#### *Data Sheet February 12, 2007*

# *FN7516.2*

# *Dual Channel Differential VDSL2 Line Driver*

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The ISL1539 is to be used for high performance long reach and high speed applications, including ADSL2, ADSL2+, and VDSL2 20dBm.

The ISL1539 is an integral part of the signal chain. The driver has been optimized for flat gain response and reduced harmonic distortion and noise in the bands of interest to improve the overall signal to noise in the system.

These drivers achieve a total harmonic distortion (THD) measurement of typically -60dB MTPR @ 1.1MHz, while consuming typically 10mA per DSL channel of total supply current. This supply current can be set using a resistor on the  $I_{ADJ}$  pin. Two other pins (C<sub>0</sub> and C<sub>1</sub>) can also be used to adjust supply current to one of four pre-set modes (full-I<sub>S</sub>, 3/4-I<sub>S</sub>, 1/2-I<sub>S</sub>, and full power-down). The ISL1539 operates on ±5V to ±15V supplies and retains its bandwidth and linearity over the complete supply range.

The device is supplied in the small footprint (4mmx5mm) 24 Ld QFN package and is specified for operation over the full -40°C to +85°C temperature range.

### *Pinouts*



#### *Features*

- 450mA output drive capability
- 44.1 $V_{\text{P-P}}$  differential output drive into 100 $\Omega$
- $-85$ dBc THD @ 1MHz 2V<sub>P-P</sub>
- High slew rate of 1200V/µs differential
- Bandwidth 80MHz  $@$  A<sub>V</sub> = 10
- Current control pins
- Channel separation
	- 80dB @ 500kHz
	- 75dB @ 1MHz
	- 60dB @ 4MHz
- Pb-free plus anneal available (RoHS compliant)

#### *Applications*

- VDSL2 20dBm
- ADSL2++





### *Ordering Information*



NOTE: Intersil Pb-free plus anneal products employ special Pb-free material sets; molding compounds/die attach materials and 100% matte tin plate termination finish, which are RoHS compliant and compatible with both SnPb and Pb-free soldering operations. Intersil Pb-free products are MSL classified at Pb-free peak reflow temperatures that meet or exceed the Pb-free requirements of IPC/JEDEC J STD-020.

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#### **Absolute Maximum Ratings** (TA = +25°C)





*CAUTION: Stresses above those listed in "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress only rating and operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied.*

*IMPORTANT NOTE: All parameters having Min/Max specifications are guaranteed. Typ values are for information purposes only. Unless otherwise noted, all tests are at the specified temperature and are pulsed tests, therefore:*  $T_J = T_C = T_A$ 





# *ISL1539*



# *Pin Descriptions*

![](_page_3_Picture_224.jpeg)

![](_page_4_Picture_149.jpeg)

![](_page_4_Picture_150.jpeg)

NOTES:

<span id="page-4-0"></span>1.  $I_{ADJ}$  controls bias current  $(I_S)$  setting for both DSL channels.

<span id="page-4-1"></span>2. Amplifiers C and D comprise DSL channel #2.  $C_{0CD}$  and  $C_{1CD}$  control  $I_S$  settings for DSL channel #2.

<span id="page-4-2"></span>3. Amplifiers A and B comprise DSL channel #1.  $C_{0AB}$  and  $C_{1AB}$  control  $I_S$  settings for DSL channel #1.

![](_page_5_Figure_1.jpeg)

![](_page_5_Figure_2.jpeg)

**FIGURE 1. FREQUENCY RESPONSE FOR VARIOUS RF (FULL POWER MODE)**

 $12$ 

![](_page_5_Figure_4.jpeg)

**FIGURE 2. FREQUENCY RESPONSE FOR VARIOUS RF (HALF POWER MODE)**

![](_page_5_Figure_6.jpeg)

**FIGURE 4. COMMON MODE FREQUENCY RESPONSE FOR VARIOUS R<sub>F</sub> (FULL POWER MODE)** 

![](_page_5_Figure_8.jpeg)

**FIGURE 6. 200kHz 2ND AND 3RD HARMONIC DISTORTION vs VOLTAGE OUTPUT (HALF POWER MODE)**

![](_page_5_Figure_10.jpeg)

![](_page_5_Figure_11.jpeg)

![](_page_5_Figure_12.jpeg)

#### *Typical Performance Curves* **(Continued)**

![](_page_6_Figure_2.jpeg)

**FIGURE 7. 1MHz 2ND AND 3RD HARMONIC DISTORTION vs OUTPUT VOLTAGE (FULL POWER MODE)**

![](_page_6_Figure_4.jpeg)

**FIGURE 8. 1MHz 2ND AND 3RD HARMONIC DISTORTION vs OUPUT VOLTAGE (HALF POWER MODE)**

![](_page_6_Figure_6.jpeg)

**FIGURE 10. 3.75MHz 2ND AND 3RD HARMONIC DISTORTION vs OUTPUT VOLTAGE (HALF POWER MODE)**

![](_page_6_Figure_8.jpeg)

