securely and efficiently, protecting individuals from accidents and preventing damage to the environment.

We have extensive experience in a wide range of industries and understand their processes and requirements. With intelligent sensors, we can deliver exactly what our customers need. In application centers in Europe, Asia and North America, system solutions are tested and optimized in accordance with customer specifications. All this makes us a reliable supplier and development partner.

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