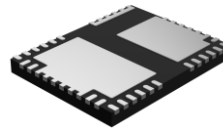


**Half Bridge GaNFast™ Power IC  
with GaNSense™ Technology**

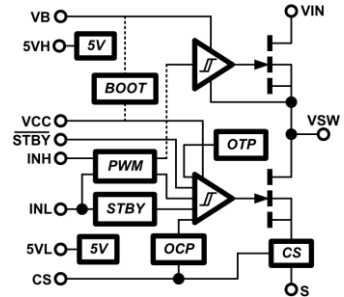
**1. Features**

**GaNFast™ Power IC**

- Wide V<sub>CC</sub> range (10 to 24 V)
- 3.3, 5, 12 V PWM input compatible
- Floating high-side with internal level shift
- Two independent logic inputs with hysteresis
- Integrated high-side bootstrap
- Shoot-through protection
- Turn-on dV/dt slew rate control (low-side and high-side)
- Slow high- & low-side turn-off dV/dt rate for EMI filter reduction
- 800 V transient voltage rating
- 650 V continuous voltage rating
- 70 mΩ high-side FET, 70 mΩ low-side FET
- Zero reverse recovery charge
- 2 KV ESD Rating (HBM)
- 500 kHz operation



QFN 8 x 10 mm



Simplified schematic

**GaNSense™ Technology**

- Integrated loss-less current sensing
- Over-current protection
- Over-temperature protection
- Autonomous low-current standby mode
- Auto-standby enable input

**Small, low profile SMT QFN**

- 8x10 mm footprint, 0.85 mm profile
- Minimized package inductance
- Enlarged cooling pads

**Sustainability**

- RoHS, Pb-free, REACH-compliant
- Up to 40% energy savings vs Si solutions
- System level 4kg CO<sub>2</sub> Carbon Footprint reduction

**Product Reliability**

- 20-year warranty

**3. Description**

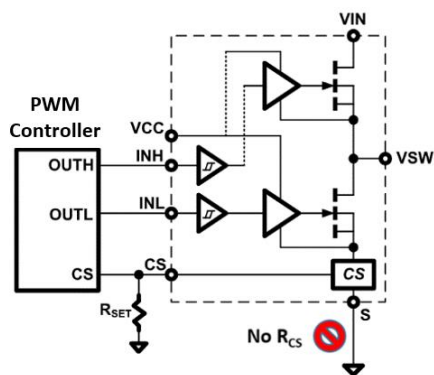
This half-bridge GaNFast™ power IC integrates high performance eMode GaN FETs with integrated gate drive, control and protection to achieve unprecedented high-frequency and high efficiency operation. GaNSense™ technology is also integrated which enables real-time, accurate sensing of voltage, current and temperature to further improve performance and robustness not achieved by any discrete GaN or discrete silicon device. GaNSense™ enables integrated loss-less current sensing which eliminates external current sensing resistors and increases system efficiency. GaNSense™ also enables short circuit and over-temperature protection to increase system robustness, while auto-standby mode increases light, tiny & no-load efficiency. These GaN ICs combine the highest dV/dt immunity, high-speed integrated drive and thermally optimized, low-inductance, QFN packaging to enable designers to achieve simple, quick, and reliable solutions. Navitas' GaN IC technology extends the capabilities of 1-ph and 3-ph motor drive applications with very high efficiencies and low EMI to achieve unprecedented power densities at a very attractive cost structure.

**2. Topologies / Applications**

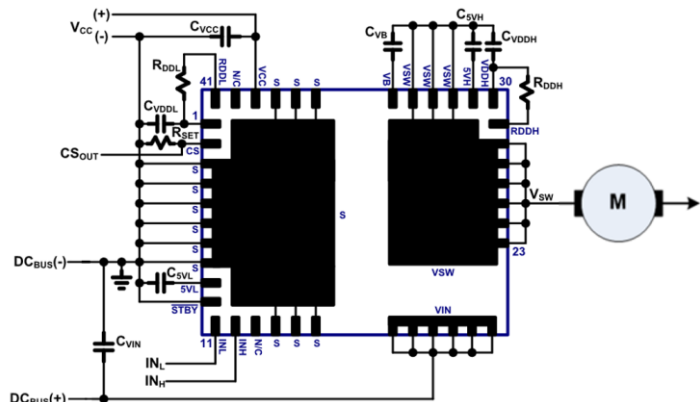
- Motor Drive

**4. Typical Application Circuits**

Loss-less Current Sensing



Motor Drive



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## 6. Specifications

### 6.1. Absolute Maximum Ratings <sup>(1)</sup> (with respect to PGND unless noted)

SYMBOL	PARAMETER	MAX	UNITS
$V_{IN}$	HV input	0 to +650	V
$V_{SW(CONT)}$	Switch Node Continuous Voltage Rating	-7 to +657	V
$V_{SW(TRAN)}$ <sup>(2)</sup>	Switch Node Transient Voltage Rating	-10 to +800	V
$I_{DSL}$ @ $T_C=100^\circ\text{C}$	Continuous Output Current (Low-side FET)	14	A
$I_{DSL}$ PULSE @ $T_C=25^\circ\text{C}$	Pulsed Output Current (Low-side FET)	28	A
$I_{DSH}$ @ $T_C=100^\circ\text{C}$	Continuous Output Current (High-side FET)	14	A
$I_{DSH}$ PULSE @ $T_C=25^\circ\text{C}$	Pulsed Output Current (High-side FET)	28	A
$V_B$ (to $V_{SW}$ )	High-side Gate Driver Bootstrap Rail	30	V
$V_{DDH}$ (to $V_{SW}$ )	High-side Gate Drive Supply Voltage	7	V
$V_{5VH}$ (to $V_{SW}$ )	High-side 5V Supply Voltage	6	V
$V_{CC}$	Supply Voltage	30	V
$V_{DDL}$	Low-side Drive Supply Voltage	7	V
$R_{DDL}$	Low-side Gate Drive Supply Resistor Setting Input	7	V
$V_{5VL}$	Low-side 5V Supply Voltage	6	V
$V_{STBY}$	Auto-Standby Mode Pin Voltage	-0.6 to +20 or $V_{CC}$	V
$V_{INH}, V_{INL}$	PWM Input Pin Voltages	-0.6 to +20 or $V_{CC}$	V
$V_{CS}$	CS Pin Voltage	5.3	V
$T_J$	Junction Temperature	-55 to 150	$^\circ\text{C}$
$T_{STOR}$	Storage Temperature	-55 to 150	$^\circ\text{C}$

(1) Absolute maximum ratings are stress ratings; devices subjected to stresses beyond these ratings may cause permanent damage.

(2)  $V_{DS(TRAN)}$  rating allows for surge ratings during non-repetitive events that are <100us (for example start-up, line interruption).  $V_{DS(TRAN)}$  rating allows for repetitive events that are <300ns, with 80% derating required (for example repetitive leakage inductance spikes).

## 6.2. Recommended Operating Conditions<sup>(3)</sup>

SYMBOL	PARAMETER	MIN	TYP	MAX	UNITS
$V_{CC}$	Supply Voltage	10	15	24	V
$V_{INH}, V_{INL}$	PWM Input Pin Voltage	0	5	15 or $V_{CC}$	V
$V_{STBY}$	Auto-Standby Mode Pin Voltage	0	5	15 or $V_{CC}$	V
$R_{DDL}$	Low-side gate drive turn-on current set resistor	300		1,500	$\Omega$
$R_{DDH}$	High-side gate drive turn-on current set resistor	300		1,500	$\Omega$
Dead-time	Between INH and INL input	500			ns
$T_J$	Operating Junction Temperature	-40		125	$^{\circ}\text{C}$

(3) Exposure to conditions beyond maximum recommended operating conditions for extended periods of time may affect device reliability.

## 6.3. ESD Ratings

SYMBOL	PARAMETER	MAX	UNITS
HBM	Human Body Model (per JS-001-2014)	2,000	V
CDM	Charged Device Model (per JS-002-2014)	500	V

## 6.4. Thermal Resistance

SYMBOL	PARAMETER	TYP	UNITS
$R_{eJC}^{(4)}$	Junction-to-Case	0.98	$^{\circ}\text{C}/\text{W}$
$R_{eJA}$	Junction-to-Ambient	40	$^{\circ}\text{C}/\text{W}$

(4)  $R_{\theta}$  measured on DUT mounted on 1 square inch 2 oz Cu (FR4 PCB)

## 6.5. Electrical Characteristics

Typical conditions:  $V_{IN}=400V$ ,  $V_{CC}=15V$ ,  $F_{SW}=50KHz$ ,  $T_{AMB}=25^{\circ}C$ ,  $I_D=7A$  (unless otherwise specified)

SYMBOL	PARAMETER	MIN	TYP	MAX	UNITS	CONDITIONS
<b><math>V_{CC}</math>, <math>V_{DDL}</math>, <math>V_B</math> and <math>V_{DDH}</math> Supply Characteristics</b>						
$V_{CCUV+}$	$V_{CC}$ UVLO Rising Threshold	8.0	8.6	9.3	V	
$V_{CCUV-}$	$V_{CC}$ UVLO Falling Threshold		7.4		V	
$I_{QCC-STBY}$	$V_{CC}$ Standby Current	200	400	560	$\mu A$	$\overline{STBY} = 0V$ , $V_{SW} \geq V_{CC}$
$I_{QCC}$	$V_{CC}$ Quiescent Current		2.5		mA	$V_{INL} = V_{INH} = 0V$ , $\overline{STBY} = 5V$
$I_{QCC-SW}$	$V_{CC}$ Operating Current		5		mA	$F_{SW} = 50KHz$ (INL and INH @ 50% Duty cycle), $V_{SW} = 0V$
$V_{DDL}$	$V_{DD}$ Supply Voltage	5.9	6.1	6.6	V	$V_{CC} = 15V$ , $V_{INL} = V_{INH} = 0V$
$V_{DDLUV+}$	$V_{DDL}$ UVLO Rising Turn-On Threshold		4.9		V	
$V_{DDLUV-HYS}$	$V_{DDL}$ UVLO Hysteresis		0.6		V	
$V_{BUIV+}$	$V_B$ UVLO Rising Threshold ( $V_B - V_{SW}$ )	8.0	8.6	9.3	V	
$V_{BUIV-}$	$V_B$ UVLO Falling Threshold ( $V_B - V_{SW}$ )		7.8		V	
$I_{QVB}$	$V_B$ Quiescent Current		1.7		mA	$V_{INH} = V_{INL} = 0V$ , $V_{SW} = 0V$ , $V_B = 15V$
$V_{DDH}$	$V_{DD}$ Supply Voltage	5.9	6.1	6.6	V	$V_B = 15V$
<b>5V Output (5V pin)</b>						
$V_{5VL}$ , $V_{5VH}$	5V Output Voltage	4.4	5.1	5.5	V	
<b>Input Logic Characteristics (INL, INH, <math>\overline{STBY}</math>)</b>						
$V_{LOGIC-H}$	Input Logic High Threshold (rising edge)		2.5	2.8	V	
$V_{LOGIC-L}$	Input Logic Low Threshold (falling edge)	1.1	1.2		V	
$V_{LOGIC-HYS}$	Input Logic Hysteresis		1.4		V	
<b>Switching Characteristics</b>						
$F_{SW}$	Switching Frequency			500	kHz	$R_{DDH}=R_{DDL}=300\Omega$
$t_{PW}^{(1)}$	Pulse width	0.05			$\mu s$	
$t_{ONHS}$	Prop Delay ( $IN_H$ from Low to High, $V_{SW}$ pulled to $V_{IN}$ )		55		ns	Fig. 3
$t_{OFFHS}$	Prop Delay ( $IN_H$ from High to Low, $V_{SW}$ tri-stated)		120		ns	Fig. 3
$t_{ONLS}$	Prop Delay ( $IN_L$ from Low to High, $V_{SW}$ pulled to $P_{GND}$ )		58		ns	Fig. 4
$t_{OFFLS}$	Prop Delay ( $IN_L$ from High to Low, $V_{SW}$ tri-stated)		120		ns	Fig. 4
High side turn on dvdt	High side turn-on dV/dt slew rate		6		V/ns	$R_{DDH} = 300\Omega$
Low side turn on dvdt	Low side turn-on dV/dt slew rate		4		V/ns	$R_{DDL} = 300\Omega$

