

# LM3677

## 3MHz, 600mA Miniature Step-Down DC-DC Converter for Ultra Low Voltage Circuits

### General Description

The LM3677 step-down DC-DC converter is optimized for powering ultra-low voltage circuits from a single Li-Ion cell battery and input voltage rails from 2.7V to 5.5V. It provides up to 600mA load current, over the entire input voltage range. The LM3677 is configured to four output voltages of 1.3V, 1.5V, 1.8V and 2.5V.

The device offers superior features and performance for mobile phones and similar portable applications with complex power management systems. Automatic intelligent switching between PWM low-noise and PFM low-current mode offers improved system control. During PWM mode operation, the device operates at a fixed-frequency of 3 MHz (typ). PWM mode drives loads from ~ 80mA to 600mA max. Hysteretic PFM mode extends the battery life by reducing the quiescent current to 16  $\mu$ A (typ) during light load and standby operation. Internal synchronous rectification provides high efficiency. In shutdown mode (Enable pin pulled down), the device turns off and reduces battery consumption to 0.01  $\mu$ A (typ).

The LM3677 is available in a lead-free (NO PB) 5-bump micro SMD package. A switching frequency of 3 MHz (typ) allows use of tiny surface-mount components. Only three external surface-mount components, an inductor and two ceramic capacitors, are required.

### Features

- 16  $\mu$ A typical quiescent current
- 600 mA maximum load capability
- 3 MHz PWM fixed switching frequency (typ)
- Automatic PFM/PWM mode switching
- Available in 5-bump micro SMD package
- Internal synchronous rectification for high efficiency
- Internal soft start
- 0.01  $\mu$ A typical shutdown current
- Operates from a single Li-Ion cell battery
- Only three tiny surface-mount external components required (solution size less than 20 mm<sup>2</sup>)
- Current overload and Thermal shutdown protection

### Applications

- Mobile phones
- PDAs
- MP3 players
- W-LAN
- Portable Instruments
- Digital still cameras
- Portable Hard disk drives

### Typical Application Circuit

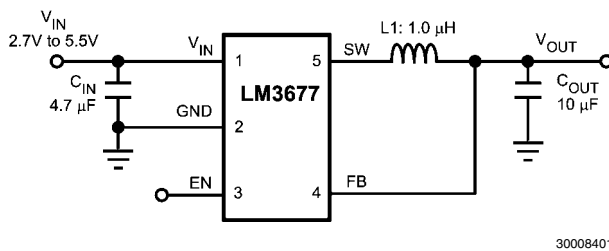
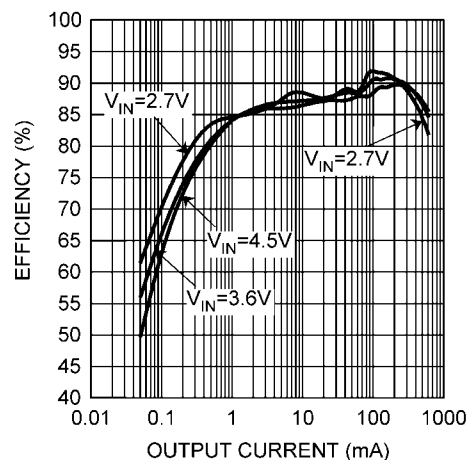


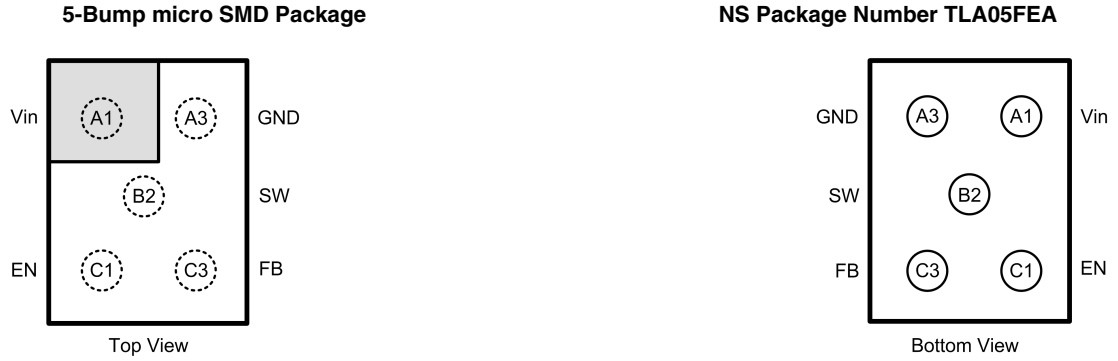
FIGURE 1. Typical Application Circuit

Efficiency vs. Output Current  
( $V_{OUT} = 1.8V$ )



30008487

## Connection Diagram and Package Mark Information



30008444

**FIGURE 2. 5 Bump Micro SMD Package**

### Pin Descriptions

Pin #	Name	Description
A1	$V_{IN}$	Power supply input. Connect to the input filter capacitor ( <i>Figure 1</i> ).
A3	GND	Ground pin.
C1	EN	Enable pin. The device is in shutdown mode when voltage to this pin is <0.4V and enabled when >1.0V. Do not leave this pin floating.
C3	FB	Feedback analog input. Connect directly to the output filter capacitor ( <i>FIGURE 1</i> ).
B2	SW	Switching node connection to the internal PFET switch and NFET synchronous rectifier.

### Ordering Information

Order Number	Spec	Package Marking	Supplied As
LM3677TL-1.3	NOPB	V	250 units, Tape-and-Reel
LM3677TLX-1.3	NOPB		3000 units, Tape-and-Reel
LM3677TL-1.5	NOPB	X	250 units, Tape-and-Reel
LM3677TLX-1.5	NOPB		3000 units, Tape-and-Reel
LM3677TL-1.8	NOPB	Y	250 units, Tape-and-Reel
LM3677TLX-1.8	NOPB		3000 units, Tape-and-Reel
LM3677TL-2.5	NOPB	Z	250 units, Tape-and-Reel
LM3677TLX-2.5	NOPB		3000 units, Tape-and-Reel

Note: 1.2V, 1.6V, 2.8V and ADJ are coming soon.

## Absolute Maximum Ratings (Note 1)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/Distributors for availability and specifications.

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/Distributors for availability and specifications.

$V_{IN}$ Pin: Voltage to GND	-0.2V to 6.0V
FB, SW, EN Pin:	(GND-0.2V) to ( $V_{IN} + 0.2V$ )
Continuous Power Dissipation (Note 3)	Internally Limited
Junction Temperature ( $T_{J-MAX}$ )	+125°C
Storage Temperature Range	-65°C to +150°C
Maximum Lead Temperature (Soldering, 10 sec.)	260°C

ESD Rating (Note 4)

Human Body Model: All Pins	2.0 kV
Machine Model: All Pins	200V

## Operating Ratings (Note 1), (Note 2)

Input Voltage Range	2.7V to 5.5V
Recommended Load Current	0mA to 600 mA
Junction Temperature ( $T_J$ ) Range	-30°C to +125°C
Ambient Temperature ( $T_A$ ) Range (Note 5)	-30°C to +85°C

## Thermal Properties

Junction-to-Ambient Thermal Resistance ( $\theta_{JA}$ ) (Note 6)	85°C/W
---	--------

**Electrical Characteristics** (Note 2), (Note 8), (Note 9) Limits in standard typeface are for  $T_J = T_A = 25^\circ\text{C}$ . Limits in **boldface** type apply over the operating ambient temperature range ( $-30^\circ\text{C} \leq T_A \leq +85^\circ\text{C}$ ). Unless otherwise noted, specifications apply to the LM3677 with  $V_{IN} = EN = 3.6V$ .

Symbol	Parameter	Condition	Min	Typ	Max	Units
$V_{IN}$	Input Voltage		2.7		5.5	V
$V_{FB}$	Feedback Voltage	PWM mode	<b>-2.5</b>		<b>+2.5</b>	%
$V_{REF}$	Internal Reference Voltage			0.5		V
$I_{SHDN}$	Shutdown Supply Current	EN = 0V		0.01	<b>1</b>	$\mu\text{A}$
$I_Q$	DC Bias Current into $V_{IN}$	No load, device is not switching		16	<b>35</b>	$\mu\text{A}$
$R_{DSON(P)}$	Pin-Pin Resistance for PFET	$V_{IN} = V_{GS} = 3.6V$ , $I_{SW} = 100\text{mA}$		350	450	m $\Omega$
$R_{DSON(N)}$	Pin-Pin Resistance for NFET	$V_{IN} = V_{GS} = 3.6V$ , $I_{SW} = -100\text{mA}$		150	250	m $\Omega$
$I_{LIM}$	Switch Peak Current Limit	Open Loop (Note 7)	<b>1085</b>	1220	<b>1375</b>	mA
$V_{IH}$	Logic High Input		<b>1.0</b>			V
$V_{IL}$	Logic Low Input				<b>0.4</b>	V
$I_{EN}$	Enable (EN) Input Current			0.01	<b>1</b>	$\mu\text{A}$
$F_{OSC}$	Internal Oscillator Frequency	PWM Mode	<b>2.5</b>	3	<b>3.5</b>	MHz

**Note 1:** Absolute Maximum Ratings indicate limits beyond which damage to the component may occur. Operating Ratings are conditions under which operation of the device is guaranteed. Operating Ratings do not imply guaranteed performance limits. For guaranteed performance limits and associated test conditions, see the Electrical Characteristics tables.

**Note 2:** All voltages are with respect to the potential at the GND pin.

**Note 3:** Internal thermal shutdown circuitry protects the device from permanent damage. Thermal shutdown engages at  $T_J = 150^\circ\text{C}$  (typ.) and disengages at  $T_J = 130^\circ\text{C}$  (typ.).