**FIGURE 12. TOTAL HARMONIC DISTORTION FOR VARIOUS FREQUENCIES (FULL POWER MODE)**

![](_page_6_Figure_10.jpeg)

**FIGURE 9. 3.75MHz 2ND AND 3RD HARMONIC DISTORTION vs OUTPUT VOLTAGE (FULL POWER MODE)**

![](_page_6_Figure_12.jpeg)

**FIGURE 11. 10MHz 2ND AND 3RD HARMONIC DISTORTION vs OUTPUT VOLTAGE (FULL POWER MODE)**

### *Typical Performance Curves* **(Continued)**

![](_page_7_Figure_2.jpeg)

**FIGURE 13. FREQUENCY RESPONSE FOR VARIOUS RADJ FIGURE 14. SUPPLY CURRENT vs RADJ FOR VARIOUS** 

![](_page_7_Figure_4.jpeg)

**POWER MODE**

![](_page_7_Figure_6.jpeg)

#### *Typical Performance Curves* (Continued)

![](_page_8_Figure_2.jpeg)

**FIGURE 19. PACKAGE POWER DISSIPATION vs AMBIENT TEMPERATURE**

### *Application Information*

The ISL1539 consists of two sets of high-power line driver amplifiers that can be connected for full duplex differential line transmission. The amplifiers are designed to be used with signals up to 30MHz and produce low distortion levels. A typical interface circuit is shown in Figure [20](#page-8-0) below.

![](_page_8_Figure_6.jpeg)

<span id="page-8-0"></span>**FIGURE 20. TYPICAL LINE INTERFACE CONNECTION**

The amplifiers are wired with one in positive gain and the other in a negative gain configuration to generate a differential output for a single-ended input. They will exhibit very similar frequency responses for gains of three or greater and thus generate very small common-mode outputs over frequency, but for low gains the two drivers RF's need to be adjusted to give similar frequency responses. The positive-gain driver will generally exhibit more bandwidth and peaking than the negative-gain driver.

If a differential signal is available to the drive amplifiers, they may be wired so:

![](_page_8_Figure_10.jpeg)

**FIGURE 21. DRIVERS WIRED FOR DIFFERENTIAL INPUT**

Each amplifier has identical positive gain connections, and optimum common-mode rejection occurs. Further, DC input errors are duplicated and create common-mode rather than differential line errors.

#### *Power Supplies and Dissipation*

Due to the high power drive capability of the ISL1539, much attention needs to be paid to power dissipation. The power that needs to be dissipated in the ISL1539 has two main contributors. The first is the quiescent current dissipation. The second is the dissipation of the output stage.

The quiescent power in the ISL1539 is not constant with varying outputs. In reality, 7mA of the 15mA needed to power the drivers is converted in to output current. Therefore, in the equation below we should subtract the average output current,  $I_O$ , or 7mA, whichever is the lowest. We'll call this term  $I_X$ .

Therefore, we can determine a quiescent current with the following equation:

$$
P_{Dquiescent} = V_S \times (I_S - 2I_X)
$$
 (EQ. 1)

where:

- $V_S$  is the supply voltage ( $V_S$ + to  $V_S$ -)
- $\lg$  is the maximum quiescent supply current ( $\lg$ + +  $\lg$ -)
- $I_X$  is the lesser of  $I_O$  or 7mA (generally  $I_X = 7$ mA)

The dissipation in the output stage has two main contributors. Firstly, we have the average voltage drop across the output transistor and secondly, the average output current. For minimal power dissipation, the user should select the supply voltage and the line transformer ratio accordingly. The supply voltage should be kept as low as possible, while the transformer ratio should be selected so that the peak voltage required from the ISL1539 is close to the maximum available output swing. There is a trade off, however, with the selection of transformer ratio. As the ratio is increased, the receive signal available to the receivers is reduced.

Once the user has selected the transformer ratio, the dissipation in the output stages can be selected with the following equation:

$$
P_{Dtransistors} = 2 \times \overline{I_0} \times \left(\frac{V_S}{2} - \overline{V_0}\right)
$$
 (EQ. 2)

where:

- $V_S$  is the supply voltage ( $V_S$ + to  $V_S$ -)
- $V<sub>O</sub>$  is the average output voltage per channel
- $\cdot$  I<sub>O</sub> is the average output current per channel

The overall power dissipation  $(P_{DISS})$  is obtained by adding PDquiescent and PDtransistor.

Then, the  $\theta_{JA}$  requirement needs to be calculated. This is done using the following equation:

$$
\theta_{JA} = \frac{(T_{JUNCT} - T_{AMB})}{P_{DISS}}
$$

(EQ. 3)

where:

- $T_{\text{JUNCT}}$  is the maximum die temperature (+150°C)
- T<sub>AMB</sub> is the maximum ambient temperature
- $P_{DISS}$  is the dissipation calculated above
- $\cdot$   $\theta$ <sub>JA</sub> is the junction to ambient thermal resistance for the package when mounted on the PCB

This  $\theta_{JA}$  value is then used to calculate the area of copper needed on the board to dissipate the power.