(1) Min Pulse width limitation is only for the high side FET

## 6.6. Electrical Characteristics (2, cont.)

Typical conditions:  $V_{DS}=400V$ ,  $V_{CC}=15V$ ,  $F_{SW}=50KHz$ ,  $T_{AMB}=25^{\circ}C$ ,  $I_D=7A$  (unless otherwise specified)

SYMBOL	PARAMETER	MIN	TYP	MAX	UNITS	CONDITIONS
<b>Current Sense Characteristics (CS pin)</b>						
$I_{CS}$	CS Pin Output Current	1.16	1.25	1.34	mA	$V_{INL} = 5V$ , $I_{DS} = 11A$
Offset	CS Output Offset		+18		$\mu A$	$V_{INL} = 5V$ , $I_{DS} = 0A$
$t_{CSDLY}$	CS Pin Delay (from $I_{DS}$ to $V_{CS}$ , at 10% rated current)		55		ns	$di/dt = 40A/\mu s$ , $R_{SET} = 400\Omega$ , $C_{CS} = 25pF$
<b>Over-Current Protection</b>						
OCP <sub>TH</sub>	OCP Threshold Voltage ( $V_{CS}$ Pin)		1.9		V	
<b>Standby Mode Characteristics</b>						
$t_{TO\_STBY}$	Time Out Delay Entering Standby Mode		90		$\mu s$	$V_{INL} = 0V$
$t_{ON\_FP}$	First Pulse Propagation Delay		460	650	ns	$V_{INL} = 5V$ pulse, $\overline{STBY} = 0V$
<b>Over-Temperature Protection</b>						
$T_{OTP+}$	OTP Shutdown Threshold		165		$^{\circ}C$	
$T_{OTP\_HYS}$	OTP Restart Hysteresis		60		$^{\circ}C$	
<b>Bootstrap FET Characteristics</b>						
$I_{BOOT}$	Bootstrap Charging Current		2		A	$V_{CC} = 12V$ , $V_B = 0V$ , $V_{SW} = 0V$

## 6.7. Electrical Characteristics (3, cont.)

Typical conditions:  $V_{DS}=400V$ ,  $V_{CC}=15V$ ,  $F_{SW}=50KHz$ ,  $T_{AMB}=25^{\circ}C$ ,  $I_D=7A$  (unless otherwise specified)

SYMBOL	PARAMETER	MIN	TYP	MAX	UNITS	CONDITIONS
<b>Low side GaN FET Characteristics</b>						
$I_{DSS}$	Drain-Source Leakage Current		0.2	25	$\mu A$	$V_{DS} = 650 V, V_{INL} = 0 V$
$I_{DSS}$	Drain-Source Leakage Current, TC =150 °C		10		$\mu A$	$V_{DS}=650V, V_{INL}=0V, T_C=150^{\circ}C$
$R_{DS(ON)}$	Low-side FET Drain-Source Resistance		70	98	m $\Omega$	$V_{INL} = 5 V, I_D = 7 A$
$V_{SD}$	Source-Drain Reverse Voltage		3.2	5	V	$V_{INL} = 0 V, V_{INH} = 0 V, I_{SD} = 7 A$
$Q_{OSS}$	Output Charge		41.5		nC	$V_{DS} = 400 V, V_{INL} = 0V, V_{INH} = 0 V$
$Q_{RR}$	Reverse Recovery Charge		0		nC	$V_{DS} = 400 V$
$C_{OSS}$	Output Capacitance		59		pF	$V_{DS} = 400 V, V_{INL} = 0 V, V_{INH} = 0 V$
$C_{O(er)}^{(1)}$	Effective Output Capacitance, Energy Related		75.5		pF	$V_{DS} = 400 V, V_{INL} = 0 V, V_{INH} = 0 V$
$C_{O(tr)}^{(2)}$	Effective Output Capacitance, Time Related		103.8		pF	$V_{DS} = 400 V, V_{INL} = 0 V, V_{INH} = 0 V$
<b>High side GaN FET Characteristics</b>						
$I_{DSS}$	Drain-Source Leakage Current		0.2	25	$\mu A$	$V_{DS} = 650 V, V_{INL} = 0 V$
$I_{DSS}$	Drain-Source Leakage Current, TC =150 °C		10		$\mu A$	$V_{DS}=650V, V_{INL}=0V, T_C=150^{\circ}C$
$R_{DS(ON)}$	High-side FET Drain-Source Resistance		70	98	m $\Omega$	$V_{INL} = 5 V, I_D = 7 A$
$V_{SD}$	Source-Drain Reverse Voltage		3.2	5	V	$V_{INL} = 0 V, V_{INH} = 0 V, I_{SD} = 7 A$
$Q_{OSS}$	Output Charge		37.5		nC	$V_{DS} = 400 V, V_{INL} = 0V, V_{INH} = 0 V$
$Q_{RR}$	Reverse Recovery Charge		0		nC	$V_{DS} = 400 V$
$C_{OSS}$	Output Capacitance		50		pF	$V_{DS} = 400 V, V_{INL} = 0 V, V_{INH} = 0 V$
$C_{O(er)}^{(1)}$	Effective Output Capacitance, Energy Related		66.6		pF	$V_{DS} = 400 V, V_{INL} = 0 V, V_{INH} = 0 V$
$C_{O(tr)}^{(2)}$	Effective Output Capacitance, Time Related		93.8		pF	$V_{DS} = 400 V, V_{INL} = 0 V, V_{INH} = 0 V$

(1)  $C_{O(er)}$  is a fixed capacitance that gives the same stored energy as  $C_{OSS}$  while  $V_{DS}$  is rising from 0 to 400 V

(2)  $C_{O(tr)}$  is a fixed capacitance that gives the same charging time as  $C_{OSS}$  while  $V_{DS}$  is rising from 0 to 400 V

### 6.8. Switching Waveforms

( $T_C = 25\text{ }^\circ\text{C}$  unless otherwise specified)

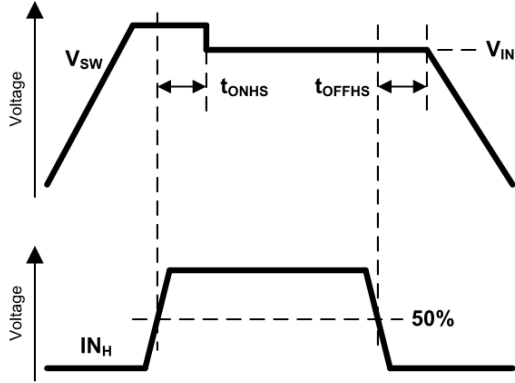


Fig. 1. Propagation Delay ZVS Mode  $t_{ONHS/OFFHS}$

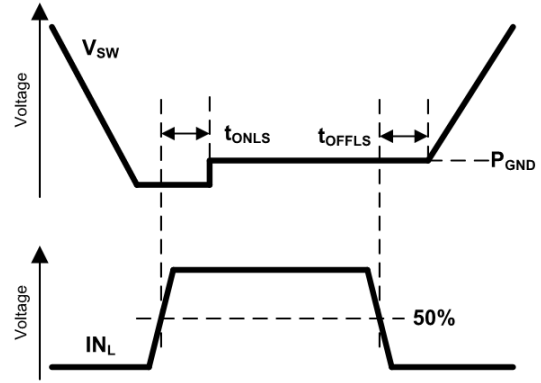


Fig. 2. Propagation Delay ZVS Mode  $t_{ONLS/OFFLS}$

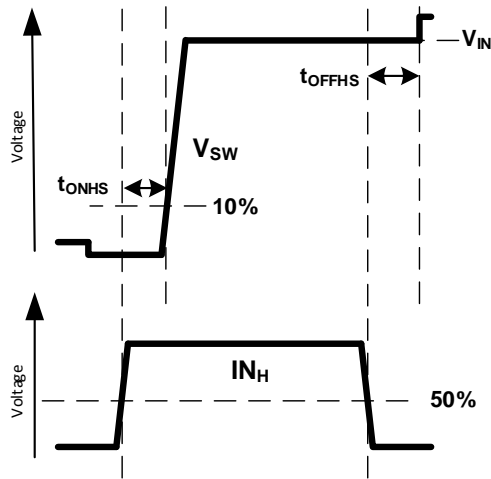


Fig. 3. Propagation Delay Hard Switching  $t_{ONHS/OFFHS}$

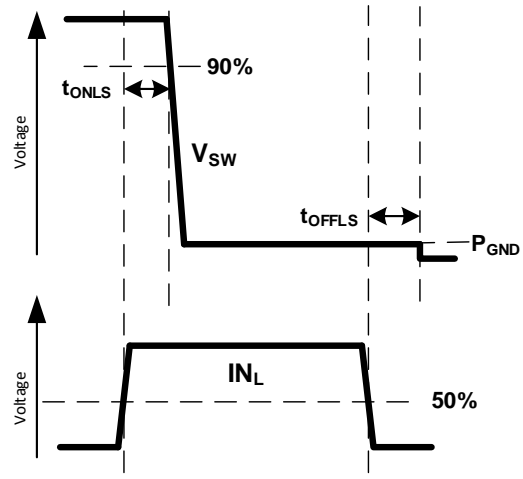


Fig. 4. Propagation Delay Hard Switching  $t_{ONLS/OFFLS}$



### 6.9. Characteristic Graphs

(GaN FET,  $T_c = 25\text{ }^\circ\text{C}$  unless otherwise specified)

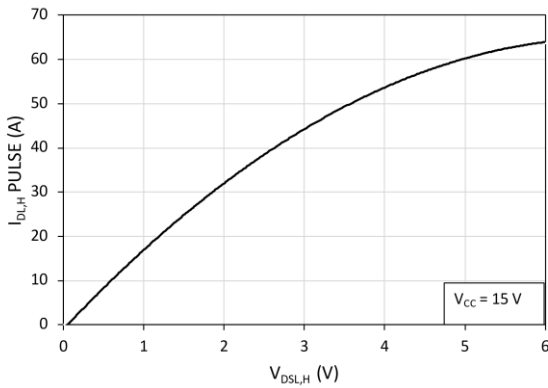


Fig. 5. Pulsed Drain current ( $I_{D, S, L, H}$  PULSE) vs. drain-to-source voltage ( $V_{D, S, L, H}$ ) at  $T = 25\text{ }^\circ\text{C}$