**Note 4:** The Human body model is a 100 pF capacitor discharged through a 1.5 k $\Omega$  resistor into each pin. The machine model is a 200 pF capacitor discharged directly into each pin. MIL-STD-883 3015.7

**Note 5:** In Applications where high power dissipation and/or poor package resistance is present, the maximum ambient temperature may have to be derated. Maximum ambient temperature ( $T_{A-MAX}$ ) is dependent on the maximum operating junction temperature ( $T_{J-MAX}$ ), the maximum power dissipation of the device in the application ( $P_{D-MAX}$ ) and the junction to ambient thermal resistance of the package ( $\theta_{JA}$ ) in the application, as given by the following equation:  $T_{A-MAX} = T_{J-MAX} - (\theta_{JA} \times P_{D-MAX})$ . Refer to Dissipation rating table for  $P_{D-MAX}$  values at different ambient temperatures.

**Note 6:** Junction to ambient thermal resistance is highly application and board layout dependent. In applications where high power dissipation exists, special care must be given to thermal dissipation issues in board design. Value specified here 85 °C/W is based on measurement results using a 4 layer board as per JEDEC standards.

**Note 7:** Refer to datasheet curves for closed loop data and its variation with regards to supply voltage and temperature. Electrical Characteristic table reflects open loop data (FB=0V and current drawn from SW pin ramped up until cycle by cycle current limit is activated). Closed loop current limit is the peak inductor current measured in the application circuit by increasing output current until output voltage drops by 10%.

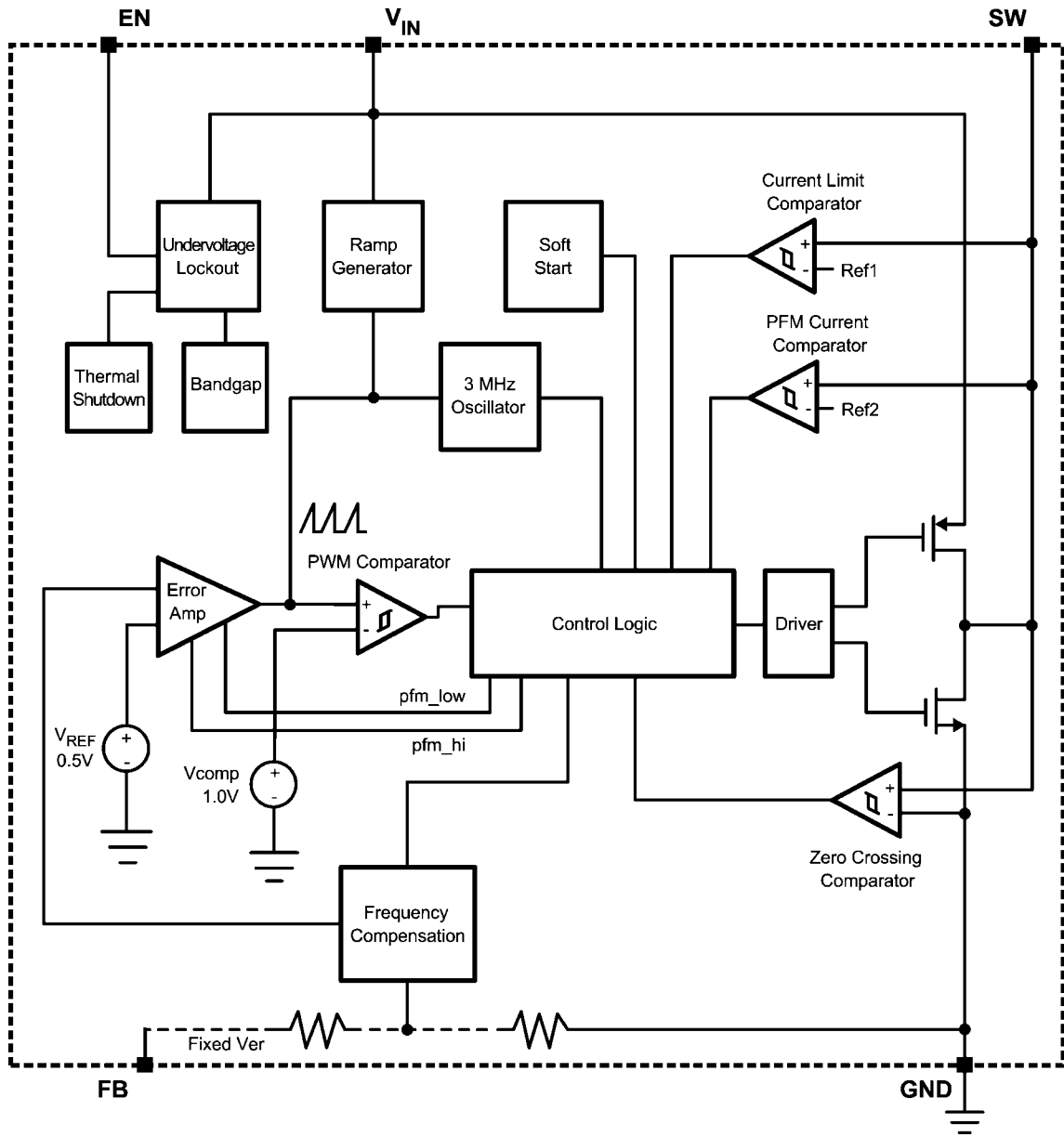
**Note 8:** Min and Max limits are guaranteed by design, test or statistical analysis. Typical numbers are not guaranteed, but do represent the most likely norm.

**Note 9:** The parameters in the electrical characteristic table are tested under open loop conditions at  $V_{IN} = 3.6V$  unless otherwise specified. For performance over the input voltage range and closed loop condition, refer to the datasheet curves.

## Dissipation Rating Table

$\theta_{JA}$	$T_A \leq 25^\circ\text{C}$ Power Rating	$T_A = 60^\circ\text{C}$ Power Rating	$T_A = 85^\circ\text{C}$ Power Rating
85°C/W (4-layer board)	1176 mW	765 mW	470 mW

Block Diagram



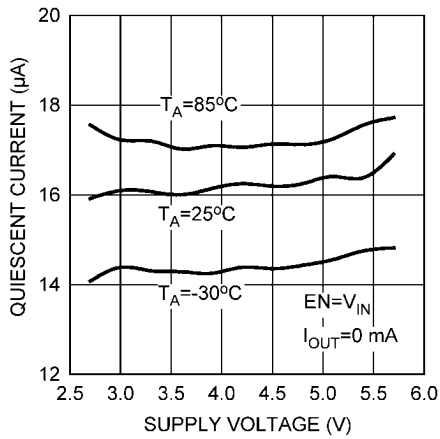
30008418

FIGURE 3. Simplified Functional Diagram

# Typical Performance Characteristics

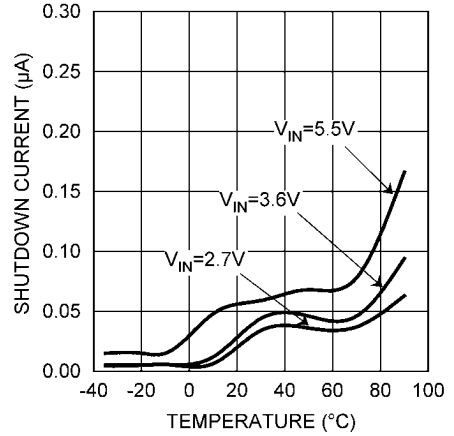
LM3677TL, Circuit of Figure 1,  $V_{IN} = 3.6V$ ,  $V_{OUT} = 1.8V$ ,  $T_A = 25^\circ C$ , unless otherwise noted.