The IRE and QFN power packages are designed so that heat may be conducted away from the device in an efficient manner. To disperse this heat, the bottom diepad is internally connected to the mounting platform of the die. Heat flows through the diepad into the circuit board copper, then spreads and convects to air. Thus, the ground plane on the component side of the board becomes the heatsink. This has proven to be a very effective technique.  $\theta_{JA}$  of +30°C/W can be achieved.

#### *Single Supply Operation*

The ISL1539 can also be powered from a single supply voltage. When operating in this mode, the GND pins can still be connected directly to GND. To calculate power dissipation, the equations in the previous section should be used, with  $V_S$  equal to half the supply rail.

#### *Output Loading*

While the drive amplifiers can output in excess of 450mA transiently, the internal metallization is not designed to carry more than 75mA of steady DC current and there is no currentlimit mechanism. This allows safely driving rms sinusoidal currents of 2mAx75mA, or 150mA. This current is more than that required to drive line impedances to large output levels, but output short circuits cannot be tolerated. The series output resistor will usually limit currents to safe values in the event of line shorts. Driving lines with no series resistor is a serious hazard.

#### *Power Supplies*

The power supplies should be well bypassed close to the ISL1539. A 3.3µF tantalum capacitor for each supply works well. Since the load currents are differential, they should not travel through the board copper and set up ground loops that can return to amplifier inputs. Due to the class AB output stage design, these currents have heavy harmonic content. If the ground terminal of the positive and negative bypass capacitors are connected to each other directly and then returned to circuit ground, no such ground loops will occur. This scheme is employed in the layout of the EL1537 demonstration board, and documentation can be obtained from the factory.

#### *Power Control Function*

The ISL1539 contains two forms of power control operation. Two digital inputs,  $C_0$  and  $C_1$ , can be used to control the supply current of the ISL1539 drive amplifiers. As the supply current is reduced, the ISL1539 will start to exhibit slightly higher levels of distortion and the frequency response will be limited. The four power modes of the ISL1539 are set up as shown in the table below.

![](_page_9_Picture_421.jpeg)

![](_page_9_Picture_422.jpeg)

# *QFN (Quad Flat No-Lead) Package Family*

![](_page_10_Figure_2.jpeg)

![](_page_10_Figure_3.jpeg)

![](_page_10_Figure_4.jpeg)

![](_page_10_Figure_5.jpeg)

**MDP0046**

#### **QFN (QUAD FLAT NO-LEAD) PACKAGE FAMILY (COMPLIANT TO JEDEC MO-220)**

![](_page_10_Picture_368.jpeg)

![](_page_10_Picture_369.jpeg)

NOTES:

- 1. Dimensioning and tolerancing per ASME Y14.5M-1994.
- 2. Tiebar view shown is a non-functional feature.
- 3. Bottom-side pin #1 I.D. is a diepad chamfer as shown.
- 4. N is the total number of terminals on the device.
- 5. NE is the number of terminals on the "E" side of the package (or Y-direction).
- 6. ND is the number of terminals on the "D" side of the package (or X-direction).  $ND = (N/2)$ -NE.
- 7. Inward end of terminal may be square or circular in shape with radius (b/2) as shown.
- 8. If two values are listed, multiple exposed pad options are available. Refer to device-specific datasheet.

# *HTSSOP (Heat-Sink TSSOP) Family*

![](_page_11_Figure_2.jpeg)

#### **MDP0048**

**HTSSOP (Heat-Sink TSSOP) Family**

<b>SYMBOL</b>	14 LD	<b>20 LD</b>	24 LD	28 LD	38 LD	<b>TOLERANCE</b>
А	1.20	1.20	1.20	1.20	1.20	Max
A1	0.075	0.075	0.075	0.075	0.075	$\pm 0.075$
А2	0.90	0.90	0.90	0.90	0.90	$+0.15/-0.10$
b	0.25	0.25	0.25	0.25	0.22	$+0.05/-0.06$
c	0.15	0.15	0.15	0.15	0.15	$+0.05/-0.06$
D	5.00	6.50	7.80	9.70	9.70	±0.10
D1	3.2	4.2	4.3	5.0	7.25	Reference
Е	6.40	6.40	6.40	6.40	6.40	<b>Basic</b>
E1	4.40	4.40	4.40	4.40	4.40	±0.10
E2	3.0	3.0	3.0	3.0	3.0	Reference
e	0.65	0.65	0.65	0.65	0.50	Basic
L	0.60	0.60	0.60	0.60	0.60	±0.15
L1	1.00	1.00	1.00	1.00	1.00	Reference
N	14	20	24	28	38	Reference
Rev. 2 12/03						

NOTES:

1. Dimension "D" does not include mold flash, protrusions or gate burrs. Mold flash, protrusions or gate burrs shall not exceed 0.15mm per side.

- 2. Dimension "E1" does not include interlead flash or protrusions. Interlead flash and protrusions shall not exceed 0.25mm per side.
- 3. Dimensions "D" and "E1" are measured at Datum Plane H.
- 4. Dimensioning and tolerancing per ASME Y14.5M**-**1994.

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