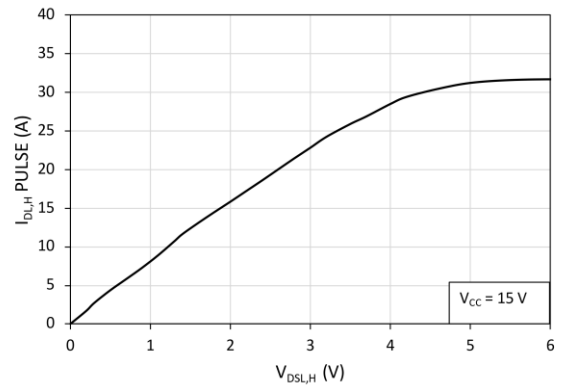


Fig. 6. Pulsed Drain current ( $I_{D, S, L, H}$  PULSE) vs. drain-to-source voltage ( $V_{D, S, L, H}$ ) at  $T = 125\text{ }^\circ\text{C}$

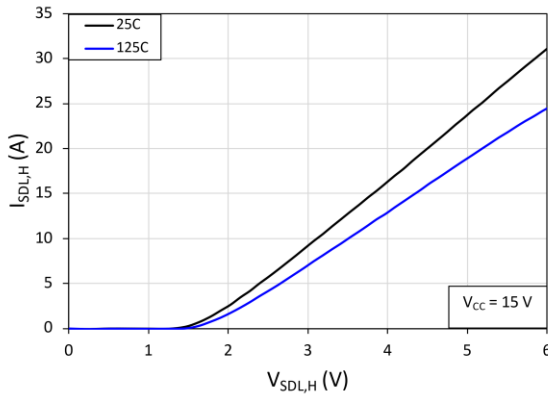


Fig. 7. Source-to-drain reverse conduction voltage ( $I_{S, D, L, H}$ )

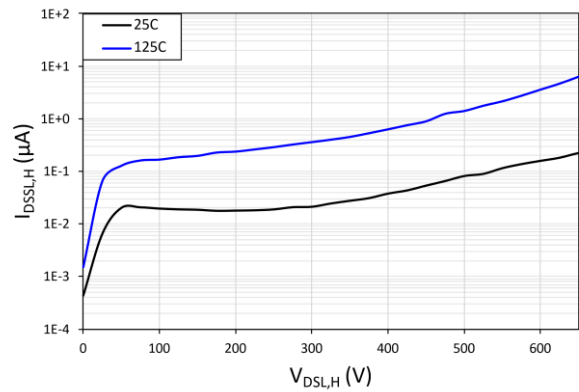


Fig. 8. Drain-to-source leakage current ( $I_{D, S, S, L, H}$ ) vs. drain-to-source voltage ( $V_{D, S, L, H}$ )

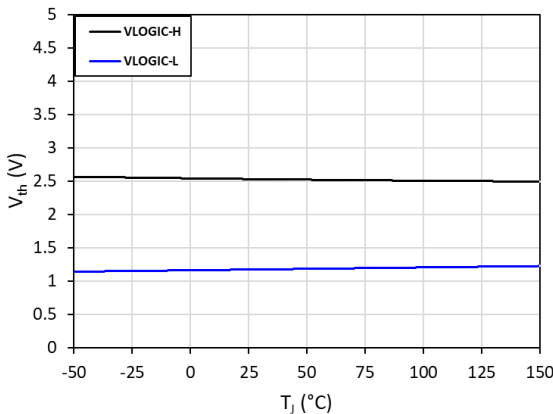


Fig. 9.  $V_{LOGIC-H}$  and  $V_{LOGIC-L}$  vs. junction temperature ( $T_j$ )

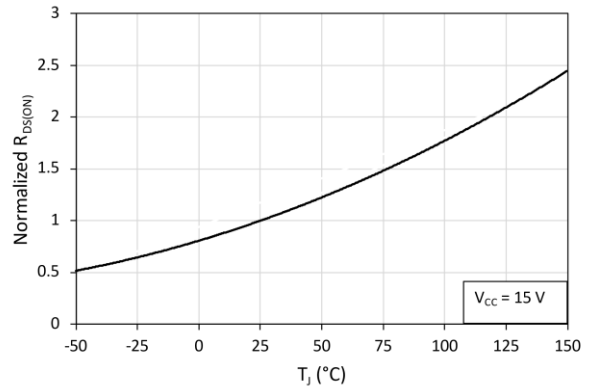


Fig. 10. Normalized on-resistance ( $R_{D, S, L, H(ON)}$ ) vs. junction temperature ( $T_j$ )

**Characteristic Graphs (Cont.)**

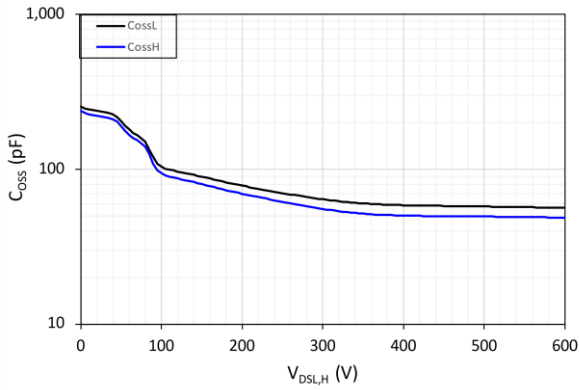


Fig. 11. Output capacitance ( $C_{OSSL,H}$ ) vs. drain-to-source voltage ( $V_{DSL,H}$ )

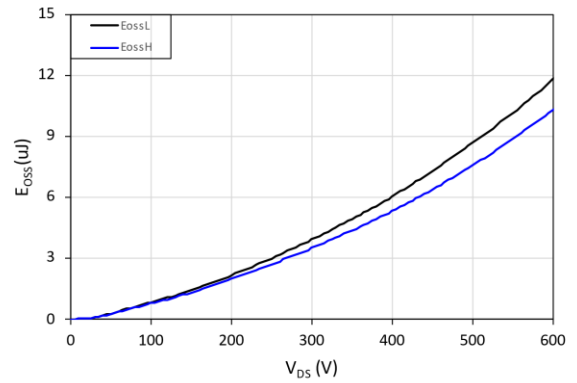


Fig. 12. Energy stored in output capacitance ( $E_{OSSL,H}$ ) vs. drain-to-source voltage ( $V_{DSL,H}$ )

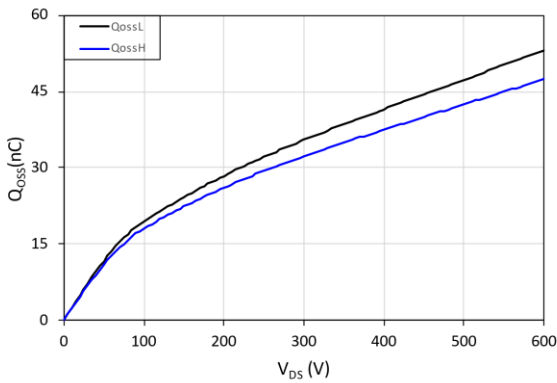


Fig. 13. Charge stored in output capacitance ( $Q_{OSS}$ ) vs. drain-to-source voltage ( $V_{DS}$ )

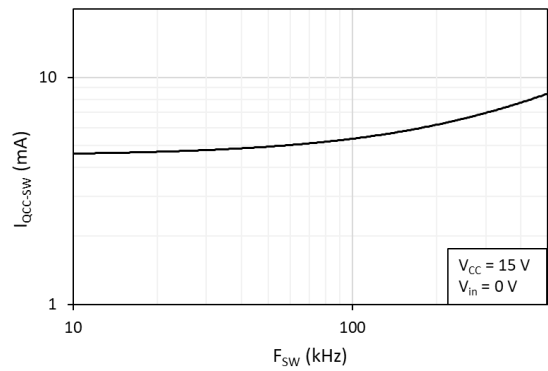


Fig. 14.  $V_{CC}$  operating current ( $I_{QCC-SW}$ ) vs. operating frequency ( $F_{SW}$ )

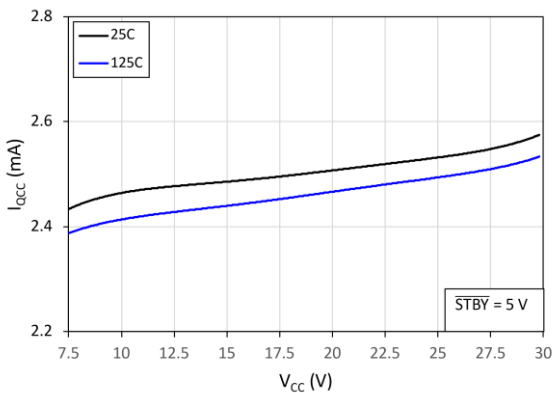


Fig. 15.  $V_{CC}$  quiescent current ( $I_{QCC}$ ) vs. supply voltage ( $V_{CC}$ )

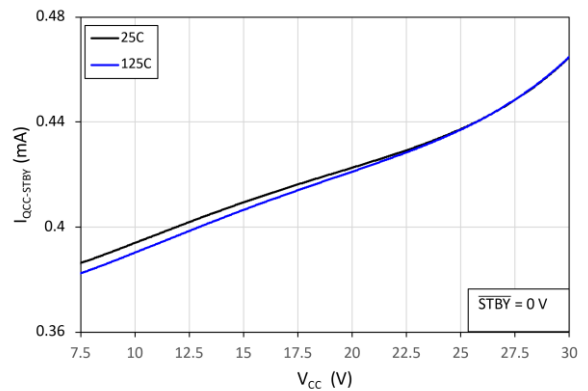


Fig. 16.  $V_{CC}$  stand-by quiescent current ( $I_{QCC}$ ) vs. supply voltage ( $V_{CC}$ )

**Characteristic Graphs (Cont.)**

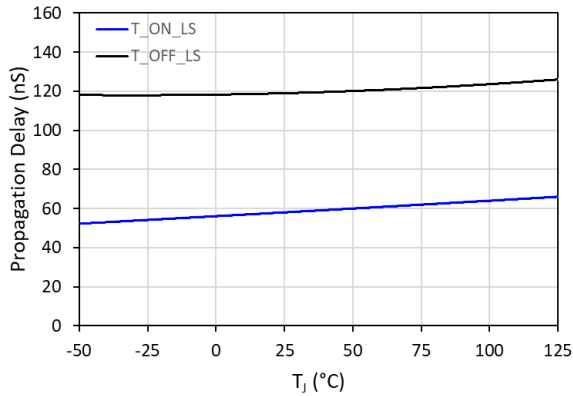


Fig. 17. Propagation delay ( $T_{ON}$  and  $T_{OFF}$ ) vs. junction temperature ( $T_J$ ) – low side

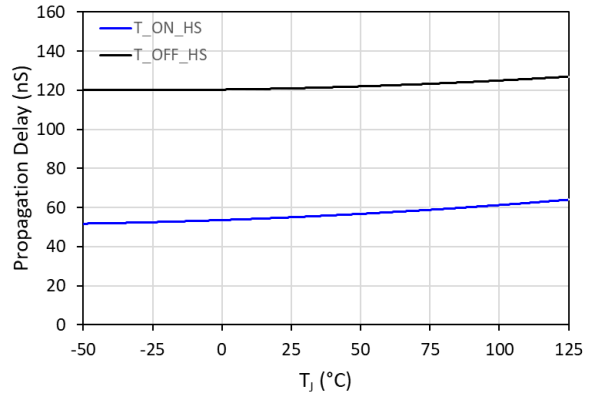


Fig. 18. Propagation delay ( $T_{ON}$  and  $T_{OFF}$ ) vs. junction temperature ( $T_J$ ) – high side