**Quiescent Supply Current vs. Supply Voltage (Switching)**



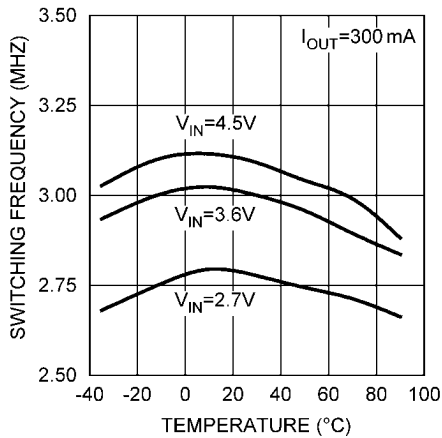
30008481

**Shutdown Current vs. Temp**



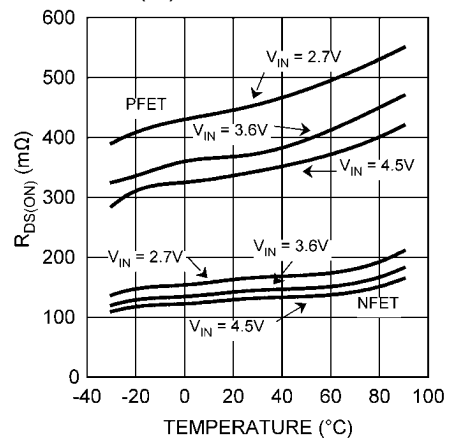
30008482

**Switching Frequency vs. Temperature**



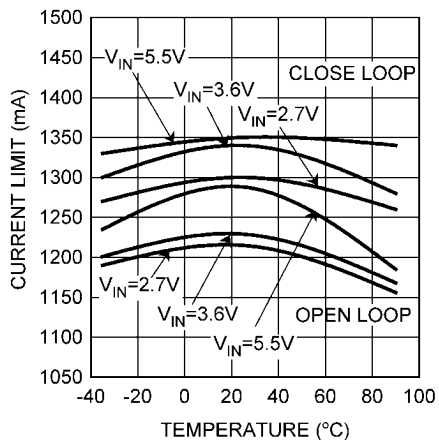
30008483

**$R_{DS(ON)}$  vs. Temperature**



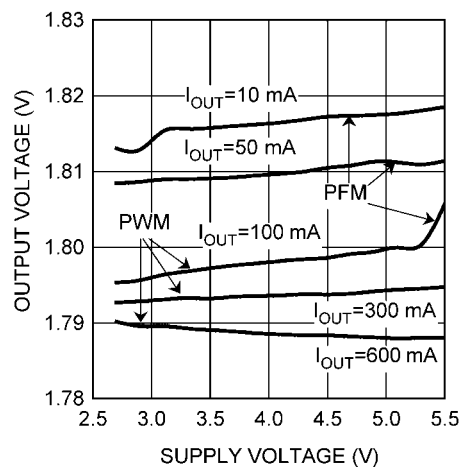
30008451

**Open/Closed Loop Current Limit vs. Temperature**



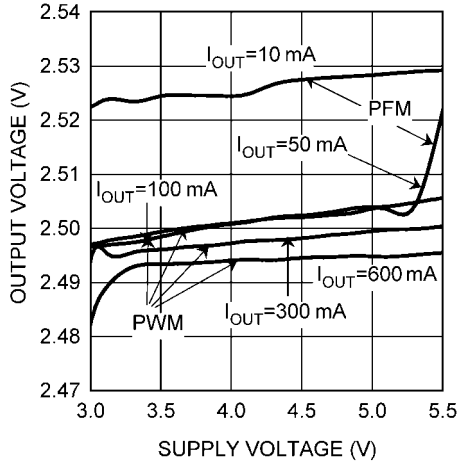
30008449

**Output Voltage vs. Supply Voltage ( $V_{OUT} = 1.8V$ )**



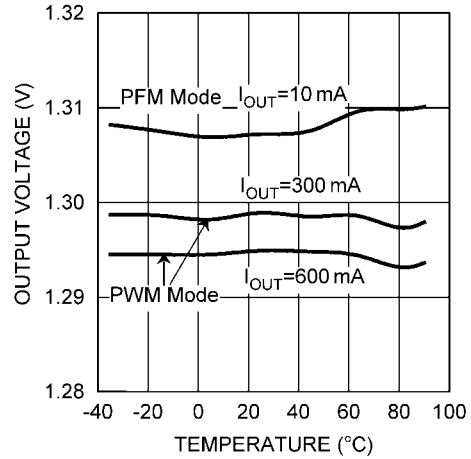
30008484

**Output Voltage vs. Supply Voltage**  
( $V_{OUT} = 2.5V$ )



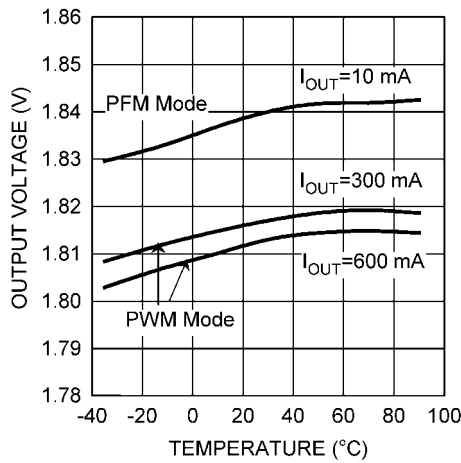
30008438

**Output Voltage vs. Temperature**  
( $V_{OUT} = 1.3V$ )



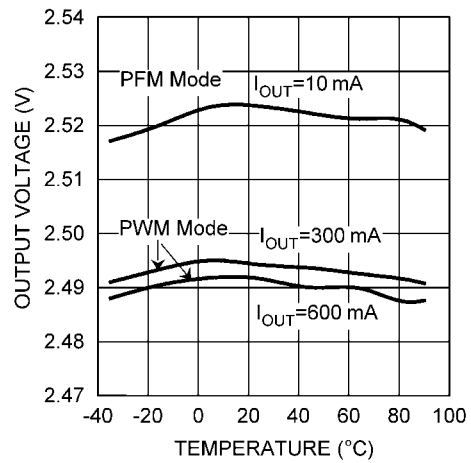
30008468

**Output Voltage vs. Temperature**  
( $V_{OUT} = 1.8V$ )



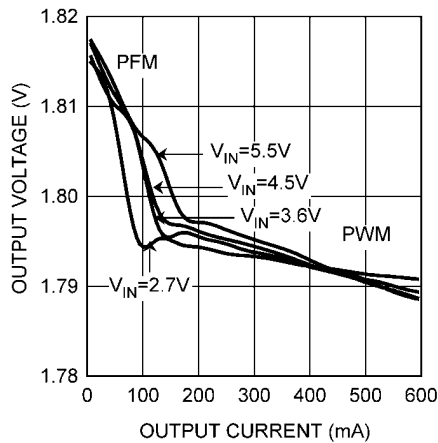
30008485

**Output Voltage vs. Temperature**  
( $V_{OUT} = 2.5V$ )



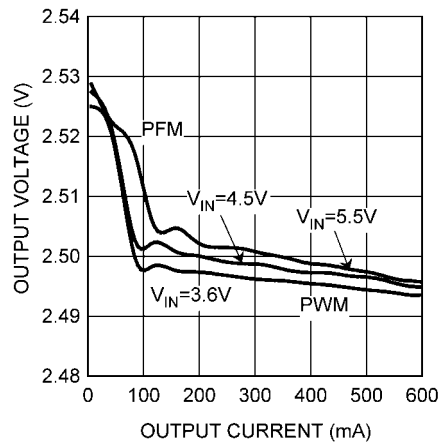
30008469

**Output Voltage vs. Output Current**  
( $V_{OUT} = 1.8V$ )



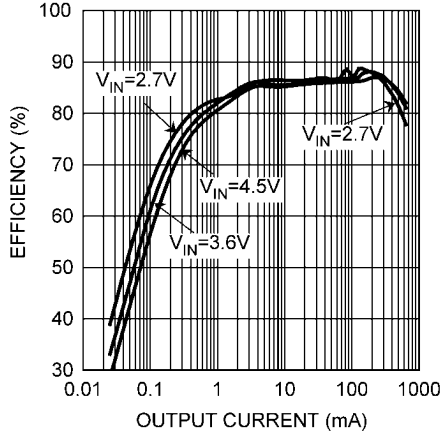
30008486

**Output Voltage vs. Output Current**  
( $V_{OUT} = 2.5V$ )



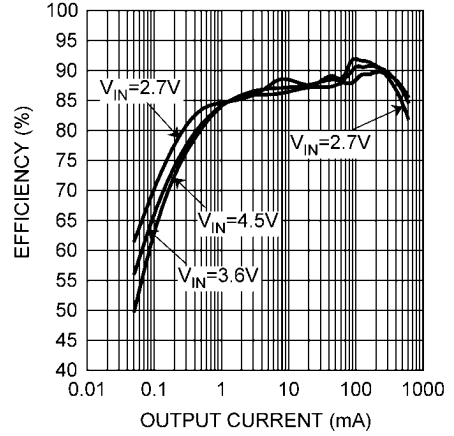
30008437

**Efficiency vs. Output Current**  
( $V_{OUT} = 1.3V$ )



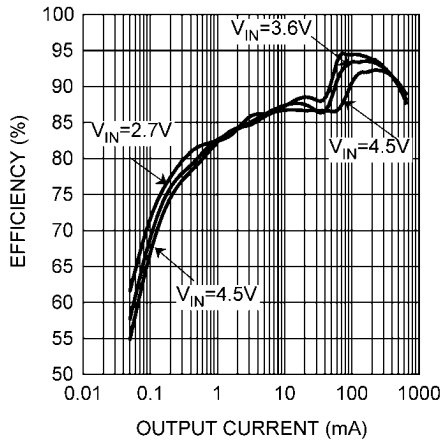
30008441

**Efficiency vs. Output Current**  
( $V_{OUT} = 1.8V$ )



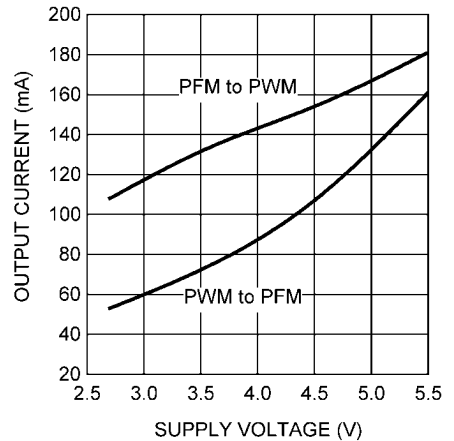
30008487

**Efficiency vs. Output Current**  
( $V_{OUT} = 2.5V$ )



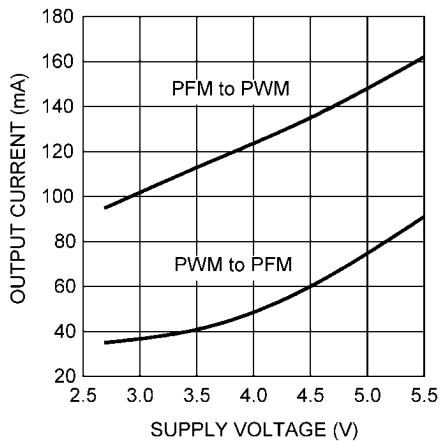
30008432

**Output Current vs. Input Voltage at Mode Change Point**  
( $V_{OUT} = 1.3V$ )



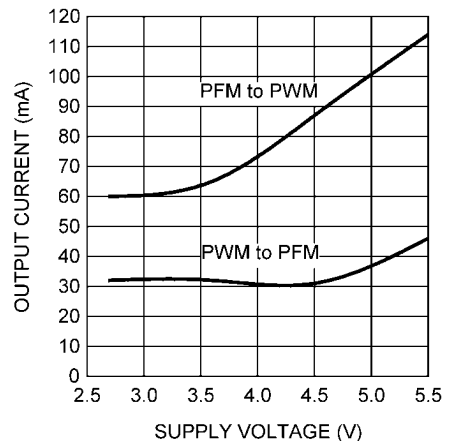
30008435

**Output Current vs. Input Voltage at Mode Change Point**  
( $V_{OUT} = 1.8V$ )



30008488

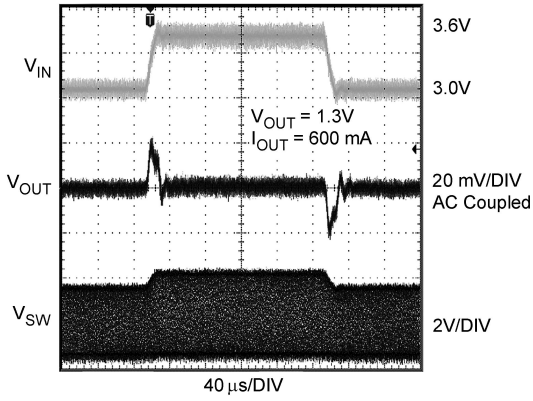
**Output Current vs. Input Voltage at Mode Change Point**  
( $V_{OUT} = 2.5V$ )



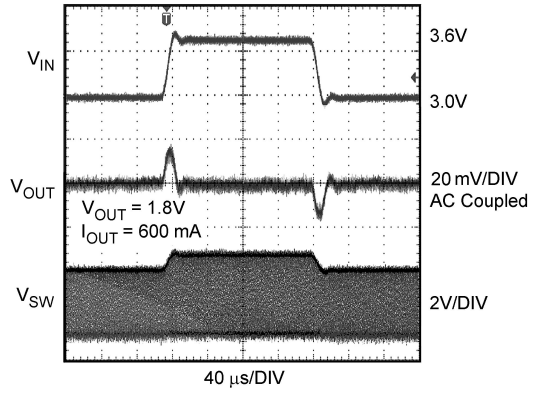
30008436



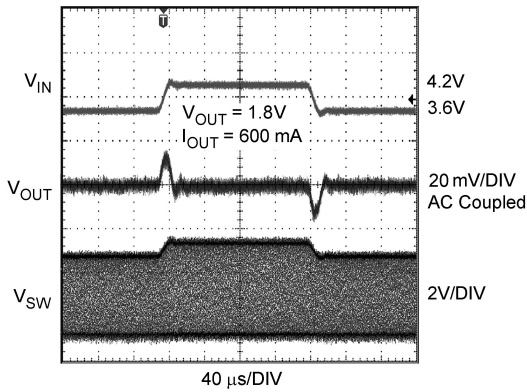
**Line Transient Response**  
 $V_{OUT} = 1.3V$  (PWM Mode)



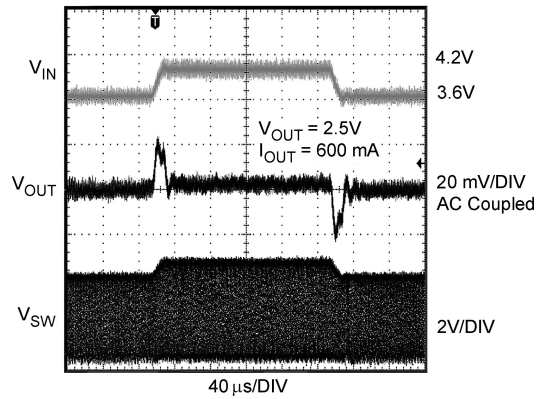
**Line Transient Response**  
 $V_{OUT} = 1.8V$  (PWM Mode)



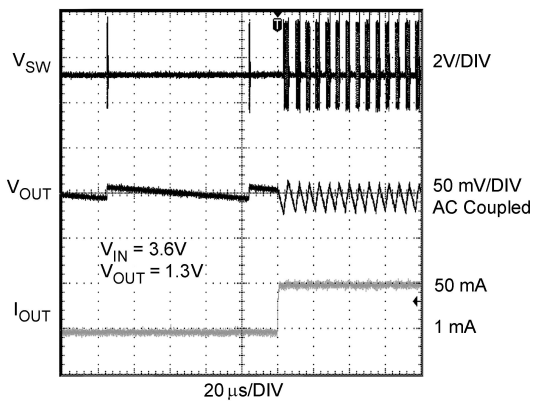
**Line Transient Response**  
 $V_{OUT} = 1.8V$  (PWM Mode)



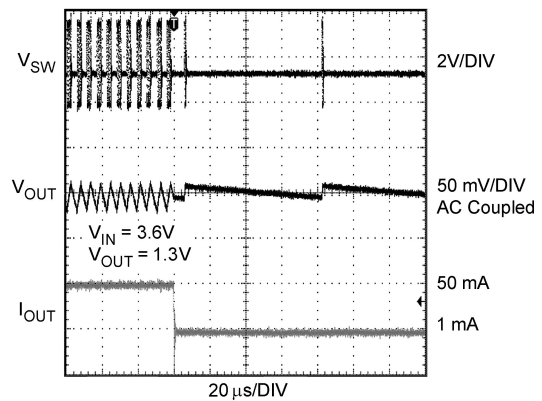
**Line Transient Response**  
 $V_{OUT} = 2.5V$  (PWM Mode)



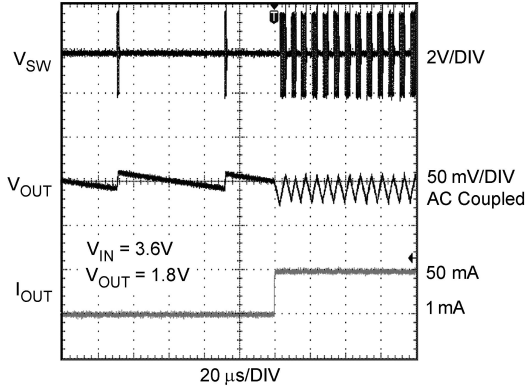
**Load Transient Response ( $V_{OUT} = 1.3V$ )**  
(PFM Mode 1mA to 50mA)



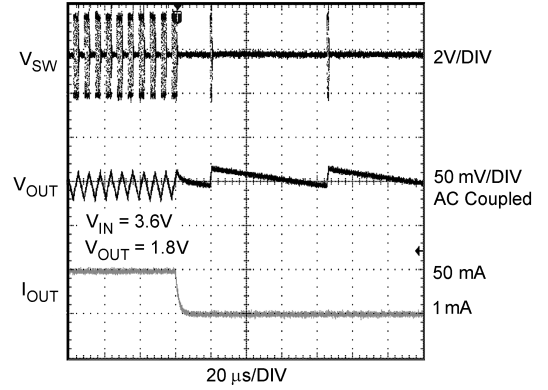
**Load Transient Response ( $V_{OUT} = 1.3V$ )**  
(PFM Mode 50mA to 1mA)



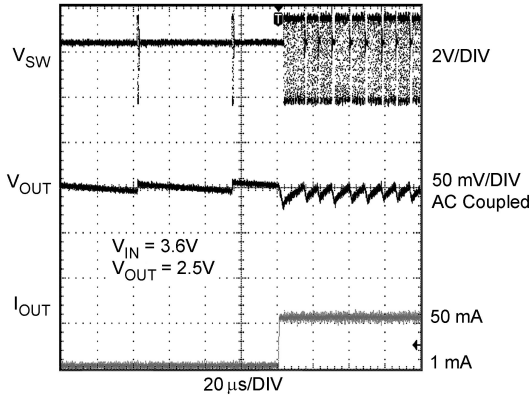
**Load Transient Response ( $V_{OUT} = 1.8V$ )  
(PFM Mode 1mA to 50mA)**



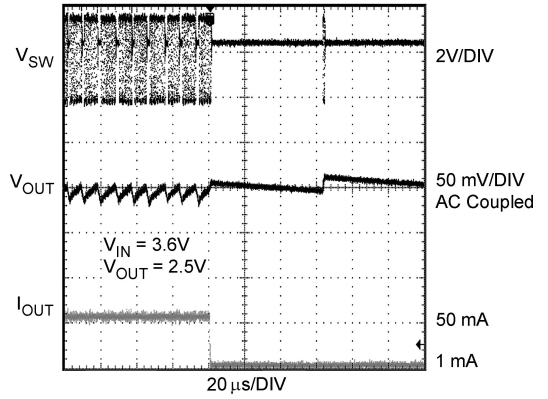
**Load Transient Response ( $V_{OUT} = 1.8V$ )  
(PFM Mode 50mA to 1mA)**



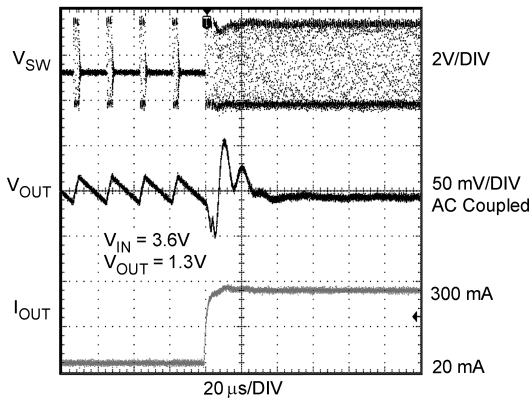
**Load Transient Response ( $V_{OUT} = 2.5V$ )  
(PFM Mode 1mA to 50mA)**



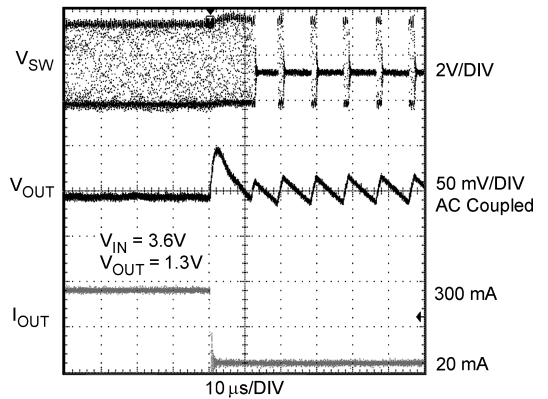
**Load Transient Response ( $V_{OUT} = 2.5V$ )  
(PFM Mode 50mA to 1mA)**



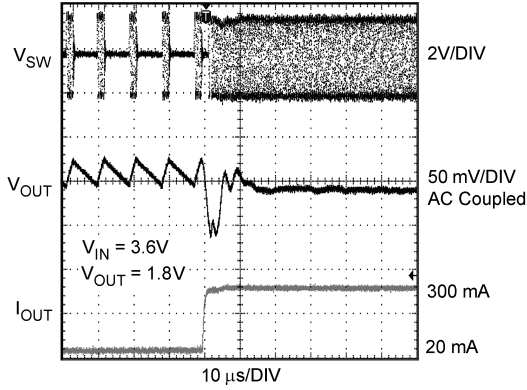
**Mode Change by Load Transients  
 $V_{OUT} = 1.3V$  (PFM to PWM)**