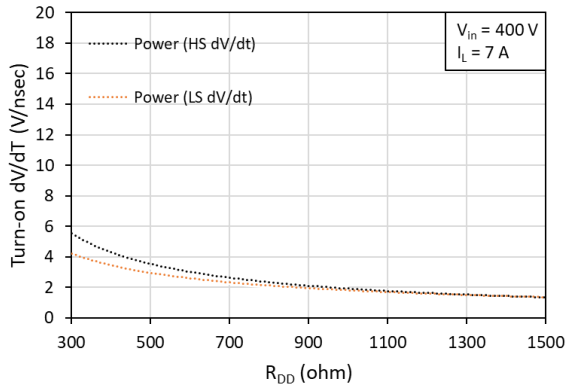


Fig. 19. Slew rate ( $dV/dt$ ) vs. gate drive turn-on current set resistance ( $R_{DDL}$ ) at  $T = 25\text{ }^\circ\text{C}$

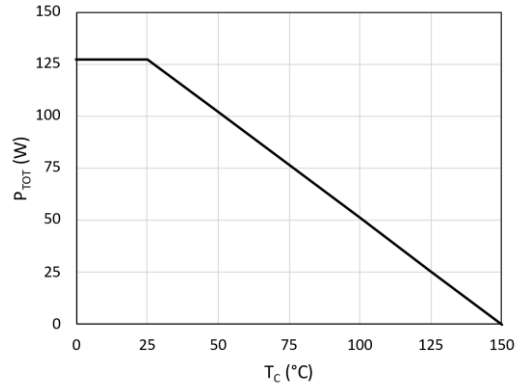


Fig. 20. Power dissipation ( $P_{TOT}$ ) vs. case temperature ( $T_C$ )

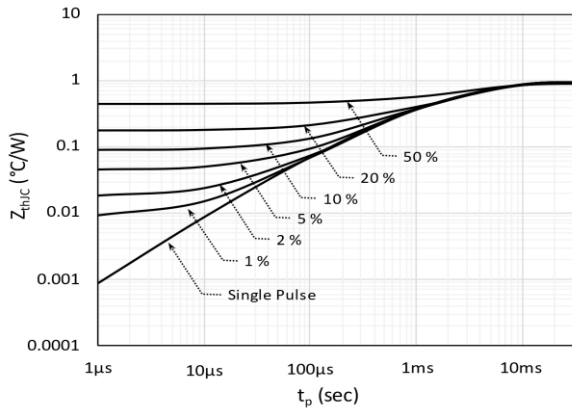


Fig. 21. Max. thermal transient impedance ( $Z_{thJC}$ ) vs. pulse width ( $t_p$ )

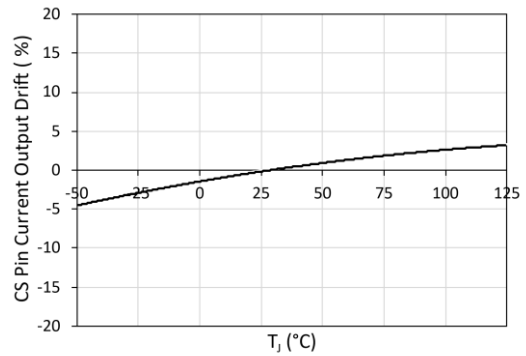


Fig. 22. CS Pin Current Output Drift vs. case temperature ( $T_C$ )

## 7. Pin Configurations and Functions

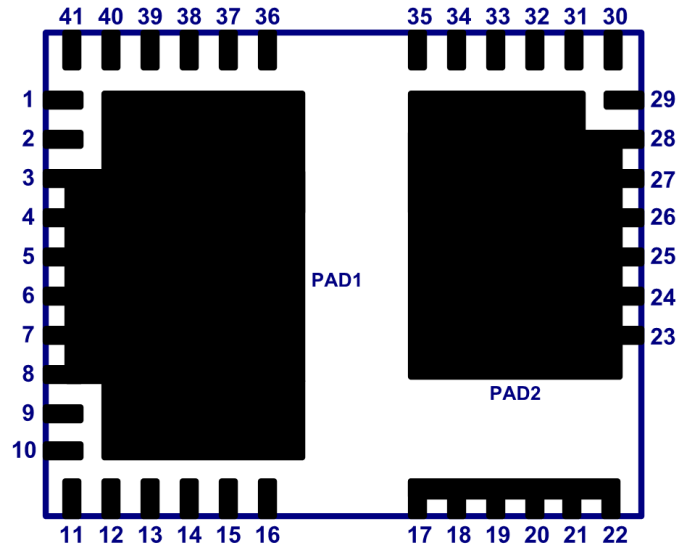


Fig. 23 Package Top View

Pin		I/O <sup>(1)</sup>	Description
Number	Symbol		
3-8,14-16,36-38 (and PAD1)	$P_{GND}$	G	Power ground
1	$V_{DDL}$	P	Low-side drive supply
2	CS	O	GaN FET IDS current sensing set pin. Internal current source and external resistor $R_{SET}$ sets current measurement level. Connect resistor from CS to SGND.
9	$5V_L$	P	Low-side 5 V supply
10	STBY	I	Auto-standby enable input (0=ON)
11	$IN_L$	I	Low-side drive input
12	$IN_H$	I	High-side drive input
13, 40	N/C		No connect
17 – 22	$V_{IN}$	P	HV input
23-28,32-34 (and PAD2)	$V_{SW}$	O	Half-bridge switch node
29	$R_{DDH}$	I	High-side gate drive turn-on current set resistor (using $R_{DD}$ resistor connected from $R_{DDH}$ pin to $V_{DDH}$ pin)
30	$V_{DDH}$	P	High-side drive supply
31	$5V_H$	P	High-side 5 V supply
35	$V_B$	P	High-side gate driver bootstrap rail
39	$V_{CC}$	P	IC supply voltage
41	$R_{DDL}$	I	Low-side gate drive turn-on current set resistor (using $R_{DD}$ resistor connected from $R_{DDL}$ pin to $V_{DDL}$ pin)

(1) I = Input, O = Output, P = Power, G = Ground, NC = No Connect

## 8. Functional Description

The functional description contains additional information regarding the IC operating modes and pin functionality.

### 8.1. GaN Power IC Connections and Component Values

The typical connection diagram for this GaN Half-Bridge IC is shown in Fig. 24. The IC pins include the drain of the high-side GaN power FET ( $V_{IN}$ ), the half-bridge mid-point switched node ( $V_{SW}$ ), the source of the low-side GaN power FET and IC GND ( $P_{GND}$ ), low-side IC supply ( $V_{CC}$ ), low-side gate drive supply ( $V_{DDL}$ ), low-side turn-on dV/dt control ( $R_{DDL}$ ), low-side 5V supply ( $5V_L$ ), low-side referenced PWM inputs ( $IN_L$ ,  $IN_H$ ), low-side current sensing output ( $CS$ ), auto-standby enable input ( $\overline{STBY}$ ), high-side supply ( $V_B$ ), high-side gate drive supply ( $V_{DDH}$ ), and high-side 5V supply ( $5V_H$ ). The external low-side components around the IC include  $V_{CC}$  supply capacitor ( $C_{VCC}$ ) connected between  $V_{CC}$  pin and  $P_{GND}$ ,  $V_{DDL}$  supply capacitor ( $C_{VDDL}$ ) connected between  $V_{DDL}$  pin and  $P_{GND}$ , turn-on dV/dt set resistor ( $R_{DDL}$ ) connected between  $V_{DDL}$  pin and  $R_{DDL}$  pin, current sense amplitude set resistor ( $R_{SET}$ ) connected between  $CS$  pin and  $P_{GND}$ , 5V supply capacitor ( $C_{5VL}$ ) connected between  $5V_L$  pin and  $P_{GND}$ , and the auto-standby enable pin ( $\overline{STBY}$ ) connected to  $P_{GND}$  to enable auto-standby mode or connected to  $5V_L$  to disable auto-standby mode. The external high-side components around the IC include  $V_B$  supply capacitor ( $C_{VB}$ ) connected between  $V_B$  pin and  $V_{SW}$ ,  $V_{DDH}$  supply capacitor ( $C_{VDDH}$ ) connected between  $V_{DDH}$  pin and  $V_{SW}$ , turn-on dV/dt set resistor ( $R_{DDH}$ ) connected between  $V_{DDH}$  pin and  $R_{DDH}$  pin, and 5V supply capacitor ( $C_{5VH}$ ) connected between  $5V_H$  pin and  $V_{SW}$ . The high side  $V_B$ ,  $5V_H$  and  $V_{DDH}$  bypass capacitors must be chosen carefully to accommodate various system considerations such as high side wake up time, high side hold up time and standby power.

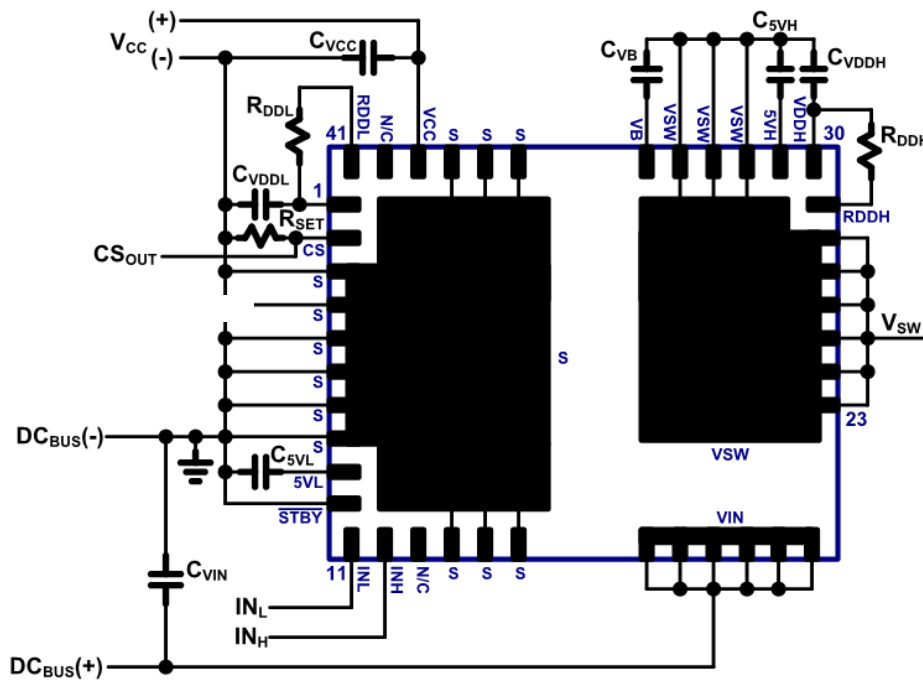


Fig. 24. IC connection diagram

The following table (Table I) shows the recommended component values (typical only) for the external components connected to the pins of this Half-Bridge GaN power IC. These components should be placed as close as possible to the IC. Please see PCB Layout Guidelines for more information.