**Mode Change by Load Transients  
 $V_{OUT} = 1.3V$  (PWM to PFM)**

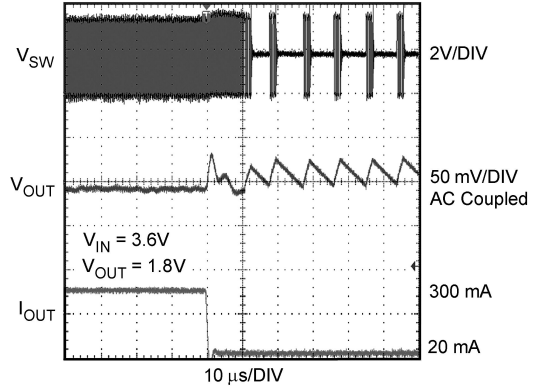


**Mode Change by Load Transients**  
 $V_{OUT} = 1.8V$  (PFM to PWM)



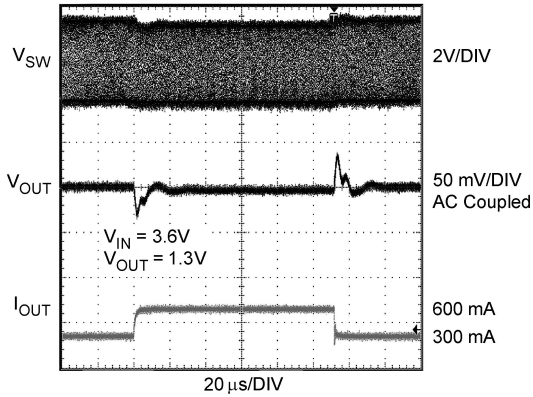
30008475

**Mode Change by Load Transients**  
 $V_{OUT} = 1.8V$  (PWM to PFM)



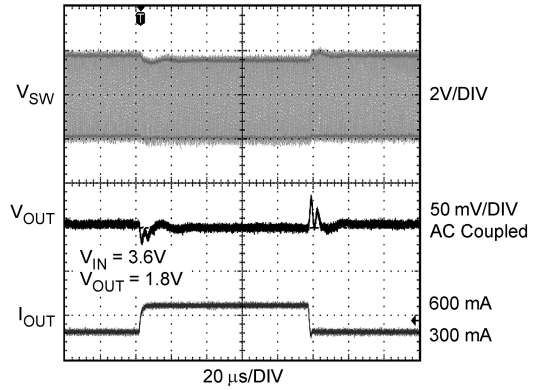
30008476

**Load Transient Response**  
 $V_{OUT} = 1.3V$  (PWM Mode)



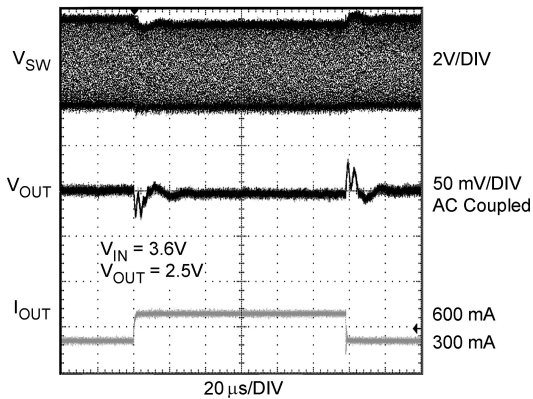
30008497

**Load Transient Response**  
 $V_{OUT} = 1.8V$  (PWM Mode)



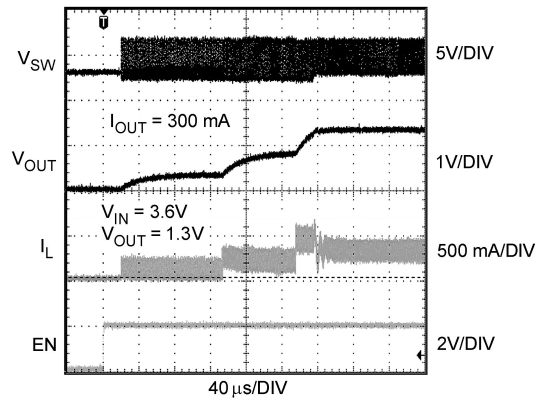
30008472

**Load Transient Response**  
 $V_{OUT} = 2.5V$  (PWM Mode)



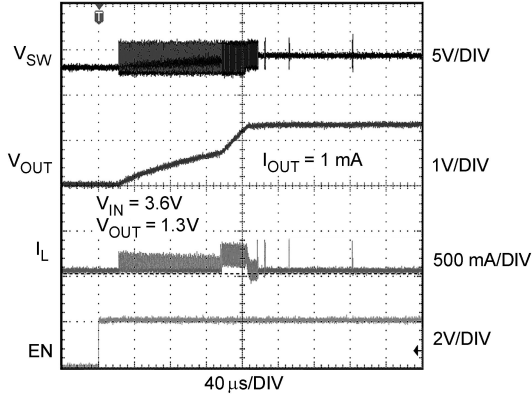
30008431

**Start Up into PWM Mode**  
 $V_{OUT} = 1.3V$  (Output Current= 300mA)

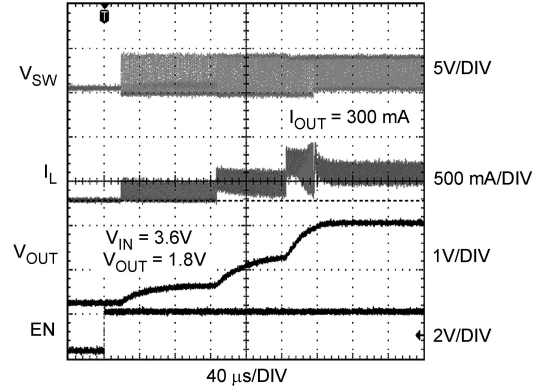


30008491

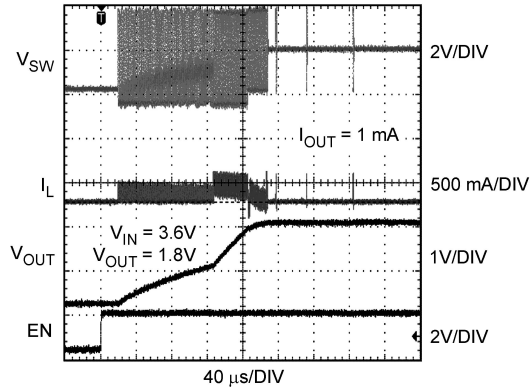
**Start Up into PFM Mode**  
 $V_{OUT} = 1.3V$  (Output Current= 1mA)



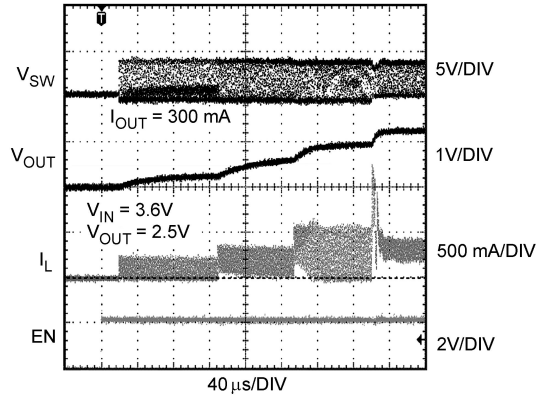
**Start Up into PWM Mode**  
 $V_{OUT} = 1.8V$  (Output Current= 300mA)



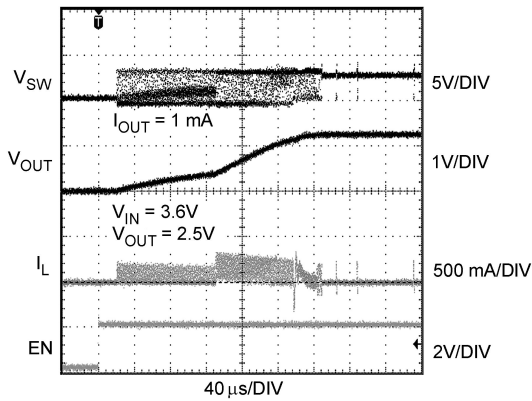
**Start Up into PFM Mode**  
 $V_{OUT} = 1.8V$  (Output Current= 1mA)



**Start Up into PWM Mode**  
 $V_{OUT} = 2.5V$  (Output Current= 300mA)



**Start Up into PFM Mode**  
 $V_{OUT} = 2.5V$  (Output Current= 1mA)



## Operation Description

### DEVICE INFORMATION

The LM3677, a high efficiency step down DC-DC switching buck converter, delivers a constant voltage from a single Li-Ion battery and input voltage rails from 2.7V to 5.5V such as cell phones and PDAs. Using a voltage mode architecture with synchronous rectification, the LM3677 has the ability to deliver up to 600mA depending on the input voltage and output voltage, ambient temperature, and the inductor chosen.

There are three modes of operation depending on the current required - PWM (Pulse Width Modulation), PFM (Pulse Frequency Modulation), and shutdown. The device operates in PWM mode at load current of approximately 80 mA or higher, having a voltage precision of  $\pm 2.5\%$  with 90% efficiency or better. Lighter load current causes the device to automatically switch into PFM mode for reduced current consumption ( $I_Q = 16 \mu\text{A typ}$ ) and a longer battery life. Shutdown mode turns off the device, offering the lowest current consumption ( $I_{\text{SHUTDOWN}} = 0.01 \mu\text{A typ}$ ).

Additional features include soft-start, under voltage protection, current overload protection, and thermal shutdown protection. As shown in *Figure 1*, only three external power components are required for implementation.

The part uses an internal reference voltage of 0.5V. It is recommended to keep the part in shutdown until the input voltage exceeds 2.7V.

### CIRCUIT OPERATION

The LM3677 operates as follows. During the first portion of each switching cycle, the control block in the LM3677 turns on the internal PFET switch. This allows current to flow from the input through the inductor to the output filter capacitor and load. The inductor limits the current to a ramp with a slope of  $(V_{\text{IN}} - V_{\text{OUT}})/L$ , by storing energy in a magnetic field.

During the second portion of each cycle, the controller turns the PFET switch off, blocking current flow from the input, and then turns the NFET synchronous rectifier on. The inductor draws current from ground through the NFET to the output filter capacitor and load, which ramps the inductor current down with a slope of  $-V_{\text{OUT}}/L$ .

The output filter stores charge when the inductor current is high, and releases it when inductor current is low, smoothing the voltage across the load.

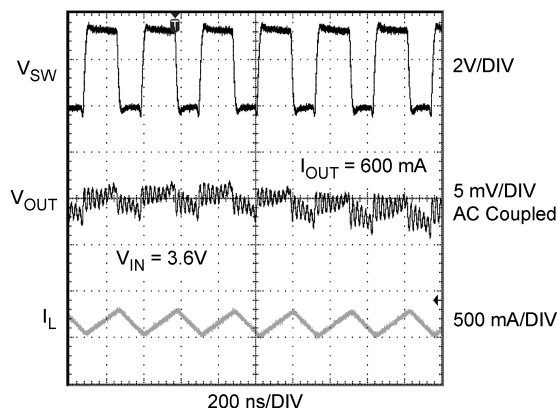
The output voltage is regulated by modulating the PFET switch on time to control the average current sent to the load. The effect is identical to sending a duty-cycle modulated rectangular wave formed by the switch and synchronous rectifier at the SW pin to a low-pass filter formed by the inductor and output filter capacitor. The output voltage is equal to the average voltage at the SW pin.

### PWM OPERATION

During PWM operation, the converter operates as a voltage-mode controller with input voltage feed forward. This allows the converter to achieve good load and line regulation. The DC gain of the power stage is proportional to the input voltage. To eliminate this dependence, feed forward inversely proportional to the input voltage is introduced.

While in PWM mode, the output voltage is regulated by switching at a constant frequency and then modulating the energy per cycle to control power to the load. At the beginning of each clock cycle the PFET switch is turned on and the inductor current ramps up until the comparator trips and the control logic turns off the switch. The current limit comparator

can also turn off the switch in case the current limit of the PFET is exceeded. Then the NFET switch is turned on and the inductor current ramps down. The next cycle is initiated by the clock turning off the NFET and turning on the PFET.



30008480

FIGURE 4. Typical PWM Operation

### Internal Synchronous Rectification

While in PWM mode, the LM3677 uses an internal NFET as a synchronous rectifier to reduce forward voltage drop and associated power loss. Synchronous rectification provides a significant improvement in efficiency whenever the output voltage is relatively low compared to the voltage drop across an ordinary rectifier diode.

### Current Limiting

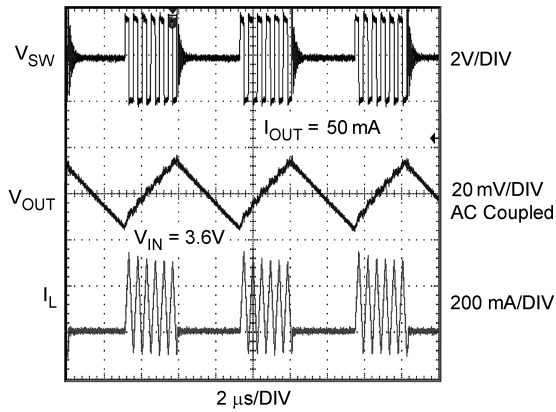
A current limit feature allows the LM3677 to protect itself and external components during overload conditions. PWM mode implements current limiting using an internal comparator that trips at 1220 mA (typ). If the output is shorted to ground the device enters a timed current limit mode where the NFET is turned on for a longer duration until the inductor current falls below a low threshold, ensuring inductor current has more time to decay, thereby preventing runaway.

### PFM OPERATION

At very light loads, the converter enters PFM mode and operates with reduced switching frequency and supply current to maintain high efficiency.

The part will automatically transition into PFM mode when either of the following conditions occurs for a duration of 32 or more clock cycles:

- A. The NFET current reaches zero.
- B. The peak PMOS switch current drops below the  $I_{\text{MODE}}$  level, (Typically  $I_{\text{MODE}} < 75\text{mA} + V_{\text{IN}}/55 \Omega$ ).



30008479

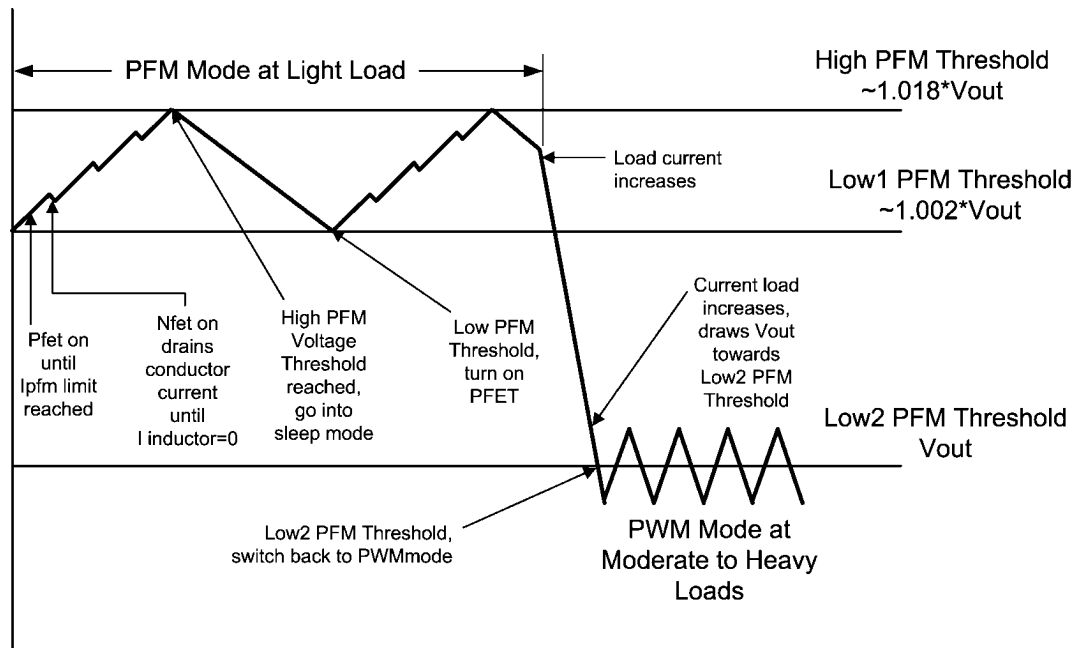
**FIGURE 5. Typical PFM Operation**

During PFM operation, the converter positions the output voltage slightly higher than the nominal output voltage during PWM operation allowing additional headroom for voltage drop during a load transient from light to heavy load. The PFM comparators sense the output voltage via the feedback pin and control the switching of the output FETs such that the output voltage ramps between  $\sim 0.2\%$  and  $\sim 1.8\%$  above the nominal PWM output voltage. If the output voltage is below the 'high' PFM comparator threshold, the PMOS power switch

is turned on. It remains on until the output voltage reaches the 'high' PFM threshold or the peak current exceeds the  $I_{PFM}$  level set for PFM mode. The typical peak current in PFM mode is:  $I_{PFM} = 112\text{mA} + V_{IN}/20\Omega$ .

Once the PMOS power switch is turned off, the NMOS power switch is turned on until the inductor current ramps to zero. When the NMOS zero-current condition is detected, the NMOS power switch is turned off. If the output voltage is below the 'high' PFM comparator threshold (see Figure 6), the PMOS switch is again turned on and the cycle is repeated until the output reaches the desired level. Once the output reaches the 'high' PFM threshold, the NMOS switch is turned on briefly to ramp the inductor current to zero and then both output switches are turned off and the part enters an extremely low power mode. Quiescent supply current during this 'sleep' mode is  $16\mu\text{A}$  (typ), which allows the part to achieve high efficiencies under extremely light load conditions.

If the load current should increase during PFM mode (Figure 6) causing the output voltage to fall below the 'low2' PFM threshold, the part will automatically transition into fixed-frequency PWM mode. When  $V_{IN}=2.7\text{V}$  the part transitions from PWM to PFM mode at  $\sim 35\text{mA}$  output current and from PFM to PWM mode at  $\sim 95\text{mA}$ , when  $V_{IN}=3.6\text{V}$ , PWM to PFM transition occurs at  $\sim 42\text{mA}$  and PFM to PWM transition occurs at  $\sim 115\text{mA}$ , when  $V_{IN}=4.5\text{V}$ , PWM to PFM transition occurs at  $\sim 60\text{mA}$  and PFM to PWM transition occurs at  $\sim 135\text{mA}$ .



30008403

**FIGURE 6. Operation in PFM Mode and Transfer to PWM Mode**

### SHUTDOWN MODE

Setting the EN input pin low ( $<0.4\text{V}$ ) places the LM3677 in shutdown mode. During shutdown the PFET switch, NFET switch, reference, control and bias circuitry of the LM3677 are turned off. Setting EN high ( $>1.0\text{V}$ ) enables normal operation. It is recommended to set EN pin low to turn off the LM3677 during system power up and undervoltage conditions when the supply is less than  $2.7\text{V}$ . Do not leave the EN pin floating.

### SOFT START

The LM3677 has a soft-start circuit that limits in-rush current during start-up. During start-up the switch current limit is increased in steps. Soft start is activated only if EN goes from logic low to logic high after  $V_{IN}$  reaches  $2.7\text{V}$ . Soft start is implemented by increasing switch current limit in steps of  $200\text{mA}$ ,  $400\text{mA}$ ,  $600\text{mA}$  and  $1220\text{mA}$  (typical switch current limit). The start-up time thereby depends on the output capacitor and load current demanded at start-up. Typical start-

up times with a 10 $\mu$ F output capacitor and 300mA load is 300  $\mu$ s and with 1mA load is 200 $\mu$ s.