<b>SYM</b>	<b>DESCRIPTION</b>	<b>TYP</b>	<b>UNITS</b>
C <sub>VCC</sub>	V <sub>CC</sub> supply capacitor	0.1	μF
C <sub>VDD</sub>	V <sub>DD</sub> supply capacitor	0.01	μF
R <sub>DDL</sub>	Low-side gate drive turn-on current set resistor	300	Ω
R <sub>SET</sub>	Current sense amplitude set resistor	See Section 8.6 , Equation 1	Ω
C <sub>5VL</sub>	5V <sub>L</sub> supply capacitor	0.022	μF
C <sub>VB</sub>	V <sub>B</sub> supply capacitor	0.01	μF
C <sub>VDDH</sub>	V <sub>DDH</sub> supply capacitor	0.01	μF
R <sub>DDH</sub>	High-side gate drive turn-on current set resistor	300	Ω
C <sub>5VH</sub>	5V <sub>H</sub> supply capacitor	0.01	μF

Table I. Recommended component values (typical only).

## 8.2. UVLO Mode

This GaN Power IC includes under-voltage lockout (UVLO) circuits for both the high side and low side power supplies for properly disabling all the internal circuitry while ensuring that the gates of power FETs are kept in their OFF state. While  $V_{CC}$  is below the  $V_{CCUV+}$  threshold (8.6V, typical) and  $V_{DDL}$  is below the  $V_{DDLUV+}$  threshold (4.9V, typical) the low side power FET gate is kept in its OFF state while an analogous situation is applicable for the high side power FET gate while  $V_B$  and  $V_{DDH}$  are below their respective UVLO thresholds. As the  $V_{CC}$  supply voltage increases (Fig. 25), the voltage at the  $V_{DDL}$  pin also increases and exceeds  $V_{DDLUV+}$ .  $V_{DDL}$  voltage continues to increase with  $V_{CC}$  until it gets limited to a constant voltage level (6.1V, typical) by the internal regulator. The  $V_{CC}$  voltage continues to increase until it exceeds  $V_{CCUV+}$  and the IC enters Normal Operating Mode. The gate drive is enabled and the control signal at the  $IN_L$  input turns the internal low side power FET on and off normally. While the low side power FET is ON the bootstrap capacitor ( $V_B$ ) is charged through the internal bootstrap FET. Analogous to the low side situation, as  $V_B$  and consequently  $V_{DDH}$  rise above their respective UVLO thresholds the high side gate driver is enabled and can respond to  $IN_H$ . During system power off, when  $V_{CC}$  decreases below the  $V_{CCUV-}$  threshold (7.4V, typical), the low side gate drive is disabled, and the IC enters UVLO Mode.

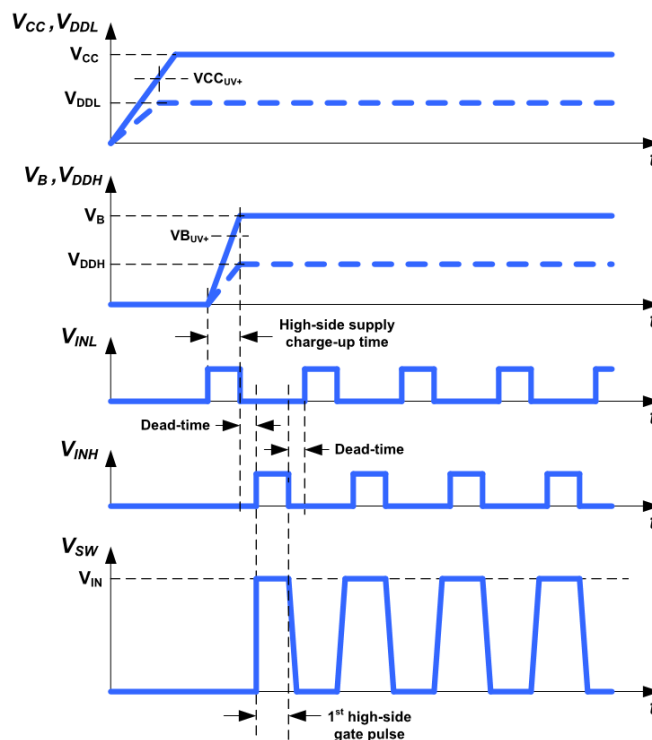


Fig. 25. UVLO Mode timing diagram

## 8.3. Normal Operating Mode

During normal operating mode,  $V_{CC}$  is set at a sufficient level (15 V typical) by the auxiliary power supply of the power converter, and  $V_B$  is at a sufficient level (as set by  $V_{CC}$  and the internal bootstrap circuit). The PWM input signals at the  $IN_L$  and  $IN_H$  pins turn the gates of the internal high- and low-side GaN power FETs on and off at the desired duty-cycle, frequency, and dead-time. The input logic signal at the  $IN_L$  pin turns the low-side half-bridge power FET on and off (0=OFF, 1=ON), and the input logic signal at the  $IN_H$  pin turns the high-side half-bridge power FET on and off (0=OFF, 1=ON). As the PWM inputs are turned on and off in a complementary manner each switching cycle, the  $V_{SW}$  pin (half-bridge mid-point) is then switched between  $P_{GND}$  ( $IN_L=1, IN_H=0$ ) and  $V_{IN}$  ( $IN_L=0, IN_H=1$ ) at the given frequency and duty-cycle (Fig. 26). This GaN Half-Bridge IC includes shoot-through protection circuitry that prevents both power FETs from turning on simultaneously. This IC also includes an internal bootstrap FET for supplying the high-side circuitry. The bootstrap FET is enabled during normal operating mode and is turned on each PWM switching cycle only when the  $IN_L$  pin is 'HIGH' and the low-side power FET is on. This will allow the  $V_B$  capacitor to be charged up each switching cycle for properly maintaining the necessary floating high-side supply voltage. The  $V_B$  capacitor value should be sized correctly such that the  $V_B$  voltage is maintained at a sufficient level above UVLO- during normal operation. Should the  $V_B$ - $V_{SW}$  voltage decrease below the  $V_{B_{UV-}}$  falling UVLO threshold

(7.8 V typical) at any time, then the high-side GaN power FET will turn off and become disabled until  $V_B - V_{SW}$  increases again above the  $V_{BUV+}$  rising threshold (8.6 V typical).

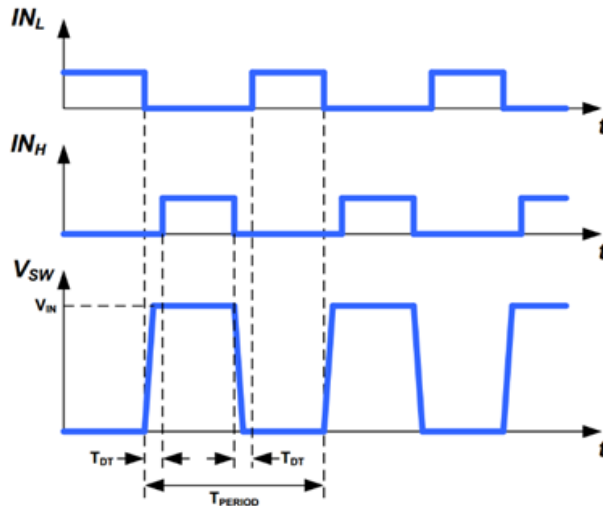


Fig. 26. Normal operating mode timing diagram

### 8.4. Low Power Standby Mode

This GaN Half-Bridge IC includes an autonomous low power standby mode for disabling the IC and reducing the  $V_{CC}$  current consumption. During normal operating mode, the PWM input signals at the  $IN_L$  and  $IN_H$  pins turn the gates of the internal high- and low-side GaN power FETs on and off at the desired duty-cycle, frequency, and dead-time. If the input pulses at the  $IN_L$  pin stop and stay below the lower  $V_{INL-}$  turn-off threshold (1.1V, typical) for the duration of the internal timeout standby delay ( $t_{TO\_STBY}$ , 90usec, typical), then the IC will automatically enter low power standby mode (Fig. 27). This will disable the gate drive and other internal circuitry and reduce the  $V_{CC}$  supply current to a low level (300uA, typical). When the  $IN_L$  pulses restart, the IC will wake up after a delay (typically around 490ns) at the first rising edge of the  $IN_L$  input and enter normal operating mode again. To enable auto standby mode, the  $\overline{STBY}$  pin should be connected to Source (set low). To disable auto standby mode,  $\overline{STBY}$  pin should be connected to the 5V<sub>L</sub> pin 7 (set high).

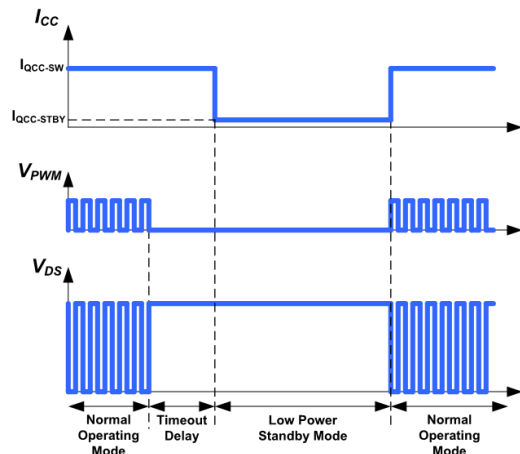


Fig. 27. Autonomous Low Power Standby Mode timing diagram



### 8.5. Programmable Turn-on dV/dt Control

During first start-up pulses or during hard-switching conditions, it is desirable to limit the slew rate (dV/dt) of the drain of the power FET during turn-on. This is necessary to reduce EMI or reduce circuit switching noise. To program the turn-on dV/dt rate of the internal power FET, a resistor ( $R_{DDL,H}$ ) is placed in between the  $V_{DDL,H}$  pin and the  $R_{DDL,H}$  pin. This resistor ( $R_{DDL,H}$ ) sets the turn-on current of the internal gate driver and therefore sets the turn-on falling edge dV/dt rate of the drain of the power FET (Fig. 28). This resistor value should be 300Ω minimum (see Table II).

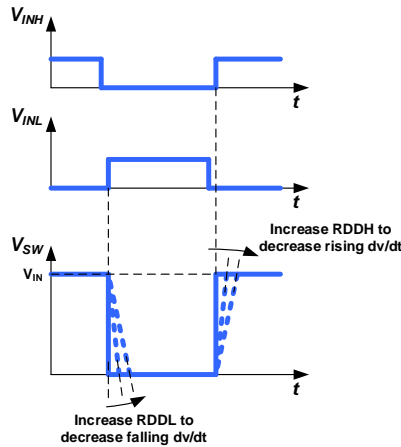


Fig. 28. Turn-on dV/dt slew rate control

SYM	DESCRIPTION	MIN	TYP	MAX	UNITS
$R_{DDL,H}$	$R_{DDL,H}$ resistor	300		1,500	Ω

Table II. Recommended  $R_{DDL,H}$  values

### 8.6. Internal Turn-off dV/dt Control

To reduce EMI and reduce circuit switching noise, it is desirable to limit the turn-off dV/dt slew rate of the drain of the low-side and high-side GaN power FETs. This GaN IC includes low-side and high-side turn-off dV/dt slew rates that are optimized for motor drive applications. The turn-off speed of the low-side and high-side GaN power FETs are internally set to a slow dV/dt rate. This slow turn-off dV/dt rate dramatically reduces conducted and radiated EMI noise across a wide frequency spectrum, especially with motor drive applications where high di/dt and dV/dt induced common mode noise exists due to motor cables. This common mode noise typically requires external common mode filters to reduce EMI but these filters can be reduced or eliminated due to the limited high-side dV/dt slew rate.