## Application Information

### INDUCTOR SELECTION

There are two main considerations when choosing an inductor; the inductor should not saturate, and the inductor current ripple should be small enough to achieve the desired output voltage ripple. Different saturation current rating specifications are followed by different manufacturers so attention must be given to details. Saturation current ratings are typically specified at 25°C. However, ratings at the maximum ambient temperature of application should be requested from the manufacturer. **The minimum value of inductance to guarantee good performance is 0.7 $\mu$ H at  $I_{LIM}$  (typ) dc current over the ambient temperature range.** Shielded inductors radiate less noise and should be preferred.

There are two methods to choose the inductor saturation current rating.

#### Method 1:

The saturation current is greater than the sum of the maximum load current and the worst case average to peak inductor current. This can be written as

$$I_{SAT} > I_{OUTMAX} + I_{RIPPLE}$$

$$\text{where } I_{RIPPLE} = \left( \frac{V_{IN} - V_{OUT}}{2 * L} \right) * \left( \frac{V_{OUT}}{V_{IN}} \right) * \left( \frac{1}{f} \right)$$

- $I_{RIPPLE}$ : average to peak inductor current
- $I_{OUTMAX}$ : maximum load current (600mA)
- $V_{IN}$ : maximum input voltage in application
- $L$ : min inductor value including worst case tolerances (30% drop can be considered for method 1)
- $f$ : minimum switching frequency (2.5MHz)
- $V_{OUT}$ : output voltage

#### Method 2:

A more conservative and recommended approach is to choose an inductor that has saturation current rating greater than the max current limit of 1375mA.

A 1.0  $\mu$ H inductor with a saturation current rating of at least 1375 mA is recommended for most applications. The inductor's resistance should be less than 0.15 $\Omega$  for good efficiency. *Table 1* lists suggested inductors and suppliers. For low-cost applications, an unshielded bobbin inductor could be considered. For noise critical applications, a toroidal or shielded-bobbin inductor should be used. A good practice is to lay out the board with overlapping footprints of both types for design flexibility. This allows substitution of a low-noise shielded inductor in the event that noise from low-cost bobbin models is unacceptable.

### INPUT CAPACITOR SELECTION

A ceramic input capacitor of 4.7  $\mu$ F, 6.3V is sufficient for most applications. Place the input capacitor as close as possible to the  $V_{IN}$  pin of the device. A larger value may be used for improved input voltage filtering. Use X7R or X5R types; do not use Y5V. DC bias characteristics of ceramic capacitors must be considered when selecting case sizes like 0603 and 0805. **The minimum input capacitance to guarantee good performance is 2.2 $\mu$ F at 3V dc bias; 1.5 $\mu$ F at 5V dc bias including tolerances and over ambient temperature range.** The input filter capacitor supplies current to the PFET switch of the LM3677 in the first half of each cycle and reduces voltage ripple imposed on the input power source. A ceramic capacitor's low ESR provides the best noise filtering of the input voltage spikes due to this rapidly changing current. Select a capacitor with sufficient ripple current rating. The input current ripple can be calculated as:

$$I_{RMS} = I_{OUTMAX} * \sqrt{\frac{V_{OUT}}{V_{IN}} * \left( 1 - \frac{V_{OUT}}{V_{IN}} + \frac{r^2}{12} \right)}$$

$$r = \frac{(V_{IN} - V_{OUT}) * V_{OUT}}{L * f * I_{OUTMAX} * V_{IN}}$$

The worst case is when  $V_{IN} = 2 * V_{OUT}$

TABLE 1. Suggested Inductors and Their Suppliers

Model	Vendor	Dimensions LxWxH(mm)	D.C.R (max)
MIPSA2520D 1R0	FDK	2.5 x 2.0 x 1.2	100 mΩ
LQM2HP 1R0	Murata	2.5 x 2.0 x 0.95	100 mΩ
BRL2518T1R0M	Taiyo Yuden	2.5x 1.8 x 1.2	80 mΩ

**OUTPUT CAPACITOR SELECTION**

A ceramic output capacitor of 10 μF, 6.3V is sufficient for most applications. Use X7R or X5R types; do not use Y5V. DC bias characteristics of ceramic capacitors must be considered when selecting case sizes like 0603 and 0805. DC bias characteristics vary from manufacturer to manufacturer and dc bias curves should be requested from them as part of the capacitor selection process.

**The minimum output capacitance to guarantee good performance is 5.75μF at 2.5V dc bias including tolerances and over ambient temperature range.** The output filter capacitor smoothes out current flow from the inductor to the load, helps maintain a steady output voltage during transient load changes and reduces output voltage ripple. These capacitors must be selected with sufficient capacitance and sufficiently low ESR to perform these functions.

The output voltage ripple is caused by the charging and discharging of the output capacitor and by the  $R_{ESR}$  and can be calculated as:

Voltage peak-to-peak ripple due to capacitance can be expressed as follows

$$V_{PP-C} = \frac{I_{RIPPLE}}{4 * f * C}$$

Voltage peak-to-peak ripple due to ESR can be expressed as follows

$$V_{PP-ESR} = (2 * I_{RIPPLE}) * R_{ESR}$$

Because these two components are out of phase the rms (root mean squared) value can be used to get an approximate value of peak-to-peak ripple.

Voltage peak-to-peak ripple,rms can be expressed as follow:

$$V_{PP-RMS} = \sqrt{V_{PP-C}^2 + V_{PP-ESR}^2}$$

Note that the output voltage ripple is dependent on the inductor current ripple and the equivalent series resistance of the output capacitor ( $R_{ESR}$ ).

The  $R_{ESR}$  is frequency dependent (as well as temperature dependent); make sure the value used for calculations is at the switching frequency of the part.

TABLE 2. Suggested Capacitors and Their Suppliers

Model	Type	Vendor	Voltage Rating	Case Size Inch (mm)
<b>4.7 μF for C<sub>IN</sub></b>				
C1608X5R0J475	Ceramic, X5R	TDK	6.3V	0603 (1608)
C2012X5R0J475	Ceramic, X5R	TDK	6.3V	0805 (2012)
GRM21BR60J475	Ceramic, X5R	muRata	6.3V	0805 (2012)
JMK212BJ475	Ceramic, X5R	Taiyo-Yuden	6.3V	0805 (2012)
<b>10 μF for C<sub>OUT</sub></b>				
C1608X5R0J106	Ceramic, X5R	TDK	6.3V	0603 (1608)
C2012X5R0J106	Ceramic, X5R	TDK	6.3V	0805 (2012)
GRM21BR60J106	Ceramic, X5R	muRata	6.3V	0805 (2012)
JMK212BJ106	Ceramic, X5R	Taiyo-Yuden	6.3V	0805 (2012)

**Micro SMD PACKAGE ASSEMBLY AND USE**

Use of the Micro SMD package requires specialized board layout, precision mounting and careful re-flow techniques, as detailed in National Semiconductor Application Note 1112. Refer to the section "Surface Mount Technology (SMD) Assembly Considerations". For best results in assembly, alignment ordinals on the PC board should be used to facilitate placement of the device. The pad style used with Micro SMD package must be the NSMD (non-solder mask defined) typ. This means that the solder-mask opening is larger than the pad size. This prevents a lip that otherwise forms if the solder-mask and pad overlap, from holding the device off the surface of the board and interfering with mounting. See Application Note 1112 for specific instructions how to do this. The 5-Bump

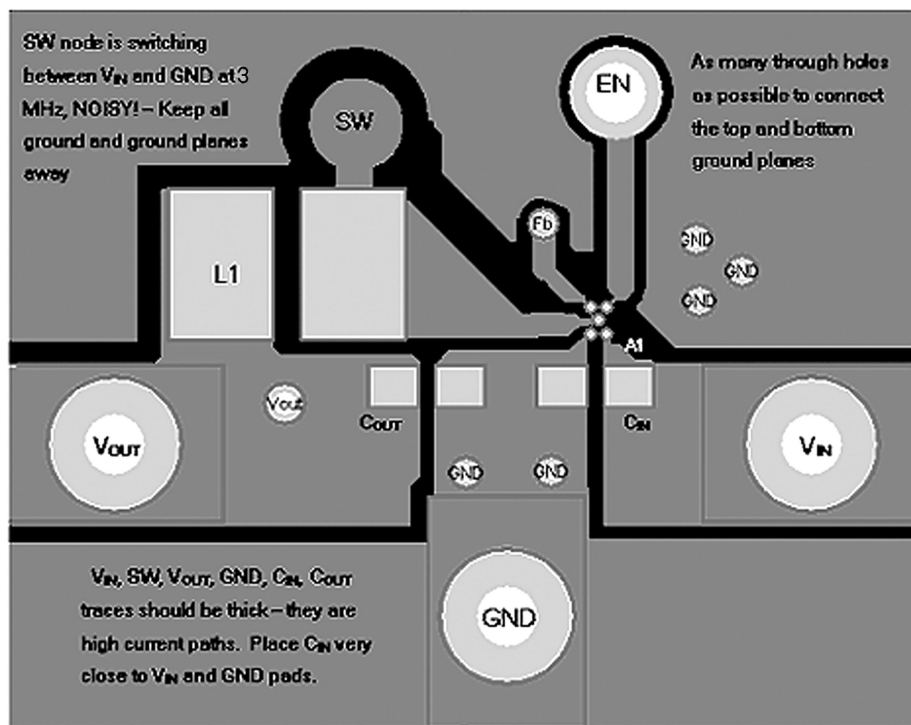
package used for LM3677 has 300 micron solder balls and requires 10.82 mils pads for mounting on the circuit board. The trace to each pad should enter the pad with a 90° entry angle to prevent debris from being caught in deep corners. Initially, the trace to each pad should be 7 mil wide, for a section approximately 7 mil long or longer, as a thermal relief. Then each trace should neck up or down to its optimal width. The important criteria is symmetry. This ensures the solder bumps on the LM3677 re-flow evenly and that the device solders level to the board. In particular, special attention must be paid to the pads for bumps A1 and A3, because GND and  $V_{IN}$  are typically connected to large copper planes, inadequate thermal relief can result in late or inadequate re-flow of these bumps.