### 8.7. GaNSense™ Technology Loss-Less Current Sensing

For many applications it is necessary to sense the cycle-by-cycle current flowing through the low-side GaN power FET. Existing current sensing solutions require a current sensing resistor to be placed in between the source of the low-side GaN power FET and  $P_{GND}$ . This resistor method increases system conduction power losses, creates a hotspot on the PCB, and lowers overall system efficiency. To eliminate this external resistor and hotspot, and increase system efficiency, this GaN Half-Bridge IC includes GaNSense™ Technology for integrated and accurate loss-less current sensing. The current flowing through the internal low-side GaN power FET is sensed internally and then converted to a current at the current sensing output pin (CS). An external resistor ( $R_{SET}$ ) is connected from the CS pin to the Source ( $P_{GND}$ ) and is used to set the amplitude of the CS pin voltage signal (Fig. 29). This allows for the amplitude of the CS pin signal to be programmed so it is compatible with different controllers with different current sensing input thresholds.

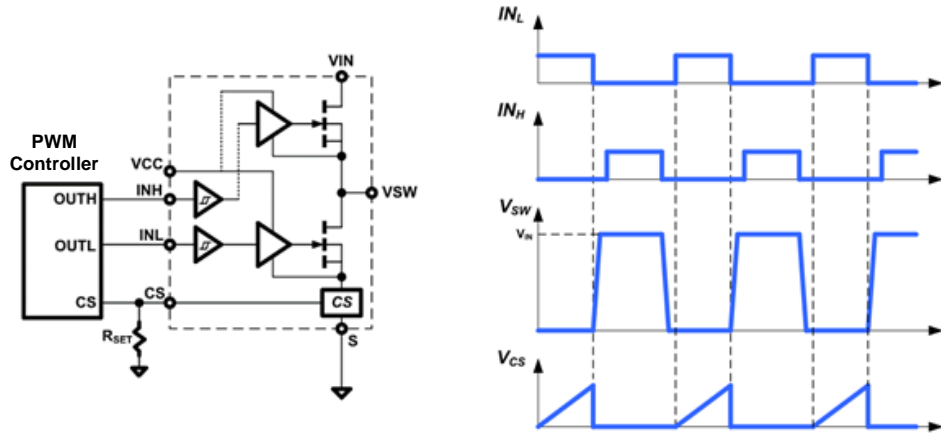


Fig. 29. External resistor sensing vs. GaNSense™ Technology

To select the correct  $R_{SET}$  resistor value, the following equation (Equation 1) can be used. This equation uses the equivalent desired external current sensing resistor value ( $R_{CS}$ ), together with the gain of the internal sensing circuitry, to generate the equivalent  $R_{SET}$  resistor value. This  $R_{SET}$  value will then give the correct voltage level at the CS pin to be compatible with the internal current sensing threshold of the system controller.

$$I_{OUT} \text{ Ratio} = \frac{I_{DS}}{I_{CS}} = \frac{11A}{0.00125A} = 8800$$

$$R_{SET} = 8800 * R_{CS}$$

Equation 1.  $R_{SET}$  resistor value equation

When comparing GaNSense™ Technology versus existing external current sensing resistor method (Fig. 30), the total ON resistance,  $R_{ON(TOT)}$ , can be substantially reduced, and the external  $R_{CS}$  resistors can be eliminated. For the example shown,  $R_{ON(TOT)}$  is reduced from 140m to 70m. This gives lower  $R_{CS}$  power losses and thermals, eliminates external op-amp and comparator sensing circuits, reduces component count, and lowers overall system cost.

**External Current Sensing Resistor Method**

**GaNFast™ with GaNSense™**

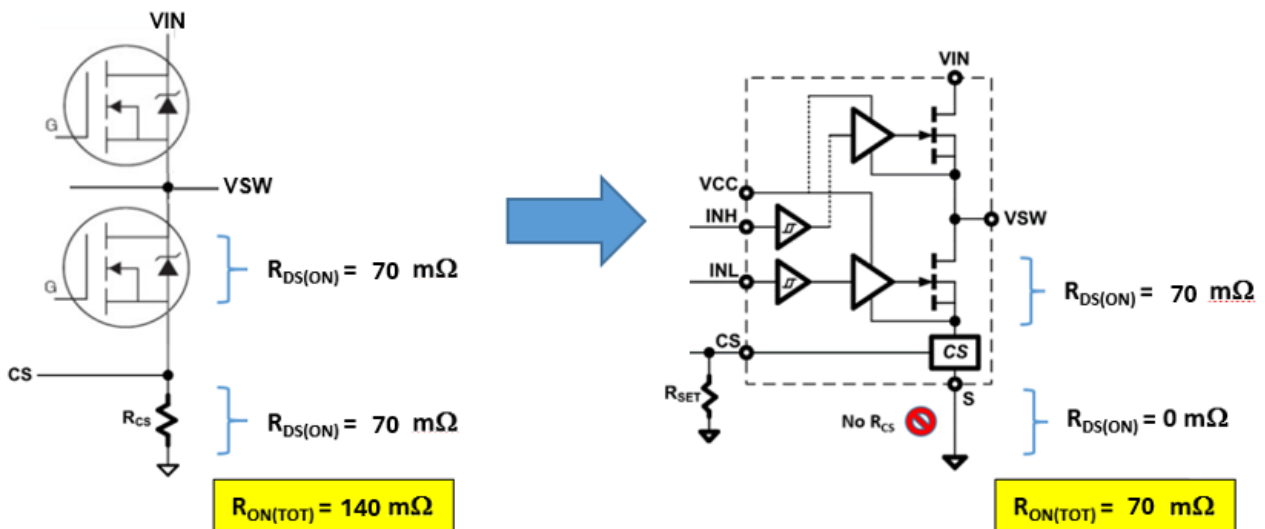


Fig. 30. External current sensing resistor vs. GaNSense™ Technology

### 8.8. Over Current Protection (OCP)

This GaN Power IC includes cycle-by-cycle over-current detection and protection (OCP) circuitry to protect the GaN power FET against high current levels. During the on-time of each switching cycle, should the peak current exceed the internal OCP threshold (1.9V, typical), the internal gate drive will turn the GaN power FET off quickly and truncate the on-time period to prevent damage occurring to the IC. The IC will then turn on again at the next PWM rising edge at the start of the next on-time period (Fig. 31). This OCP protection feature will self-protect the IC each switching cycle against fast peak over current events and greatly increase the robustness and reliability of the system. The actual peak current threshold can be calculated using Equation 2 and is a function of the internal current-sensing ratio and the external  $R_{SET}$  resistor. The internal OCP threshold (1.9V, typical) is much higher than the OCP thresholds of many popular QR, ACF and PFC controllers. This ensures good compatibility of this IC with existing controllers without OCP threshold conflicts.

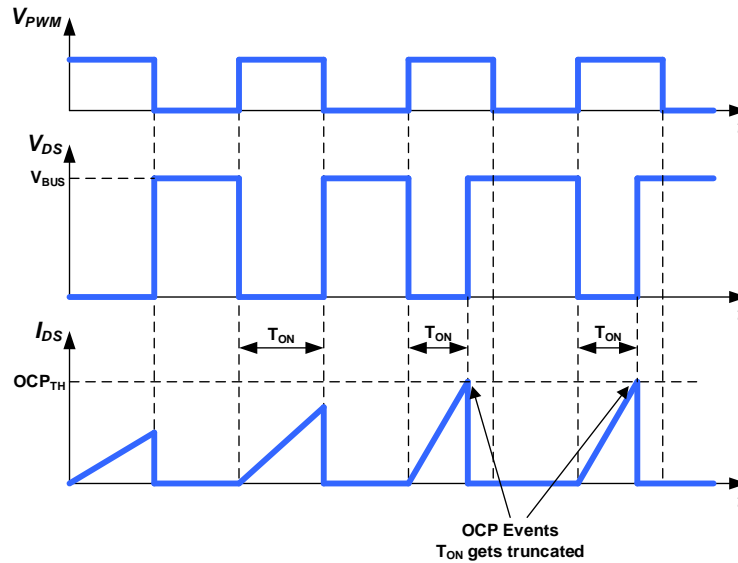


Fig. 31. OCP threshold timing diagram

$$I_{OCP} = \frac{[ 1.9 \text{ V} \times 8800 ]}{R_{SET}}$$

Equation 2. OCP trip current threshold equation

### 8.9. Over Temperature Protection (OTP)

This GaN Power IC includes over-temperature detection and protection (OTP) circuitry to protect the IC excessively high junction temperatures ( $T_J$ ). High junction temperatures can occur due to overload, high ambient temperatures, and/or poor thermal management. Should  $T_J$  exceed the internal  $T_{OTP+}$  threshold (165C, typical) the IC will latch off safely. When  $T_J$  decreases again and falls below the internal  $T_{OTP-}$  threshold (105C, typical), then the OTP latch will be reset. Until then, internal OTP latch is guaranteed to remain in the correct state while  $V_{CC}$  is greater than 5V. During an OTP event, this GaN IC will latch off and the system  $V_{CC}$  supply voltage will drop due to the loss of the aux winding supply. The system  $V_{CC}$  will fall below the lower UV- threshold of the controller and the high-voltage start-up circuit will turn-on and  $V_{CC}$  will increase again (

Fig. 32).  $V_{CC}$  will increase above the rising UV+ threshold and the controller will turn on again and deliver PWM pulses again.

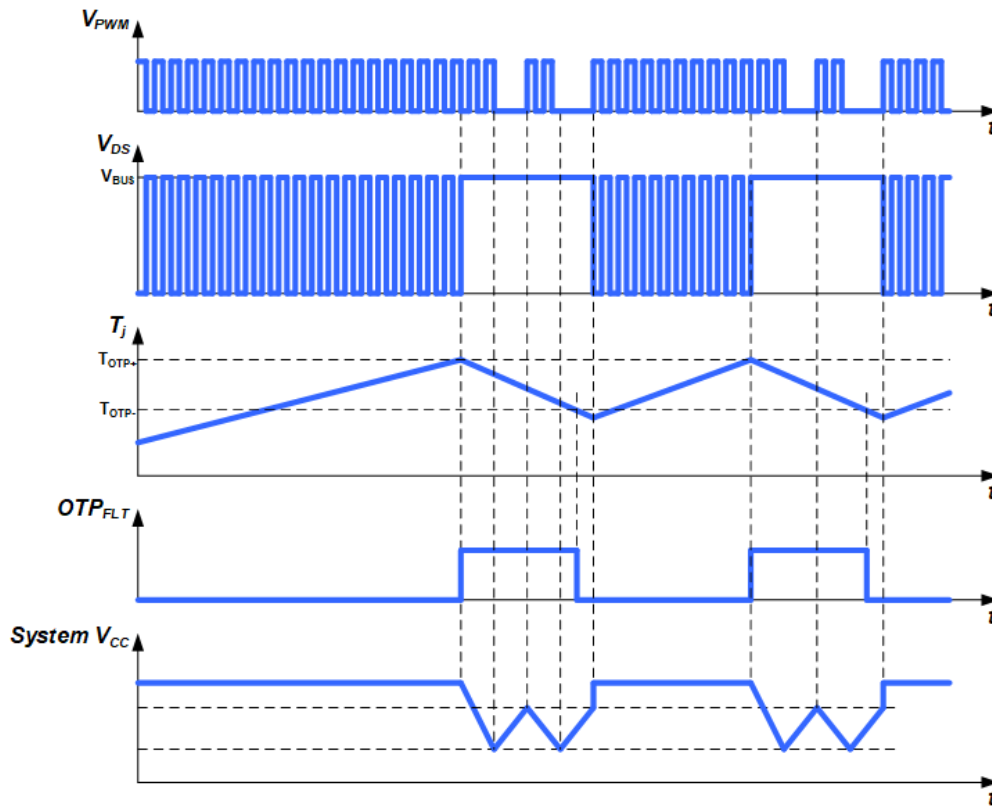


Fig. 32. OTP threshold timing diagram

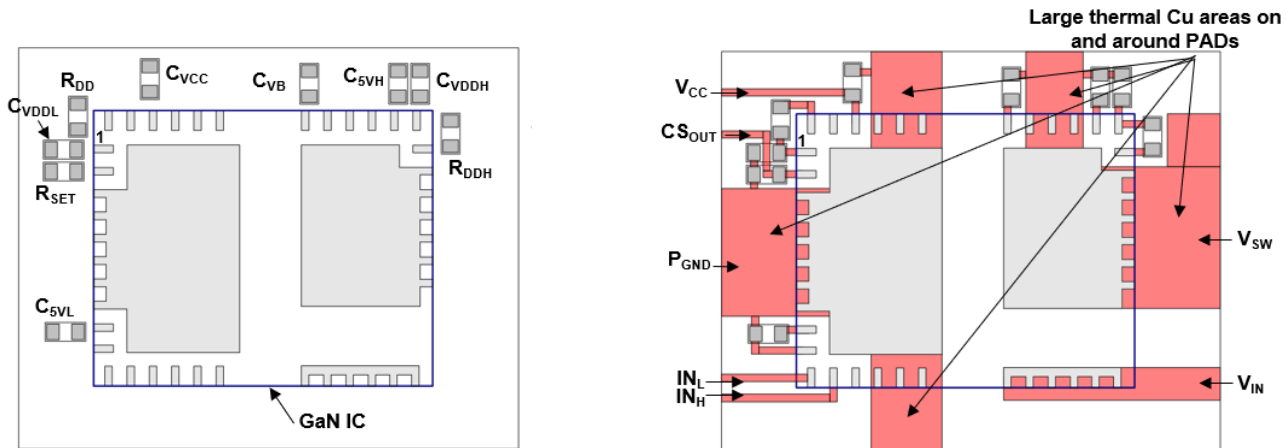
## 9. PCB Layout Guidelines

For best electrical and thermal results, these PCB layout guidelines (and 4 steps below) must be followed:

- 1) Place IC components as close as possible to the GaN IC. Place  $R_{SET}$  resistor directly next to CS pin to minimize high frequency switching noise.
- 2) Connect the ground of IC components to Source to minimize high frequency switching noise. Connect controller ground also to Source ( $P_{GND}$ ).
- 3) Route all connections on single layer. This allows for large thermal copper areas on other layers.
- 4) Place large copper areas on and around Pad1 and Pad2.
- 5) Place many thermal vias inside Pad1 and Pad2 and inside Pad1 and Pad2 copper areas.

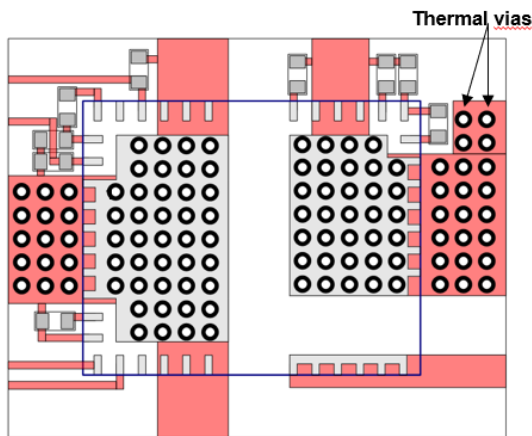
Place large possible copper areas on all other PCB layers (bottom, top, mid1, mid2).

**Do not extend copper planes from the low-side across the components or pads of the high-side; do not extend copper planes from the high-side across the components or pads of the low-side! Keep high and low-side layouts separate. Do not overlap!**

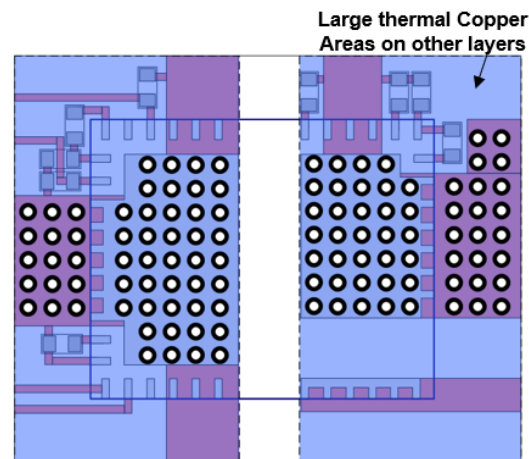


Step 1. Place GaN IC and components on PCB.  
Place components as close as possible to IC

Step 2. Route all connections on single layer. Make large copper areas on and around Source pad

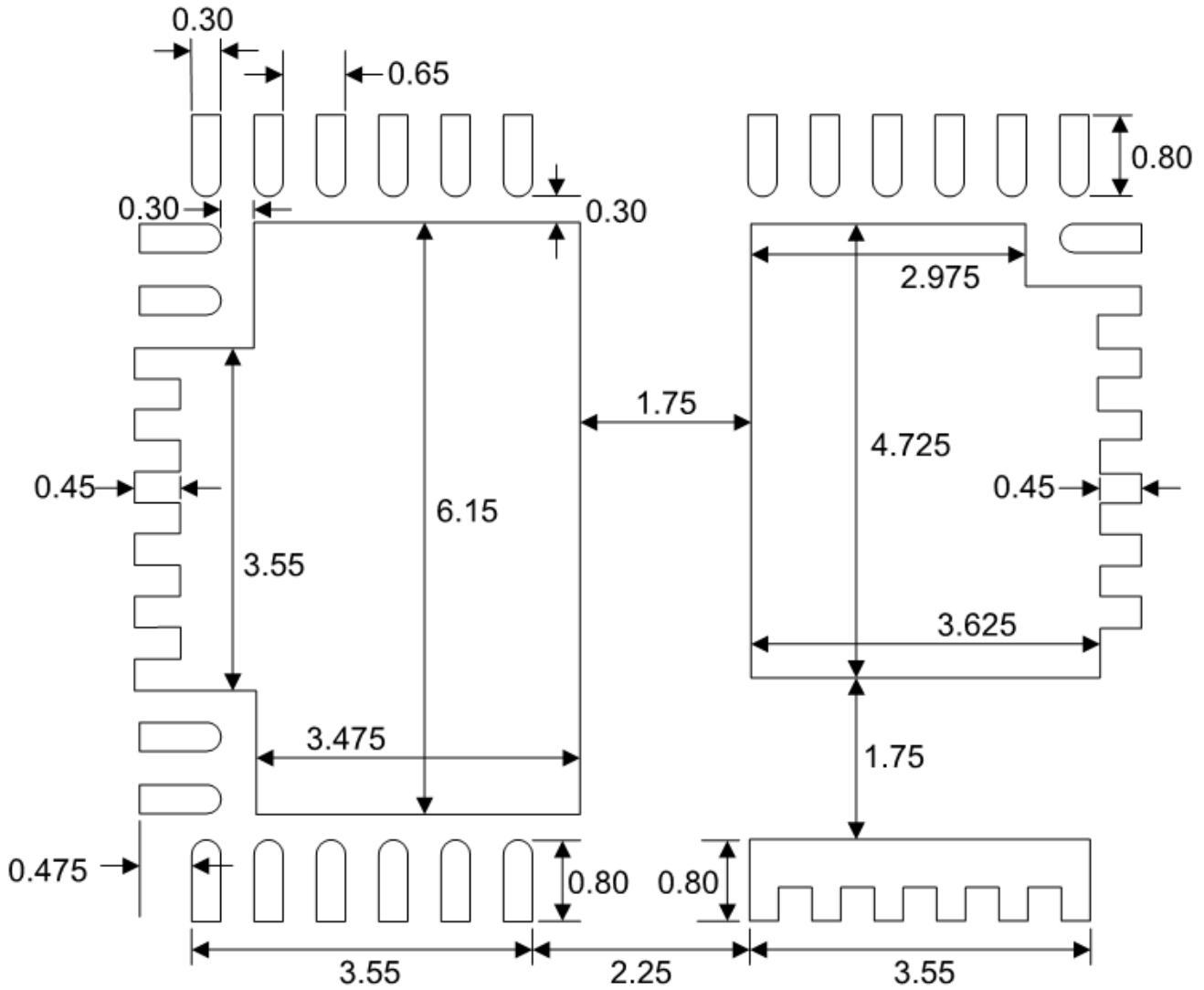


Step 3. Place many thermal vias inside source pad and inside source copper areas.  
(dia=0.65mm, hole=0.33mm, pitch=0.925mm, via wall=1mil)



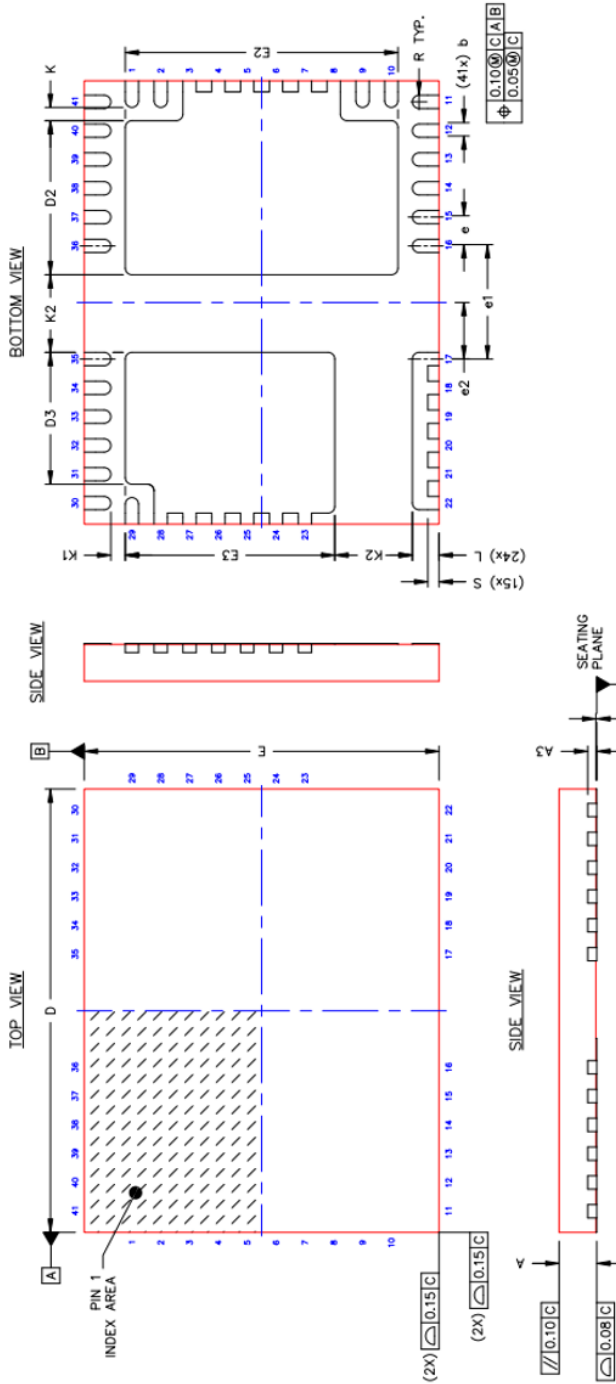
Step 4. Place large copper areas on other layers. Make all thermal copper areas as large as possible!