The Micro SMD package is optimized for the smallest possible size in applications with red or infrared opaque cases. Because the Micro SMD package lacks the plastic encapsulation characteristic of larger devices, it is vulnerable to light. Backside metallization and/or epoxy coating, along with front-side shading by the printed circuit board, reduce this sensitivity. However, the package has exposed die edges. In particular, Micro SMD devices are sensitive to light, in the red and infrared range, shining on the package's exposed die edges.

## BOARD LAYOUT CONSIDERATIONS

PC board layout is an important part of DC-DC converter design. Poor board layout can disrupt the performance of a DC-DC converter and surrounding circuitry by contributing to EMI, ground bounce, and resistive voltage loss in the traces. These can send erroneous signals to the DC-DC converter IC, resulting in poor regulation or instability. Poor layout can also result in re-flow problems leading to poor solder joints between the Micro SMD package and board pads. Poor solder joints can result in erratic or degraded performance.



30008454

FIGURE 7. Board Layout Design Rules for the LM3677

Good layout for the LM3677 can be implemented by following a few simple design rules, as illustrated in Figure.

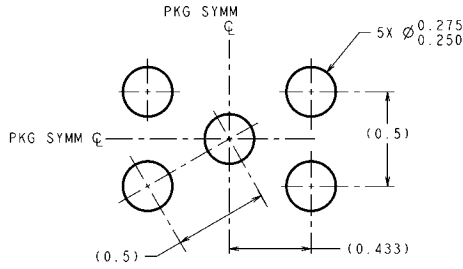
1. Place the LM3677 on 10.82 mil pads. As a thermal relief, connect to each pad with a 7 mil wide, approximately 7 mil long trace, and then incrementally increase each trace to its optimal width. The important criterion is symmetry to ensure the solder bumps on the re-flow evenly (see *Micro SMD Package Assembly and Use*).
2. Place the LM3677, inductor and filter capacitors close together and make the traces short. The traces between these components carry relatively high switching currents and act as antennas. Following this rule reduces radiated noise. Special care must be given to place the input filter capacitor very close to the  $V_{IN}$  and GND pin.
3. Arrange the components so that the switching current loops curl in the same direction. During the first half of each cycle, current flows from the input filter capacitor, through the LM3677 and inductor to the output filter capacitor and back through ground, forming a current loop. In the second half of each cycle, current is pulled up from ground, through the LM3677 by the inductor, to the output filter capacitor and then back through ground, forming a second current loop. Routing these loops so the current curls in the same direction prevents magnetic field reversal between the two half-cycles and reduces radiated noise.
4. Connect the ground pins of the LM3677, and filter capacitors together using generous component-side copper fill as a pseudo-ground plane. Then connect this to the ground-plane (if one is used) with several vias. This reduces ground-plane noise by preventing the switching currents from circulating through the ground plane. It also reduces ground bounce at the LM3677 by giving it a low-impedance ground connection.
5. Use wide traces between the power components and for power connections to the DC-DC converter circuit. This reduces voltage errors caused by resistive losses across the traces.
6. Route noise sensitive traces such as the voltage feedback pathway from noisy traces between the power components. The voltage feedback trace must remain close to the LM3677 circuit and should be routed directly from FB to  $V_{OUT}$  at the output capacitor and should be routed opposite to noise components. This reduces EMI radiated onto the DC-DC converter's own voltage feedback trace.

7. Place noise sensitive circuitry, such as radio IF blocks, away from the DC-DC converter, CMOS digital blocks and other noisy circuitry. Interference with noise-sensitive circuitry in the system can be reduced through distance.

In mobile phones, for example, a common practice is to place the DC-DC converter on one corner of the board, arrange the

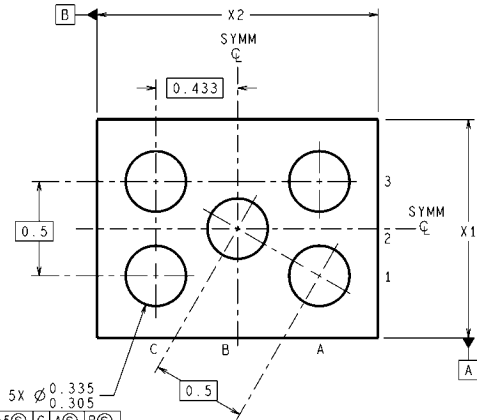
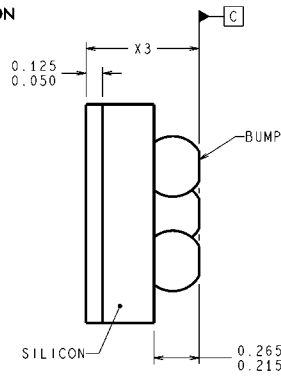
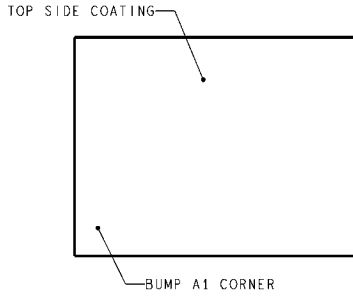
CMOS digital circuitry around it (since this also generates noise), and then place sensitive preamplifiers and IF stages on the diagonally opposing corner. Often, the sensitive circuitry is shielded with a metal pan and power to it is post-regulated to reduce conducted noise, using low-dropout linear regulators.

**Physical Dimensions** inches (millimeters) unless otherwise noted



**DIMENSIONS ARE IN MILLIMETERS**  
DIMENSIONS IN ( ) FOR REFERENCE ONLY

**LAND PATTERN RECOMMENDATION**



TLA05XXX (Rev C)

**5-Bump (Large) Micro SMD Package, 0.5mm Pitch**  
**NS Package Number TLA05FEA**

The dimensions for X1, X2, and X3 are as given:

X1 = 1.107 mm +/- 0.030mm

X2 = 1.488 mm +/- 0.030mm

X3 = 0.600 mm +/- 0.075mm

## Notes

THE CONTENTS OF THIS DOCUMENT ARE PROVIDED IN CONNECTION WITH NATIONAL SEMICONDUCTOR CORPORATION ("NATIONAL") PRODUCTS. NATIONAL MAKES NO REPRESENTATIONS OR WARRANTIES WITH RESPECT TO THE ACCURACY OR COMPLETENESS OF THE CONTENTS OF THIS PUBLICATION AND RESERVES THE RIGHT TO MAKE CHANGES TO SPECIFICATIONS AND PRODUCT DESCRIPTIONS AT ANY TIME WITHOUT NOTICE. NO LICENSE, WHETHER EXPRESS, IMPLIED, ARISING BY ESTOPPEL OR OTHERWISE, TO ANY INTELLECTUAL PROPERTY RIGHTS IS GRANTED BY THIS DOCUMENT.

TESTING AND OTHER QUALITY CONTROLS ARE USED TO THE EXTENT NATIONAL DEEMS NECESSARY TO SUPPORT NATIONAL'S PRODUCT WARRANTY. EXCEPT WHERE MANDATED BY GOVERNMENT REQUIREMENTS, TESTING OF ALL PARAMETERS OF EACH PRODUCT IS NOT NECESSARILY PERFORMED. NATIONAL ASSUMES NO LIABILITY FOR APPLICATIONS ASSISTANCE OR BUYER PRODUCT DESIGN. BUYERS ARE RESPONSIBLE FOR THEIR PRODUCTS AND APPLICATIONS USING NATIONAL COMPONENTS. PRIOR TO USING OR DISTRIBUTING ANY PRODUCTS THAT INCLUDE NATIONAL COMPONENTS, BUYERS SHOULD PROVIDE ADEQUATE DESIGN, TESTING AND OPERATING SAFEGUARDS.

EXCEPT AS PROVIDED IN NATIONAL'S TERMS AND CONDITIONS OF SALE FOR SUCH PRODUCTS, NATIONAL ASSUMES NO LIABILITY WHATSOEVER, AND NATIONAL DISCLAIMS ANY EXPRESS OR IMPLIED WARRANTY RELATING TO THE SALE AND/OR USE OF NATIONAL PRODUCTS INCLUDING LIABILITY OR WARRANTIES RELATING TO FITNESS FOR A PARTICULAR PURPOSE, MERCHANTABILITY, OR INFRINGEMENT OF ANY PATENT, COPYRIGHT OR OTHER INTELLECTUAL PROPERTY RIGHT.

### LIFE SUPPORT POLICY

**NATIONAL'S PRODUCTS ARE NOT AUTHORIZED FOR USE AS CRITICAL COMPONENTS IN LIFE SUPPORT DEVICES OR SYSTEMS WITHOUT THE EXPRESS PRIOR WRITTEN APPROVAL OF THE CHIEF EXECUTIVE OFFICER AND GENERAL COUNSEL OF NATIONAL SEMICONDUCTOR CORPORATION.** As used herein:

Life support devices or systems are devices which (a) are intended for surgical implant into the body, or (b) support or sustain life and whose failure to perform when properly used in accordance with instructions for use provided in the labeling can be reasonably expected to result in a significant injury to the user. A critical component is any component in a life support device or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system or to affect its safety or effectiveness.

National Semiconductor and the National Semiconductor logo are registered trademarks of National Semiconductor Corporation. All other brand or product names may be trademarks or registered trademarks of their respective holders.

Copyright© 2007 National Semiconductor Corporation

For the most current product information visit us at [www.national.com](http://www.national.com)



**National Semiconductor  
Americas Customer  
Support Center**  
Email:  
[new.feedback@nsc.com](mailto:new.feedback@nsc.com)  
Tel: 1-800-272-9959

**National Semiconductor Europe  
Customer Support Center**  
Fax: +49 (0) 180-530-85-86  
Email: [europe.support@nsc.com](mailto:europe.support@nsc.com)  
Deutsch Tel: +49 (0) 69 9508 6208  
English Tel: +49 (0) 870 24 0 2171  
Français Tel: +33 (0) 1 41 91 8790

**National Semiconductor Asia  
Pacific Customer Support Center**  
Email: [ap.support@nsc.com](mailto:ap.support@nsc.com)

**National Semiconductor Japan  
Customer Support Center**  
Fax: 81-3-5639-7507  
Email: [jpn.feedback@nsc.com](mailto:jpn.feedback@nsc.com)  
Tel: 81-3-5639-7560