**10. Recommended PCB Land Pattern**



Top View  
All dimensions are in mm

**11. Package Outline (Power QFN)**



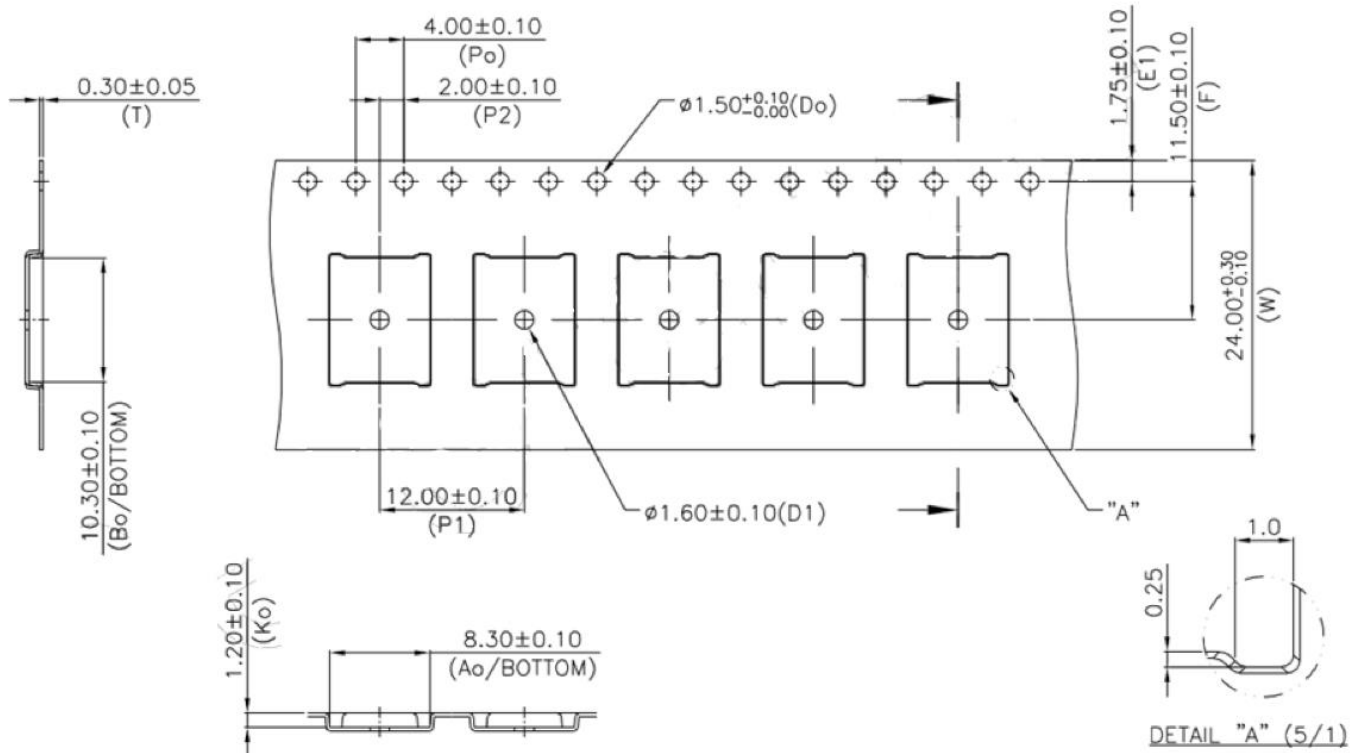
W C

SYM	MIN	NOM	MAX
A	0.80	0.85	0.90
A1	0.00	—	0.05
A3	—	0.203 REF.	—
b	0.25	0.30	0.35
D	9.90	10.00	10.10
E	7.90	8.00	8.10
D2	3.425	3.475	3.525
E2	6.10	6.15	6.20
D3	2.925	2.975	3.025
E3	4.675	4.725	4.775
e	0.65 BSC		
e1	2.55 BSC		
e2	1.275 BSC		
K	—	0.30 REF.	—
K1	—	0.325 REF.	—
K2	—	1.75 REF.	—
L	0.55	0.60	0.65
R	—	0.15 REF.	—
S	0.20	0.25	0.30

**NOTES:**

1. DIMENSIONING AND TOLERANCING CONFORM TO ASME Y14.5M -- 1994.
2. ALL DIMENSIONS ARE IN MILLIMETERS.
3. MAXIMUM ALLOWABLE BURRS IS 0.050 MM IN ALL DIRECTIONS.

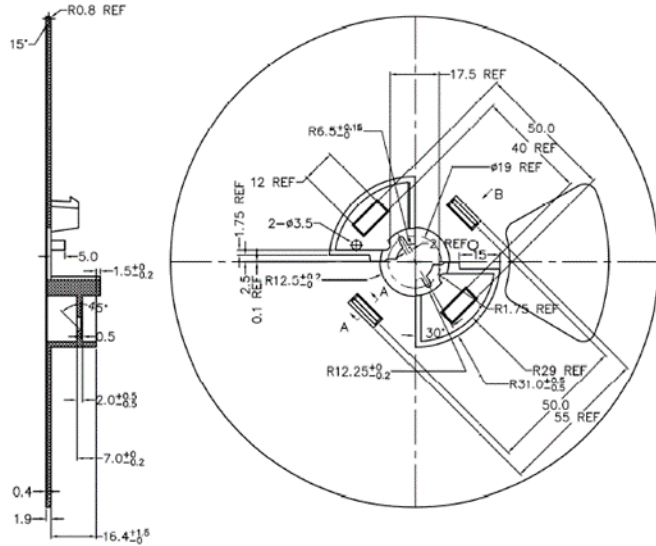
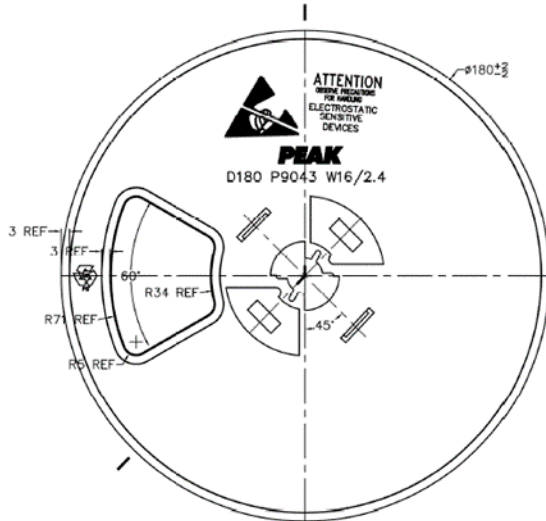
## 12. Tape and Reel Dimensions



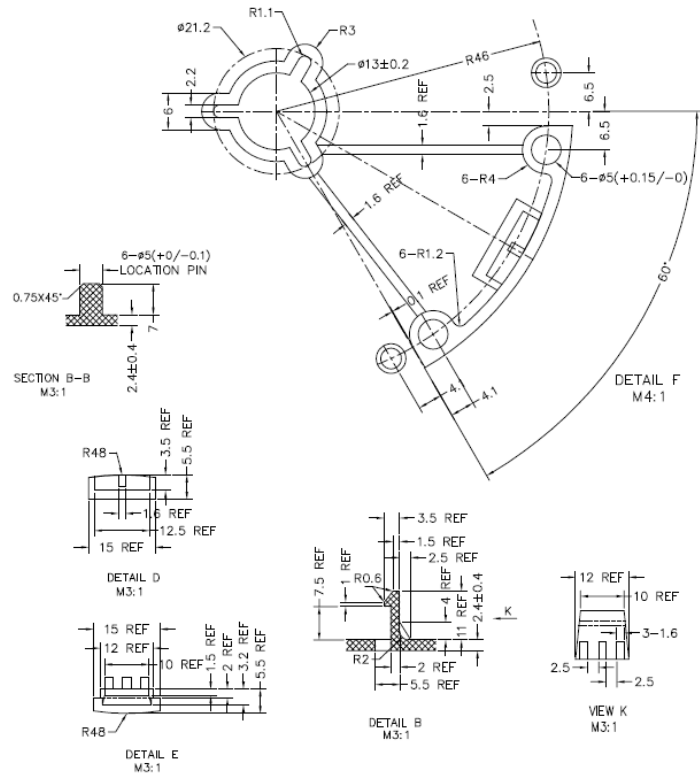
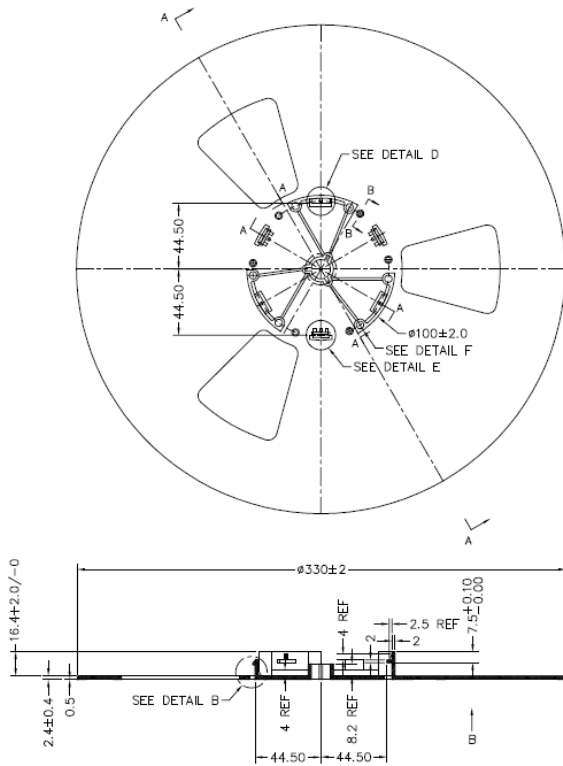


**13. Tape and Reel Dimensions (Cont.)**

7" Reel



13" Reel



## 14. Ordering Information

Part Number	Operating Temperature Grade	Storage Temperature Range	Package	MSL Rating	Packing (Tape & Reel)
NV6269M-RA	-55°C to +150°C T <sub>CASE</sub>	-55°C to +150°C T <sub>CASE</sub>	8 x 10 mm PQFN	3	1000: 7" Reel
NV6269M	-55°C to +150°C T <sub>CASE</sub>	-55°C to +150°C T <sub>CASE</sub>	8 x 10 mm PQFN	3	5000: 13" Reel

## 15. 20-Year Limited Warranty

The product(s) described in this data sheet **include a** warranty period of twenty (20) years under, and subject to the terms and conditions of, Navitas' express limited product warranty, available at <https://navitassemi.com/terms-conditions>. The warranted specifications include only the MIN and MAX values only listed in Absolute Maximum Ratings, ESD Ratings and Electrical Characteristics sections of this datasheet. Typical (TYP) values or other specifications are not warranted.



## 16. Revision History

Date	Status	Notes
Mar. 21, 2024	Preliminary Revision	Graphs need to be updated
May. 13, 2024	Prelim Update	All data and graphs added. Theta JA to be updated.
Sep. 24, 2024	Final	Change RDD from 100/1000 to 300/1500. Fix several typos.

## Additional Information

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Contact [info@navitassemi.com](mailto:info@navitassemi.com)

